

Report No. (To be assigned by NHTSA)

DEVELOPMENT OF A TEST METHODOLOGY FOR EVALUATING CRASH COMPATIBILITY AND AGGRESSIVENESS

> TEST REPORT 2 1975 FORD TORINO-TO-NHTSA TEST DEVICE

Contract DOT-HS-7-01758



March 1979

FINAL REPORT

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Prepared for:

U.S. DEPARTMENT OF TRANSPORTATION NATIONAL HIGHWAY TRAFFIC SAFETY ADMINISTRATION WASHINGTON, D.C. 20590 Prepared for the Department of Transportation, National Highway Traffic Safety Administration, under Contract No. DOT-HS-7-01758. This document is disseminated under the sponsorship of the Department of Transportation in the interest of information exchange. The United States Government assumes no liability for the contents or use thereof.

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TECHNICAL REPORT STANDARD TITLE PAGE

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1. Report No. 2. Government Ac	ccession No. 3. Recipient's Catalog No.
4. Title and Subtitle TEST REPORT #2, 1	.975 5. Report Date March 1979
FORD TORINO-TO-NHTSA TEST DEVICE	6. Performing Orgn Code
7. Author(s)	8. Performing Orgn Rpt No. 8316-78-106A
9. Performing Organization Name and Address	10. Work Unit No.
Dynamic Science, Inc. A Talley Industries Company	11. Contract or Grant No.
1850 West Pinnacle Peak Road Phoenix, Arizona 85027	DOT-HS-7-01758 13. Type of Report and
12. Sponsoring Agency Name and Address U.S. Department of Transportation	TEST REPORT May - Sept 1978
Administration	14. Sponsoring Agency Code
15. Supplementary Notes	
Test No. 3 and 4 of a Series of 8	Tests
16. Abstract	
four-door sedans. The objective of establish a test methodology for e and aggressiveness. The Test Devi faced, load-measuring tool which barrier and fixed barrier collisio	of these tests was to help evaluating crash compatibility ice is a unique honeycomb is adaptable to both moving ons.
Data contained in this report inc presentations of vehicle deformat: data, vehicle and simulated occupa and displacement values, dynamic of tiometers, and restraint survival are tabular summaries of occupant and interior static vehicle deform loads and vehicle descriptions. Device collision is compared to the Test Device collision.	lude graphical and tabular ion, Test Device load cell ant acceleration, velocity displacement of string poten- distances. Also included injury criteria, exterior mation, and restraint system Data for a 40-mph fixed Test hat for an "equivalent" moving
 	10 Dictribution Statement
17. Key Words Fixed Test Device, Moving Test Device, Compatibility, Aggres- siveness, Ford Torino	Document is available to the public through the National Technical Information Service, Springfield, Virginia 22161
19. Security Classif. (of this report) 20. Security C (of this pa	lassif. 21. No. Pages 22. Price age) 226
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1.0 INTRODUCTION

A series of eight full-scale crash tests was conducted to establish a test methodology for evaluating vehicle crash compatibilities and aggressiveness. The objectives of these tests were:

- To obtain the necessary data for establishing appropriate criteria for evaluating vehicle aggressiveness of intermediate, subcompact, and lightweight subcompact-size cars. The vehicles tested were all 1975 model cars which included Honda Civic CVCC, Volvo 244DL, Ford Torino, and Plymouth Fury.
- To investigate the Dynamic Science segmented load cell Test Device concept for sensitivity to measure the basic types of aggressiveness, namely, architectural, mass, and structural aggressiveness.

A summary of the car-to-Test Device test conditions is shown in Table 1-1. This test report presents the results of Tests Numbers 3 and 4, head-on collisions between the NHTSA Test Device and the 1975 Ford Torino four-door sedans.

The Test Device is a unique honeycomb-faced load-measuring tool which is adaptable to both moving barrier collisions (see Figure 1-1) and fixed-barrier collisions (see Figure 1-2). The barrier face of the Test Device is made up of 40 six-inch-thick energy-absorbing aluminum honeycomb modules, each individually connected to load cells. At selected locations, 6 string potentiometers were added to record honeycomb dynamic displacement. The Ford car was first crashed into the fixed Test Device (Test 3), and then a similar model was tested into the moving Test Device (Test 4). The closing speed for the moving Test Device tests was selected to give the same energy change (Δ E)* as in the corresponding fixed Test Device test. (See Appendix A for determination of equivalent closing speed for moving Test Device collisions.)

*Note: This and subsequent moving Test Device tests used equal energy absorption ΔE instead of equal velocity change (ΔV) as the equivalent speed criteria.

TABLE 1-1. SUMMARY OF CAR-TO-TEST DEVICE TEST CONDITIONS

Test Number	Test Date	Test Configuration	Car Model	Car Weight (1b)	Barrier Weight (1b)	Closing Velocity (mph)
г	April 17, 1978	Honda Front-to- Fixed Test Device (Head-on)	1975 Honda CVCC 2-door sedan	2205	Fixed**	40.83
7	April 20, 1978	Honda Front-to- Moving Test Device (Head-on)	1975 Honda CVCC 2-door sedan	2205	3994	62.24***
2	May 9, 1978	Ford Front-to- Fixed Test Device (Head-on)	1975 Ford Torino 4-door sedan	4550	Fixed**	40.52
4	May 16, 1978	Ford Front-to- Moving Test Device (Head-on)	1975 Ford Torino 4-door sedan	4550	4002	59.10*
ſſ	June 6, 1978	Volvo Front-to- Fixed Test Device (Head-on)	1975 Volvo 244DL 4-door sedan	3351	Fixed**	45.11
w	June 8, 1978	Volvo Front-to- Moving Test Device (Head-on)	1975 Volvo 244DL 4-door sedan	3353	4007	61.38*
7	June 13, 1978	Plymouth Front-to- Fixed Test Device (Head-on)	1975 Plymouth Fury 4-door sedan	4439	Fixed**	40.73
ω	June 16, 1978	Plymouth Front-to- Moving Test Device (Head-on)	1975 Plymouth Fury 4-door sedan	444	4012	58 . 02*
*Base(**Fixe(**Base(d on equal energ 1 barrier test d 1 on equal veloc	y absorption (ΔE). evice weight > 100,0 ity change (ΔV).	00 pounds.			6/20/78







2.0 TEST METHODOLOGY AND PROCEDURE

This section presents a brief description of the test methodology and procedures used for conducting the car-to-Test Device head-on collisions.

2.1 VEHICLE DESCRIPTION

The vehicles used in these tests were both 1975 Ford Torino four-door sedans. Tables 2-1 and 2-2 present the incoming vehicle inspection performed on each car used for the fixed and moving Test Device tests, respectively.

For the tests to be conducted, two Part 572, male 50th percentile Alderson anthropomorphic dummies (GFE) were in the two front seating positions of the car. Each occupant was properly restrained with the vehicle's lap and shoulder belt restraint system. The seat tracks were welded in their midposition with the seat back latches secured to prevent breakaway and rotation. Test weights for the Fords were determined by averaging test weights of cars used in other crashes. All collisions were headon with no lateral offset distance between car and Test Device face.

2.2 FIXED TEST DEVICE TESTS

The Ford-to-fixed Test Device test was conducted at the barrier impact facility (see Figure 2-1) with the centerline of the test car in line with the centerline of the fixed Test Device face. The vehicle impact velocity (see Table 1-1) was controlled to within ±1 mph.

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Contractor: Dynamic Science, Inc. Contract No.: DOT-HS-7-01758 VIN NO.: 5A27H125599 Make: Ford NHTSA Wo.: Year: 1975 Color: Dark Blue Model: Torino 4-Door Auto Trans: (ves) no Pwr Steering: (ves) no Seats: Bench: X (front) Bucket: Pwr Brakes: (ves) no Auto Speed Cont: yes no Seats: Bench: X Pwr Seats: yes no Auto Speed Cont: yes no Split Bench: Pwr Seats: yes no Anti Skid Brake: yes no Split Bench: Pwr Windows: yes no Anti Skid Brake: yes no Split Bench: Pwr Windows: yes no Anti Conditioning: (ves) no Split Bench: Pwr Windows: yes no Brakes: drum: R disc: P Clock: yes no Brakes: drum: R Clock: yes no Brakes: drum: R Steel Eng. Front: Dayton Steel Radial Tire Size: * Ply Rating: 4 Mfg. & Line: Rear: Uniroyal Steel Belter Steel Eng. Total 35: Bias Ply: Belted: X Radial X / Type : Y-8 Cylinders: 8 Displ:CIJ Trans, # Fwd. Speeds: 3 Shipping Weight: 4180 1b Odometer: 31995 miles Dealer (name, address, and phone number) Olsen Chevrolet Williams, Arizona Remarks (list additional accessories not listed above) *FR-GR78-14 and RR-HR78-14. Date of Manufacture: 11/74 Dynamic Science No.:604 Date Received: Fuel Capacity: "Space Saver" Spare Tire yes Fuel Capacity: "space Saver" Spare Tire yes 1. Is the vehicle stock throughout? Describe: _Yes 1. Is the vehicle stock throughout? Describe: _Yes	Contractor: Dynamic Sciend	THE DESCRIPTION - M	OATING TERT	DEVICE	1EST	
VIN NO.: 5A27H125599 Make: Ford NHTSA Wo.: Year: 1975 Color: Dark Blue Model: Torino 4-Door Auto Trans: (yes) no Seats: Bench: X Pwr Brakes: (yes) no Auto Speed Cont: yes no Seats: Bench: X Pwr Brakes: (yes) no Anti Skid Brake: yes no Split Bench: Split Pwr Windows: yes no Anti Skid Brake: yes no Split Bench: Split Back ino Rear Window Def.: yes no Split Bench: Bench: Split Back ino Rear Window Def.: yes no Back Bench: Split Beck Eng. Total 35.		ce, Inc. Contr	act No.:	DOT-HS-7	-01758	
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Year: 1975 Color: Dark Blue Model: Torino 4-Door Auto Trans: Year no Pwr Steering: Year no Seats: Bench: X Pwr Brakes: Year no Auto Speed Cont: yes no Seats: Bench: X Pwr Seats: yes no Auto Speed Cont: yes no Split Bucket:	NHTSA No.:	·				
Auto Trans: (ves) no Pwr Steering: (ves) no Seats: Bench: X Pwr Brakes: (ves) no Auto Speed Cont: ycs no Bucket:	Year: 1975	Color: Dark Blu	<u>e</u>	Model:	Torino 4	-Door
Art Blake: (ves) No Antic Speed contr. yes No Pwr Seats: yes no Anti Skid Brake: yes No Split Pwr Windows: yes no Air Conditioning: (yes) no Split Pwr Windows: yes no Air Conditioning: (yes) no Split Tinted Glass: yes no Brack Bench: Dench: Dench: Radio: (yes) no Brakes: drum: R disc: F Clock: yes no Brakes: Arget Aland Mfg. 4 Line: Rear: Uniroyal Steel Beltee: Trans, # Fwd. Speeds: 3 Shipping Weight: 4180 lb Odometer: 31995 miles Dealer name, address,	Auto Trans: (yes) no	Pwr Steering: (ye	s) no	Seats: (front)	Bench:	X
WAY Space: yes no Antiskid Brake: yes no Banch: Pwr Windows: yes no Air Conditioning: yes no Split Tinted Glass: yes no Rear Window Def.: yes no Split Radio: (yes) no Brakes: drum: R disc: F Clock: yes no Brakes: Affit Addis Juiroyal Steel Balter DisplicEl Trans, # Fwd. Speeds: 3 Shipping Weight: 4180 lb Odometer: 31995 miles Dealer fname, address, and p	PWI BLAKES: (Yes) 110	Auto speed cont. ye			Split	
Per Windows: yes No Air conditioning: yes No split Tinted Glass: yes No Rear Window Def.: yes No Split Radio: (res) no Brakes: drum: R disc: F Dench:	Pwr Seats: yes no	Nici Skid Brake: ye			Bench:	
Radio: (res) no Brakes: drum: R disc: F Radio: (res) no Brakes: drum: R disc: F Clock: yes (no) Front: Dayton Steel Radial Tire Size: * Ply Rating: 4 Mfg. & Line: Rear: Uniroyal Steel Belter Steel Eng. Total 35: Bias Ply: Belted: X Radial X / Type : V-8 Cylinders: 8 Displ:CII Trans, # Fwd. Speeds: 3 Shipping Weight: 4180 lb Odometer: 31995 Miles Dealer (name, address, and phone number) Olsen Chevrolet Williams, Arizona Remarks (list additional accessories not listed above) *FR-GR78-14 and RR-HR78-14. Date of Manufacture: 11/74 Dynamic Science No.: 604 Date Received: 1/78 Tilting Steering Wheel: yes (no) Telescoping Steering Wheel: yes (no) Fuel Capacity: (from owner's manual) Restraint System Std. 3-point Production Belts 1. Is the vehicle stock throughout? Describe: Yes	Tintod Clause vos	Boar Window Dof :			Split Back	
Rearbing Yes no blakes: 010m. <u>k</u> 0150: <u>1</u> Clock: yes no Front: Dayton Steel Radial Tire Size: * Ply Rating: <u>4</u> Mfg. & Line: Rear: <u>Uniroyal Steel Belter</u> Bias Ply:	Padios	Brakes, drum, P	disc: F		Bench:	
Clock: yes no. Front: Dayton Steel Radial Tire Size: * Ply Rating: 4 Mfg. & Line: Rear: Uniroyal Steel Relter Bias Ply: Belted: X Radial X /Type : V-8 Cylinders: 8 Displ:CI Trans, # Fwd. Speeds: 3 Shipping Weight: 4180 1b Odometer: 31995 miles Dealer (name, address, and phone number) Olsen Chevrolet Williams, Arizona	Rauto: Vesi no	DLAKES: UTUM: K				
Tire Size:Piy Rating:4Mrg. & Line: Rear: Uniroyal Steel Belter Steel Total 35. Bias Ply: Belted:X Radial X / Type : V-8Cylinders: 8Displ:CI Trans, # Fwd. Speeds:3Shipping Weight: 4180 lbOdometer:31995 miles Dealer (name, address, and phone number) Olsen Chevrolet Williams, Arizona Remarks (list additional accessories not listed above) *FR-GR78-14 and RR-HR78-14. Date of Manufacture: Dynamic Science No.:O4 Date Received:78 Tilting Steering Wheel: yes Telescoping Steering Wheel: yes no Fuel Capacity: "Space Saver" Spare Tire yes no Restraint System Std. 3-point Production Belts Is the vehicle stock throughout? Describe: Yes	Clock: yes not		Fror	nt: Day	ton Steel	Radial
Steel Total 3. Bias Ply: Belted: X Radial X / Type : V-8 Cylinders: 8 Displ:CI Trans, # Fwd. Speeds: 3 Shipping Weight: 4180 1b Odometer: 31995 miles Dealer (name, address, and phone number) Olsen Chevrolet Williams, Arizona Odometer: 31995 miles Remarks (list additional accessories not listed above) *FR-GR78-14 and RR-HR78-14. Free of Manufacture: 11/74 Dynamic Science No.: 604 Date Received: 1/78 Tilting Steering Wheel: yes no Telescoping Steering Wheel: yes no Fuel Capacity:	Tire Size: * Ply Ra	ting: <u>4</u> Mfg.	& Line: <u>Rear</u> Eng.	: Unire	oya⊥ Stee	L Belted R
Trans, # Fwd. Speeds:	Bias Ply: Belted:	X Radial X /	Type : V-8	Cylind	ers: <u>8</u>	Displ: <u>CID</u>
Dealer (name, address, and phone number) Olsen Chevrolet Williams, Arizona Remarks (list additional accessories not listed above) *FR-GR78-14 and RR-HR78-14. Date of Manufacture: 11/74 Dynamic Science No.: 604 Date Received: 1/78 Tilting Steering Wheel: yes no Telescoping Steering Wheel: yes no Fuel Capacity: "Space Saver" Spare Tire yes no (from owner's manual) Restraint System Std. 3-point Production Belts 	Trans, # Fwd. Speeds:	Shipping Weight:	4180 lb	Odome	ter: <u>3199</u>	5 miles
<pre>*FR-GR78-14 and RR-HR78-14. Date of Manufacture: 11/74 Dynamic Science No.: 604 Date Received: 1/78 Tilting Steering Wheel: yes no Telescoping Steering Wheel: yes no Fuel Capacity: "Space Saver" Spare Tire yes no (from owner's manual) Restraint System Std. 3-point Production Belts 1. Is the vehicle stock throughout? Describe: Yes</pre>	Remarks (list additional acc	essories not listed a	bove)			
Date of Manufacture: 11/74 Dynamic Science No.: 604 Date Received: 1/78 Tilting Steering Wheel: yes no Telescoping Steering Wheel: yes no Fuel Capacity:		1R78-14.				
Tilting Steering Wheel: yes (no) Telescoping Steering Wheel: yes (no) Fuel Capacity: "Space Saver" Spare Tire yes (no) (from owner's manual) Restraint System Std. 3-point Production Belts 1. Is the vehicle stock throughout? Describe: Yes	*FR-GR78-14 and RR-H		co No + 604	Date	Received:	_1/78
Fuel Capacity: "Space Saver" Spare Tire yes no (from owner's manual) "Space Saver" Spare Tire yes no Restraint System Std. 3-point Production Belts 1. Is the vehicle stock throughout? Describe: Yes	*FR-GR78-14 and RR-F	4 Dynamic Scien				(no)
Restraint System Std. 3-point Production Belts 1. Is the vehicle stock throughout? Describe: Yes	*FR-GR78-14 and RR-H Date of Manufacture: <u>11/74</u> Tilting Steering Wheel:	4 Dynamic Scien yes no T	elescoping S	teering W	neel: yes	\sim
1. Is the vehicle stock throughout? Describe: Yes	*FR-GR78-14 and RR-F Date of Manufacture: 11/74 Tilting Steering Wheel: Fuel Capacity:	4 Dynamic Scien yes no T	elescoping S Space Saver"	teering W Spare Ti	re yes	no
1. Is the vehicle stock throughout? Describe:	*FR-GR78-14 and RR-H Date of Manufacture: 11/74 Tilting Steering Wheel: Fuel Capacity:	4 Dynamic Scien yes no T 's manual) pint Production Bel	elescoping S Space Saver" LS	teering W Spare Ti	re yes	no
	*FR-GR78-14 and RR-H Date of Manufacture: 11/74 Tilting Steering Wheel: Fuel Capacity:	4 Dynamic Scien yes no T 's manual) pint Production Bel	elescoping S Space Saver" LS	teering W Spare Ti	re yes	
	*FR-GR78-14 and RR-H Date of Manufacture: <u>11/74</u> Tilting Steering Wheel: Fuel Capacity: <u>(from owner)</u> Restraint System <u>Std. 3-pc</u> 1. Is the vehicle stock th	4 Dynamic Scien yes no T 's manual) pint Production Bel 	elescoping S Space Saver" LS Yes	teering W Spare Ti	re yes	
2. Does vehicle show evidence of prior accident history? Describe: NO	*FR-GR78-14 and RR-H Date of Manufacture: 11/74 Tilting Steering Wheel: Fuel Capacity:	4 Dynamic Scien yes no T 's manual) Dint Production Bel hroughout? Describe:	elescoping S Space Saver" ts Yes	teering W Spare Ti	re yes	
	*FR-GR78-14 and RR-H Date of Manufacture: 11/74 Tilting Steering Wheel: Fuel Capacity:	4 Dynamic Scien yes no T 's manual) Dint Production Bel hroughout? Describe:	elescoping S Space Saver" ts Yes history? D	teering W Spare Ti escribe:_	re yes	
3. Does vehicle show any significant corrosion? Describe: NO	*FR-GR78-14 and RR-H Date of Manufacture: <u>11/74</u> Tilting Steering Wheel: Fuel Capacity: <u>(from owner)</u> Restraint System <u>Std. 3-pc</u> 1. Is the vehicle stock th 2. Does vehicle show evide	4 Dynamic Scien yes no T 's manual) pint Production Bel hroughout? Describe: ence of prior accident	elescoping S Space Saver" ts Yes history? D	teering W Spare Ti escribe:_	re yes	
	*FR-GR78-14 and RR-H Date of Manufacture: <u>11/74</u> Tilting Steering Wheel: Fuel Capacity: <u>(from owner)</u> Restraint System <u>Std. 3-pc</u> <u>1</u> . Is the vehicle stock th <u>2</u> . Does vehicle show evide 3. Does vehicle show any statements	4 Dynamic Scien yes no T 's manual) pint Production Bel hroughout? Describe: ence of prior accident significant corrosion?	elescoping S Space Saver" ts Yes history? D Describe:_	teering W Spare Ti escribe: NO	re yes	
D Added Event human	*FR-GR78-14 and RR-F Date of Manufacture: <u>11/74</u> Tilting Steering Wheel: Fuel Capacity: <u>(from owner)</u> Restraint System <u>Std. 3-pc</u> 1. Is the vehicle stock th 	4 Dynamic Scien yes no T 's manual) Dint Production Bel hroughout? Describe: ence of prior accident significant corrosion?	elescoping S Space Saver" ts Yes history? D Describe:_	teering W Spare Ti escribe: NO	re yes	

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The test vehicle was instrumented with 16 accelerometers, 1 string potentiometer, 6 seat belt loads, and an impact sensor. The test vehicle was placed at the head of the test track facing the barrier where it was attached to the tow and guidance system. The fixed Test Device was instrumented with 40 load cells, 6 string potentiometers, 2 strain gauges, and an impact sensor.

Upon completion of the pre-crash checkout of the instrumentation, the vehicle was towed to the specified test speed and released from the tow system just prior to impact. The data from the test vehicle was transmitted to the data acquisition center via umbilical cable with telemetry as a backup. The data from the fixed Test Device was transmitted by umbilical cable only (see Figure 2-2). In order to achieve the weight goal outlined in the test plan, the rear windows of the test vehicle were removed prior to testing. See Table 2-3 for a crash test summary of the fixed Test Device configuration.

2.3 MOVING TEST DEVICE TESTS

The Ford-to-moving Test Device test was conducted at the midrange station of the crash track facility (see Figure 2-1) with the centerline of the test car in line with the center of the moving Test Device face. The vehicle impact velocity of each test vehicle (see Table 1-1) was controlled to within ±1 mph.

The test vehicle was instrumented exactly the same as the vehicle used in the fixed Test Device test with the abort bottle placed inside the trunk of the vehicle. This was done for safety reasons. The test vehicle was placed at the head of the test track, facing the barrier. The moving Test Device was instrumented the same as the fixed Test Device with the addition of 2 longitudinal accelerometers and an additional strain gauge attached to the frame rails of the moving Test Device. The moving Test Device was placed



Data Acquisition - Vehicle-to-Fixed Barrier Tests. Figure 2-2.

TABLE 2-3	. CRASH TEST SUMMARY 83	16-3	
Test No. 8316-3	ContractDOT	-115-7-01758	
Test Date May 9, 19	78 Time000	Temperature <u>83</u> °F	
Test Configuration Fr	ont-to-Front, Head-on		
Vehicle No. 1(P	A) 1975 Ford Torino 4-doo	r Sedan	
Vehicle No. 2(E	3) Fixed Test Device		
VEHICLE DATA	Vehicle A	Vehicle B	
Test Weight (lb)	4550	>100,000	
Impact Angle (deg)*	0°	180°	
Offset Distance (in.)	0	. 0	
Impact Velocity (mph)**	40.52	0	
DUMMY DATA			
Туре	Part 572 Alderson	None	
Locations	LF (Driver) - # 759***	~=	
	RF (Passenger) - # 760**	*	
Restraints	Lap/Shoulder Belt	None	
	Lap/Shoulder Belt	***	
INSTRUMENTATION			
Number of Data Channels	4 1.	48	
Number of Cameras	7		

*With respect to tow track centerline facing fixed barrier. **Speed trap measurement. ***Alderson Dummy Serial No. at the barrier end of the track. See Table 2-4 for a crash test summary of the moving Test Device configuration. The rear window of the Ford was not removed for this test.

Both vehicles were attached to the tow and guidance system. After the pre-crash checkout of the instrumentation, the vehicles were towed to the specified test speed and released from the tow system just prior to impact. The data from the test vehicle and moving Test Device were transmitted to the data acquisition center via umbilical cable with telemetry as a backup (Figure 2-3).

	TABLE 2-	4. CRASH TEST SUMMARY 8	316-4		
	Test No. 8316-4	ContractDO	T-IIS-7-01758		
	Test Date May 16, 1	.978 Time 1422	Temperature 88 °F		
	Test Configuration F	ront-to-Front, Head-on			
	Vehicle No. 1(A) 1975 Ford Torino 4-do	or sedan		
	Vehicle No. 2(B) Moving Test Device			
	VEHICLE DATA	VEHICLE A	VEHICLE B		
	Test Weight (lb)	4550	4002		
	Impact Angle (deg)*	0 °	180°		
Offset Distance (in.)		0	0		
<pre>Impact Velocity (mph) **</pre>		29.55	. 29.55		
	DUMMY DATA				
	Туре	Part 572 Alderson	None		
Locations		LF (Driver) - # 759***	_		
		<u>RF (Passenger) - # 760*</u>	**		
Restraints		Lap/Shoulder Belt	None		
		Lap/Shoulder Belt			
	INSTRUMENTATION				
	Number of Data Channels	41	53		
	Number of Cameras	7			

*With respect to tow track centerline facing fixed barrier. **Speed trap measurement. ***Alderson Dummy Serial No.

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3.0 DATA ACQUISITION

3.1 DATA ACQUISITION METHODS

The overall plan for obtaining the necessary data is outlined in Table 3-1. The table defines the test parameter, measurement method, and recording method used during the conduct of this program.

Test Parameter	Measurement Method	Magnetic Tape	Written Log	Photo- graphic Analysis
Impact Time	Contact switch sig- nal impressed on millisecond time base	X		
Approach Velocity	Tow cable velocity sensor	х		
Impact Velocity	Speed trap entrance and exit signals from speed trap	X*		
Rebound Velocity	Calculated from high- speed film analysis and compartment accelerometer data	х		х
Test Device and Vehicle Accelera- tion Measurements	Accelerometers, un- bound strain gauge type	Х		
Test Device Honeycomb Crush	String potentiometer and direct linear measurement	X	X X	
Stress in Test Device frame and Horizontal Beams	Strain gauges	Х		
Forces on Test Device Honeycomb	Load cells	Х		

TABLE 3-1. DATA REQUIREMENTS

		Magnetic	Written	Photo-
Test Parameter	Measurement Method	Tape	Log	Analysis
Vehicle Structural Deformation	Direct linear mea- surement		Х	
Vehicle Static Crush	Direct linear mea- surement		Х	
Vehicle Static Crush	Film analysis			Х
Restraint Survival Distance	Direct linear mea- surement		X	
Steering Column Intrusion	Direct linear mea- surement		х	
Firewall Intrusion	String potentiometer and static measure- ments	Х	х	
Fuel Leakage	Observation and timed measurement		х	
Windshield Reten- tion	Direct measurement and observation		Х	
Occupant Head and Chest Acceleration	Triaxial accelerom- eters	х		
Occupant Femur Loads	Load cells	х		
Seat Belt Loads	Load cells	х		
Vehicle Weight by Wheel	Direct pre-test mea- surement using balance scales		х	
Ballast Weight	Balance scale		Х	

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TABLE 3-1. DATA REQUIREMENTS (CONTD)

3.2 INSTRUMENTATION

3.2.1 Test Vehicle Instrumentation

The test vehicle contained two Part 572 anthromorphic dummies positioned in the left and right front seating locations. Prior to each test use, the dummies were inspected and adjusted to meet the torque and characteristic requirements for these devices. Sixteen structural accelerometers and one string potentiometer were installed on the vehicle and consisted of the following (see Figure 3-1):

- 1. A biaxial (X, Z) mount located on the left rocker panel near the B-pillar to measure accelerations of the occupant compartment.
- 2. A biaxial (X, Z) mount similar to No. 1, but on the right side of the vehicle.
- 3. A biaxial mount (X, Z) located on the rear floor structure over the rear axle.
- 4. A biaxial mount (X, Z) located on the upper centerline of the firewall in the engine compartment to measure acceleration of the forward section of the passenger compartment.
- 5. A biaxial mount (X, Z) located on the centerline of the rear axle to measure acceleration of the rear drive train and rear suspension assembly.
- A single mount (X) located on the top of the engine block in a protective case to measure acceleration of the engine.
- A single mount (X) located on the front frame crossmember in a protective case to measure axial acceleration of the front frame.
- 8. A triaxial mount (X, Y, Z) located near the vehicle center of gravity on the drive tunnel at the longitudinal C.G. to measure acceleration of the compartment.
- 9. A single mount (X) located in a position similar to that in No. 6, but on the bottom of the engine.





	VEHICLE ACCELEROMETER LOCATIONS AND PHYSICAL COORDINATES					MAXIMUM EXPECTED READINGS		
NO.	DESCRIPTION OF LOCATION	X**	Y**	Z**	LONG*	LAT*	VERT*	
1	Rocker panel near B-							
	pillar behind driver's							
	seat	98	-27	15	50		50	
2	Rocker panel near B-		-					
	pillar behind passen-							
	ger's seat	98	+27	15	50		50	
• 3	Centerline of rear deck							
	above rear axle	58	0	27	50		50	
4	Centerline of firewall							
	at A-pillar inside							
	engine compartment	155	- 3	+33	100		100	
5	Centerline of rear axle	55	0	6	100		100	
6	Engine block (Top							
	centerline)	120	0	+29	200			
7	Front crossmember	171	0	6	200			
8	Longitudinal center of							
	gravity of car	117	0	16	50	50	50	
2	Engine block (Bottom							
	centerline)	129	0	6	200			
10	String Potentiometer	132	0	24	_15_ir	1		

*In G.

**Reference points:

X - Direction - Centerline of rear bumper

Y - Direction - Conterline of vehicle - left centerline (-), right centerline (+)

Z - Direction - Ground level

Figure 3-1. Vehicle Accelerometer Instrumentation.

- 10. A string potentiometer installed on the interior firewall to measure the intrusion of the firewall into the occupant compartment.
- 11. A tape switch mounted onto the forwardmost portions of the car to record impact.

3.2.2 Test Vehicle Occupant Instrumentation

The following test dummy instrumentation was installed for the driver and right front passenger positions:

- 1. A triaxial accelerometer mount located in the head to measure its acceleration.
- 2. A triaxial accelerometer mount located in the chest cavity to measure chest acceleration.
- 3. A femur load cell mounted in the femur of each leg to measure femur loads.
- 4. Two seat belt load cells were mounted onto the lap belt with an additional seat belt load cell mounted onto the shoulder belt for each of the two front occupant restraint systems. The lap belt load cells were mounted on each side of the occupant.

The instrumentation requirements for the dummy occupants are given in Table 3-2.

3.2.3 Moving Test Device Instrumentation

The moving Test Device was instrumented with 40 load cells, 6 displacement string potentiometers, 3 strain gauges, 2 accelerometers, and 1 tape switch. Their purposes and locations were as follows:

- 1. A load cell mounted between each honeycomb module and Test Device rigid face to measure impact forces.
- 2. A string potentiometer displacement transducer mounted at selected honeycomb locations to measure dynamic honeycomb displacement.

Occupant Accelerometer and Loa	Maximum Expected Readings					
Description of Locations	Long	Lat	Vert	Long*	Lat*	<u>Vert*</u>
Driver head accelerometer	Х	х	X	200	100	200
Passenger head accelerometer	х	Х	х	200	100	200
Driver chest accelerometer	х	Х	Х	100	50	100
Passenger chest accelerometer	Х	х	х	100	50	100
Driver left and right femur load cell				3000 1b		
Passenger left and right femur load cell		ie.		3000 1b		
*Tn G.						

TABLE 3-2. OCCUPANT INSTRUMENTATION

- 3. A single (X) accelerometer mounted on the longitudinal frame rails (mounted on each side) to measure acceleration of the Test Device.
- 4. Two strain gauges mounted on selected horizontal impact face beams to measure strains developed in the front structure due to the impact force.
- 5. One strain gauge mounted on the right side of the Test Device longitudinal frame rail to measure strain in the vehicle frame structure.
- 6. One tape switch mounted onto a selected honeycomb module to record the time of impact.

Figure 3-2 defines the typical instrumentation honeycomb module; Figure 3-3 describes the location of instrumentation on the Test Device impact face; and Figure 3-4 shows the location of the instrumentation on the Test Device vehicle structure.

3.2.4 Fixed Test Device Instrumentation

The instrumentation on the fixed Test Device was the same as on the moving Test Device except that the strain gauges and accelerometers on the Test Device frame were deleted (Figure 3-5).





1975 Ford Torino/Test Device Honeycomb Interface and String Potentiometer Locations. Figure 3-3.



			1	
AlR Test Device Accelerom-			•	
reter frame rail right				
Side	84	46	2.0	100.6
A2L Test Device Accelerom-				
eter frame rail left				
side	84	- 46	20	100 G
SG1 Row 8 horizontal beam	140	0	20	2500 U in.Zin.
SG2Row_C_borizontal_beam	140	• 0	24	7500 µ in./1n.
SG3 Test device frame rail			_	
right side	78	46	21	7500 0 in./in.
40 Load cells				15.0 F1b
*Reference Points:				
X Direction - Rear End of	f Test	Devic	e	
Y Direction - Centeiline	of Tee	st Dev	ice -	Left (-), Right ((+)

Z direction - Ground Lovel.

Figure 3-4. Moving Test Device Instrumentation.


Figure 3-5. Fixed Test Device Installation and Strain Gauge Location.

3.3 PHOTO-INSTRUMENTATION REQUIREMENTS

3.3.1 Fixed Test Device Photography

Six high-speed (four 1000 fps and two 500 fps) cameras and one panning (24 fps) camera were used as shown in Table 3-3 for the fixed Test Device/moving vehicle tests.

The panning camera documented the instrumentation, pre-test and post-test configurations, pre-test and post-test dummy positions, and the Test Device and vehicle crush profiles.

3.3.2 Moving Test Device Photography

Six high-speed (four 1000 fps and two 500 fps) cameras and one panning (24 fps) camera were used as shown in Table 3-4 for the moving Test Device/moving vehicle tests.



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**Camera perpendicular to line of vehicle travel.

	o t e s o t o e ↓ + ↓ ↓ ↓ ↓	R/S (CAR)				<u>1</u> 1 1 1	-1 -1 -1
DEVICE			~ ~	0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	2 5 תנה 2 5 תנה	13.mm 13.mm	25mm 13mm
. CAMERA LOCATIONS - MOVING TEST	6/78 Head-on	vice wice and test (TEST DSVICE)	FRAME RATE P. 1000 fr/sec D. 1000 fr/sec 2. 200 fr/sec 3. Other 24 fr/sec 5. 500 fr/sec D. 100 Hz (S msec/light) 2. 200 Hz (S msec/light) 2. 200 Hz (S msec/light) 3. Other	Field of View	Right Front Occupant Compartment Treff Front Occupant Compartment	Overall of Moving Barrier and Car A B-Pillar to B-Pillar of Both Vehicles	Overall of Car A Front Half of Both Vehicles at Impact Panning Test and Overall Results
TABLE 3-4	Test No: <u>8316-4</u> Test Date: <u>5/1</u> Test Type: <u>Car-to-Hoving Test Device</u>	Vehicle A (Away): 19/0 Ford TOFIN Vehicle B (Barrier): Moving Test De Comments: Camera locations are apprimay be moved at the discretion of th Engineer	CANERA VES CANERA VES STILS V STILS V C PIT C C C C C C C C C C C C C C C C C C C	Loc. Location	<pre>1 Left Side ** 2 Right Side**</pre>	3 Left Side** 4 Right Side**	<pre>5 Right Side ** 6 Covernead at 7 Left Side</pre>

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**Cameras perpendicular to line of vehicle travel.

4.0 SUMMARY OF TEST RESULTS

This section of the report presents the results of the Fordto-Test Device crash tests performed under Task 4. Copies of instrumentation data traces (Calcomp plots) are included in Appendix B for Test No. 3 and in Appendix C for Test No. 4.

4.1 TEST SUMMARY: FORD-TO-TEST DEVICE TESTS

A summary of pertinent pre-test and post-test Test Device conditions are given in Tables 4-1 through 4-7. Pre-test and post-test views of crash configurations are shown in Figures 4-1 and 4-2 for fixed Test Device tests and in Figures 4-3 and 4-4 for moving Test Device tests.

Test weights for each vehicle were determined by weighing each wheel of the car to obtain a total weight. The vehicle was then rotated 180 degrees and the weighing procedure repeated to obtain an average weight for the vehicle.

Compartment and engine acceleration was determined by an averaging of accelerometers located near the B-pillar of the vehicle and the top and bottom of the engine block (see Figure 3-1).

Maximum mutual dynamic crush data, as well as the chronology of events for each vehicle, were determined by high-speed film analysis. Maximum dynamic crush on the car was determined by subtracting 6 inches of honeycomb crush from the maximum mutual dynamic crush for each test.

4.1.1 Fixed Test Device Test

In the fixed Test Device test, the Ford impacted the aluminum honeycomb modules at a speed of 40.5 mph, causing approximately 31 inches of static crush to the vehicle. The final speed

	·····			
TABL	E 4-1. CRASH	TEST SUM	1ARY	
Test No.	7			8
Test Date	June 13, 197	8	June 16, 1	978
Time	1242		1119	· · · · · · · · · · · · · · · · · · ·
Temperature	101° F		95°F	
Test Configuration	Front-to-From Head-on	nt	Front-to-F Head-on	ront
Vehicle A	1975 Plymout	h Fury	1975 Plymo	uth Fury
Vehicle B	Fixed Test D	evice	Moving Tes	t Device
	VEHICLE A	DATA		
Test Weight by Wheel (lb)	LF-1224 R LR- 984 R	F-1236 R- 995	LF-1221 LR-1021	RF-1235 RR- 967
Total Weight (lb) 4439		444	4
Longitudinal C.G. (from center of front axle) (in.)	52.5		52.	5
Impact Angle (deg)*	0		0	
Offset Distance (in.)	0		0	
Impact Velocity (mph)**	40.73		58.	02
	OCCUPA	NTS		
Туре	Part 572 Ald	erson	Part 572 A	lderson
Locations	LF (Driver) RF (Passenge	- #759 r) - #760	LF (Driver RF (Passen) - #759 ger) - #760
Restraints	Standard Pro Lap/Shoulder	duction Belt	Standard P Lap/Should	roduction er Belt
	INSTRUMEN	TATION		
Number of Data Channels	Vehicle A - Vehicle B -	41 48	Vehicle A Vehicle B	- 41 - 53
Number of Cameras	7		7	
*With respect to tow	track center	line faci	ng fixed ba	rrier.

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**Closing speed from speed trap measurement.

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VEHICLE: 1975 Ford Torino 4	-door Sedan	
Vehicle Parameter	Test 3 (Fixed Test Device)	Test 4 (Moving Test Device)
Car Test Weight (lb)	4550	4550
Overall Vehicle Length/Width (in.)	218.1/79.3	217.8/79.3
Car Speed (mph)	40.5	29.6
Final Speed (mph @ msec)	-6.6 @ 152	-1.9 @ 115
Coefficient of Restitution	0.16	0.12
Velocity Change (mph @ msec)	47.1 @ 152	31.5 @ 115
Maximum Compartment Accelera tion (G @ msec)	48.2 @ 66	-44.6 @ 61
Maximum Engine Acceleration (G @ msec)	-79.9 @ 52	-116.6 @ 40
Maximum Dynamic Crush (in.)	37.8 (F)	36.5 (F)
Maximum Static Crush • Hood Level (in.) • Between Bumper/Hood (in • Bumper Level (in.)	30.4 30.6 31.8	30.3 29.3 31.0
Maximum Post-test Intrusion (in.)	8.1	4.3
Maximum Mutual Dynamic Crush (in.)	43.8 (F)	42.5 (F)
Maximum Individual Load Cell Force (klb @ msec)***	12.36 @ 58 (B7)	9.79 @ 44 (C5)
Maximum Total Load Cell Forc (klb @ msec)***	e 108.5 @ 56	99.9 @ 43
Normalized Maximum Force* (lb/lb)	23.8	22.0
Vehicle Damage Index**	12FCAW9	12FCAW9

***Some load may have been lost due to load cell contact with backing plate (see Figures 4-32 and 4-33).

TABLE 4-3.	SUMMARY OF	PRE-TEST	ENGINE/BUMPER/FIREWALL
	CHARACTERI	STICS	

•

Test No.	3	4
Type of Test	Fixed Test Device	Moving Test Device
Impact Velocity (Closing, mph)	40.5	59.1
Engine Size (CID)	351	351
Engine Weight* (1b)	891	891
Engine Height/Width (in.)	23/24	23/24
Bumper to Engine (in.)	30.8	30.6
Engine Length (in.)	28.0	28.0
Engine to Firewall (in.)	33.0	33.0
Bumper to Firewall (in.)	63.8	63.6

*Includes engine and rigid attachments such as transmission and drive train.

TABLE 4-4. SUMMARY OF PRE-TEST DUMMY POSITION DATA CHARACTERISTICS

		moving Te	t 4 st Device	
Left Front Occupant	Right Front Occupant	Left Front Occupant	Right Front Occupant	
5.3	5.3	5.3	5.3	
2.6	2.6	2.6	2.6	
26.8	26.8	27.0	26.8	
20.4	20.3	21.4	21.1	
13.8	18.8	13.5	18.4	
5.5/5.1	8.5/8.3	5.8/5.1	7.8/7.8	
	Front <u>Occupant</u> 5.3 2.6 26.8 20.4 13.8 5.5/5.1	Interfer Right Front Front 0ccupant 0ccupant 5.3 5.3 2.6 2.6 26.8 26.8 20.4 20.3 13.8 18.8 5.5/5.1 8.5/8.3	Interce Right Interce Front Front Occupant Occupant 5.3 5.3 5.3 5.3 2.6 2.6 2.6 2.6 26.8 26.8 27.0 20.4 20.3 21.4 13.8 18.8 13.5 5.5/5.1 8.5/8.3 5.8/5.1	

*From rearmost position to midpoint. **To dash panel for RF passenger.

	TABLE 4-5. SUM	MARY OF POST-TEST OF	SERVATIONS
VEHICLE:	1975 Ford Toring	0 4-door Sedan	
Test No.	3 (Fixed Test D	evice)	
Dummy Co.	ntact Points:	Left Front	Right Front
Head	~ :	Dash Panel and Top of Steering Wheel	Dash Panel
Chest-		Steering Wheel Hub	None
Knees-		Knee Bolsters,	Glove Compartment
Glazing:	windshield crac	ked and 50 percent	retained.
Doors: F	Required tools to	o open all doors.	
Doors:_F Seat Bel	Required tools to	open all doors. Okay	
Doors:_F Seat Bel Restrain	Required tools to t Anchorages: ts: Okay	o open all doors. Okay	
Doors:F Seat Bel Restrain Fuel Lea	Required tools to t Anchorages: ts:Okay kage:None	o open all doors. Okay	
Doors:_F Seat Bel Restrain Fuel Lea General	Required tools to t Anchorages: ts:	o open all doors. Okay diator leakage. Oi	l from differential
Doors: F Seat Bel Restrain Fuel Lea General	Required tools to t Anchorages: ts: kage: Observations: ut when drive lin	o open all doors. Okay diator leakage. Oi e broke. Exhaust p	l from differential ipe was bent. Honey
Doors: F Seat Bel Restrain Fuel Lea General leaked ou	Required tools to t Anchorages: ts: kage: None Observations: Observations: ut when drive lin	o open all doors. Okay diator leakage. Oi e broke. Exhaust p re pulled off when	l from differential ipe was bent. Honey hood latch on vehicl
Doors: F Doors: F Seat Bel Restrain Fuel Lea General leaked ou comb modu	Required tools to t Anchorages:	o open all doors. Okay diator leakage. Oi e broke. Exhaust p re pulled off when i ing off module from	l from differential ipe was bent. Honey hood latch on vehicl Test Device face.
Doors:I Seat Bel Restrain Fuel Lea General leaked ou comb modu pinched a Dash pane	Required tools to t Anchorages:	o open all doors. Okay diator leakage. Oi e broke. Exhaust p re pulled off when ing off module from ide separated from	l from differential ipe was bent. Honey hood latch on vehicl Test Device face. firewall. Rear of
Doors: _ H Seat Bel Restrain Fuel Lea General G leaked ou comb modu pinched a Dash pane Jehicle r	Required tools to t Anchorages:	o open all doors. Okay diator leakage. Oi e broke. Exhaust p re pulled off when ing off module from ide separated from ockwise 3-3/4 inches	l from differential ipe was bent. Honey hood latch on vehicl Test Device face. firewall. Rear of s. Vehicle rebounde

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TABLE 4-5. SUMMARY OF POST-TEST OBSERV	JATIONS (CONTD)
VEHICLE: 1975 Ford Torino 4-door Sedan	
Test No. 4 (Moving Test Device)	
Dummy Contact Points: Left Front	Right Front
Head Dash Panel	Dash Panel
Chest Steering Wheel	None
Knees Knee Bolsters	Glove Compartment
Glazing: Windshield was cracked and was 80	percent retained.
Doors: Required tools to open all doors.	
Soat Polt Anchomerce Okay	
Seat Beit Anchorages: Okay	
Restraints. Okav	
Fuel Leakage: None	
General Observations: Radiator leakage. Exh	aust pipe was bent
Honeycomb module D1 was pulled off by car.	Modules Cl. D2. and
All were sheared off by car at impact. Pass	enger dash panel was
destroyed by striking of occupant's head on	dash. Centerline of
vehicle was on centerline of monorail after	test. Front bumper
rotated upward. Vehicle pushed Test Device	21 feet past impact
location before stopped by technicians.	

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TABLE 4-6.	. INJURY CRITERIA SUMMA	ARY
Occupant Position	Left Front	Right Front
TEST	GEIXED TEST DEVICE)	
HIC	1824 @ 94-116	1691 @ 88-122
Head G* @ msec	112.2 @ 106	113.0 @ 109
CSI	942 @ 200	668 @ 200
Chest G* @ msec	84.5 @ 90	58.8 @ 98
Femur Load (lb)	Left Right	Left Right
	-1407 -1635	-807 -1173
RSD (in.)**	Pre Post	Prė Post
•	13.5 13.3	13.7 13.2
TEST 4	(MOVING TEST DEVICE)	······································
ніс	765 @ 80-127	1211 @ 89-118
Head G* @ msec	75.4 @ 102	1060 @ 109
CSI	518 @ 200	326 @ 200
Chest G* @ msec	58.8 @ 89	40.5 @ 90
Femur Load (lb)	Left Right	Left Right
	-2169 -1588	-692 -609
RSD (in.)**	Pre Post	Pre Post
	10.7 9.8	9.5 8.4

*3-msec clip. **RSD computed with 7-msec time shift to correct for honey-comb crush of Test Device.

	TABLE 4-7. CHRONOLOGY OF CRASH EVENTS
VEHICLE:	1975 Ford Torino 4-door Sedan
Time (msec)	Test 3 - Fixed Test Device Event
. 0	Impact (visual)
18	Right front fender starts to deform
20	Left front fender starts to deform
31	Driver starts forward motion
32	Hood starts failure
62	Passenger starts forward motion
82	Driver hits steering wheel with chin
96	Driver hits dash with head
101	Passenger hits dash with head, driver starts rebound
104	Maximum mutual dynamic crush (43.8 in.), passenger hits dash
105	Vehicle rebound begins
114	Rear wheels leave ground
120	Passenger starts rebound
175	Maximum pitch angle 4.6°
183	Driver recontacts seat
206	Passenger recontacts seat
297	Rear wheels touch ground

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-	TABLE 4-7. CHRONOLOGY OF CRASH EVENTS (CONTD)
VEHICLE:	1975 Ford Torino 4-door Sedan
Time (msec)	Test 4 - Moving Test Device Event
0	Impact (visual)
12	Hood buckles
14	Left front fender starts to deform
24	Honeycomb module Al0 sheared off
29	Honeycomb module D2 sheared off
35	Honeycomb module Dl sheared off
55	Driver begins forward motion
56	Passenger begins forward motion
65	Windshield cracks
78	Maximum mutual dynamic crush (42.5 in.) with pitch angle 1°
88	Driver hits dash panel
91	Passenger hits dash panel
115	Vehicles separate, Test Device begins rebound
131	Passenger begins rebound
140	Driver begins rebound
238	Passenger recontacts seat
240	Driver recontacts seat



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Figure 4-1. Pre-test Vehicle Configuration - Test 3.







Figure 4-3. Pre-test Vehicle Configuration - Test 4.



Figure 4-4. Post-test Vehicle Configuration - Test 4. NOTE: TEST DEVICE PUSHED BACK BY CAR APPROXIMATELY 21 FEET. of the Ford was -6.6 mph, giving a total velocity change of 47.1 mph.

The maximum dynamic crush on the car was 37.8 inches at 104 milliseconds, with a pitch angle of 4.6 degrees. Rebound of the Ford off of the face of the fixed Test Device caused the rear of the car to rotate 3.8 inches counterclockwise from the barrier centerline. The Ford rebounded approximately 3 inches from the initial impact point, pulling off honeycomb modules B5 and C5 with the structure of the car.

4.1.2 Moving Test Device Test

In the moving Test Device test, the Ford impacted the aluminum honeycomb module at a closing speed of 59.1 mph, causing approximately 30.5 inches of static crush to the vehicle. The final speed of the Ford was -1.9 mph. The final speed of the Test Device was -5.3 mph. The total velocity change to the car was 43.7 mph.

The maximum dynamic crush on the car was 36.5 inches at 78 milliseconds and a pitch angle of 1.0 degree. Moving Test Device tests conducted under this program have been adjusted to give the same ΔE for moving barrier collisions for a similar fixed barrier collision (see Appendix A). Upon impact of the moving Test Device with the Ford, the moving Test Device was pushed back by the car approximately 21 feet before being manually stopped by test personnel. After impact, the Ford appeared to remain stationary near the impact location, putting the remaining energy from the collision into pushing the Test Device backwards. Since the Test Device has no sheet metal deforming around the tires and the Ford was 550 pounds heavier, the energy transmitted by the Ford caused the Test Device to be put in a free wheeling state in the reverse direction of travel. The centerline of the Ford remained in line with the centerline of the track after impact.

Vehicle data, including all pre-test and post-test measurements and summaries of vehicle accelerometer and string potentiometer data, are discussed in Section 4.2. Test Device data, including summaries of load cell, string potentiometer, accelerometer, strain gauge data, and honeycomb crush profiles, are discussed in Section 4.3. Occupant response data is discussed in Section 4.4.

4.2 VEHICLE STRUCTURAL RESPONSE

This section of the report presents data on the Ford's structural response to the collision with the fixed and moving Test Devices. This includes pre-test and post-test measurements made at selected locations on the vehicle, steering wheel displacements, vehicle exterior and interior profiles, and accelerometer data.

Static crush measurements of the Ford for both fixed and moving Test Device tests are shown in Table 4-8. Pre-test and post-test bumper match-ups are shown in Figures 4-5 through 4-8. In both tests, the car deformed uniformly with the flat surface of the Test Device. Since the closing speed for the moving Test Device test was selected to give the same change in energy (ΔE), the crush measurements were very similar for both tests.

Exterior profiles are given in Tables 4-9 and 4-10. Measurements for the frontal exterior profile of the Ford were made at three levels: the hood level, the bumper level, and a level between the hood and bumper level. In both tests, the bumper of the Ford rotated upward due to the force of impact. The rotation of the front bumper guards caused concentrated loads to be recorded by the Test Device's load cells.

Vehicle interior intrusion profiles and steering wheel displacement values are given in Tables 4-11 through 4-13. Compartment intrusion is shown in Figures 4-9 through 4-12. In both tests the dash panel became detached from the frame of the car and the



TABLE 4-8. PRE- AND POST-TEST DIMENSION MEASUREMENTS

		(Moving Test Device Test) Test 4										
	Pre-	test	Post-	test	Diffe	rence	Pre-	test	Post-	test	Diffe	rence
	LS	RS	LS	RS	LS	RS	LS	RS	_LS	RS	LS	RS
A	118.1	117.8	108.9	109.1	9.2	8.7	118.1	117.8	110.3	112.2	7.8	5.6
в	46.5	46.4	25.0	22.5	21.5	23.9	46.0	46.6	22.3	22.0	23.7	24.6
С	53.6	53.8	53.6	53.9	0.0	-0.1	53.4	53.6	53.8	53.8	-0.4	-0.2
D	218.2	218.0	187.5	185,5	30.7	32.5	217.5	218.0	186.4	188.0	31.1	30.0
I	36.6	36.6	36.5	35.6	0.1	1.0	36.6	36.6	36.0	36.1	0.6	0.5
G	102,4	102.3	101.5	101.5	0.9	0.8	102.1	102.1	102.0	102.8	0.1	-0.7
L	116.6	116.6	116.0	115.8	0.6	0,8	116.5	116.8	115.8	115.4	0.7	1.4
м	135.5	135.5	133.5	132.8	2.0	2.7	135.4	135.5	134.1	134.0	1.3	1.5
N	24.4	24.4	24.4	24.4	0.0	0.0	24.4	24.4	24.4	24.4	0.0	0.0
0	51.8	51.8	54.0	53.4	-2.2	-1.6	51.8	52.0	53.0	52.9	-1.2	-0.9
Р	31.5	31.4	32.5	33.4	1.0	1.0	30.5	31.4	31.1	31.8	-0.6	-0.4
Q	12.9	12.9	13.1	12.4	-0.2	0.5	13.1	13.4	12.8	12.3	0.3	1.1
R	13.3	13.5	13.9	13.3	-0.6	0.2	13.5	13.8	13.3	12.9	0,2	0.9
z	79.2	79.1	51.5	47.4	27.7	31.7	78.8	79.3	48.4	49.1	30.4	30.2

Note: All measurements in inches.



Figure 4-5. Pre-test Bumper Match - Test 3.







Figure 4-7. Pre-test Bumper Match - Test 4.



Figure 4-8. Post-test Bumper - Test 4. = 0070008

		TABLE 4	4-9. CAR EXTERIOR PROFILES AND STATIC CRUSH FOR TEST 3
Location	R.P.* (in.)	Height (in.)	Distance Left of Center (in.)** Distance Right of Center (in.)** 36 30 24 18 12 6 12 18 24 30 36
	•		Pre-test Profile (Distance from R.P in.)
Hood Level	220	30.9	- 11.6 11.4 11.6 10.0 8.4 7.1 8.4 10.0 11.6 11.5 11.6 -
Between Bumper/ Hood	220	26.1	- 13.8 13.6 11.8 11.0 9.4 7.5 9.3 10.9 11.6 13.5 13.6 -
Bumper Level	220	17.8	8.3 7.3 7.1 7.0 2.0 3.6 2.1 3.6 2.1 6.9 7.3 7.5 8.6
			Post-test Profile (Distance from R.P in.)
Hood Level	220	34.0	- 37.9 39.6 39.8 38.8 37.6 34.8 38.3 40.4 39.0 38.8 38.0 -
Between Bumper/ Hood	220	31.1	- 40.1 40.0 39.1 41.0 39.4 35.5 39.0 41.5 38.9 40.3 41.1 -
Bumper Level	220	25.0	40.0 39.3 39.1 39.0 34.6 35.4 33.5 34.8 33.3 36.3 35.8 35.1 35.0
			Post-test Static Crush (in.)
Hood Level		3.1	- 26.3 28.2 28.2 28.8 29.2 27.7 29.9 30.4 27.4 27.3 26.4 -
Between Bumper/ Hood		5.0	- 26.3 26.4 27.3 30.0 30.0 28.0 29.7 30.6 27.3 26.8 27.5 -
Bumper Level		7.2	31.7 32.0 32.0 32.0 32.6 31.8 31.4 31.2 31.2 29.4 28.5 27.6 26.4
*Referer **As view	ice pla red fro	ane from om drive	m rear bumper of car. er position in car.

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		TABLE (4-10.	CAR	EXTE	RIOR	PROFI	LES A	ND STAT	LIC CRI	USH FC	DR TES	4		
Location	R.P.* (in.)	Height (in.)	Diste 36 P	ance 30 re-te	Left 24 sst P	of Ce 18 rofil	nter 12 e (Dis	(in.) 6 stance	н К К С Ш К С Ш К С Ш К С Ц К С С Ц К С С Ц С С С С С С С С С	Dista 6 R.P	ance F 12 in.)	kight 18	of Ce 24	nter 30	(in.)** 36
Hood Level	220	31.0	T	12.	8 12.	5 11.	8 10.	8	5 7.4	8.	5 10.1	11.6	12.5	12.6	1
Between Bumper/ Hood	220	26.3	i	13.	8 I3.	5 11.	9 11.	- 6 0	8.0	10.0	0 11.6	11.8	13 . 5	13 . 6	ł
Bumper Level	220	18.3	9.0	7.	97.	6 7.	г 2.	4.4	0 2.4	С	2.3	6•9	7.4	7.6	8. 6
			Post	-test	E Pro	file	(Dista	ance i	rom R.	г	n.)				
Hood Level	220	32.0	r	37.	l 38.	8 39.	6 39	1 38.6	35.3	38.0	39.9	38.4	37.4	36.1	1
Between Bumper/ Hood	220	29.0	I	98.	1 40.	68 8	6 40 . 1	5 37.3	36.3	6° 68	40.8	37.4	39.0	37.5	I
Bumper Level	220	22.0	35,9	35.8	3 36.	4 34.	4 33.4	4 34.4	32.7	33.8	32.8	3 2 .8	35.6	35.0	35.2
					Post-	test	Statio	c Crue	sh (in.						
Hood Level		1.0	I	24.	3 26.	3 27.	8 29.]	L 30.3	27.9	29.4	29.	8 26.8	3 24.9	23.5	
Between Bumper/ Hood		2.7	I	24.6	26.8	3 27.	7 28.5	5 27.8	28.3	29.3	29.	2 26.8	3 25.5	23.9	i
Bumper Level		3.7	26.9	27.9	28.8	3 27	3 31.(30.4	30.3	29.9	30.1	5 28.9	9 28.2	27.4	26.6
*Referen **As view	ce pla ed fro	ne from m drive	r pos	bum itior	er of i in d	f car car.		ŝ							

CAR INTERIOR PROFILES AND STATIC INTRUSION FOR FIXED TEST DEVICE TEST TABLE 4-11.

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	* 4 2	Heicht	йŬ	eft Froi Occupant	t t	At String	Ric	ght Fron Occupant	t t
Location	(in.)	(in.)	Т** Т	**0	R* *	Centerline	* * 1	** 0	R**
		Pre-tes	t Profi	le (Dis	tance f	[rom R.P in.)			
Dash Level	115	39.5	14.5	15.0	14.8	14.3	14.6	14.4	14.0
Knee Level	115	26.5.	19.0	19.4	19.4	18.9	21.8	22.5	22.8
Floor Level	128	17.0	25.3	25.6	25.3	19.9	25.1	25.9	25.5
		Post-te	st Prof	ile (Di	stance	from R.P in.)			
Dash Level	115	39.3	11.6	11.1	10.8	10.7	11.3	10.3	10.0
Knee Level	115	24.3	22.5	18.4	21.5	17.1	22.9	23.4	23.9
Floor Level	128	20.6	21.0	18.5	17.4	11.8	17.3	19.1	20.8
		Pos	st-test	Static	Intrusi	ion (in.)			
Dash Level		-0.2	2.9	3.9	4.0	3.6	3.3	4.1	4.0
Knee Level		-2.0	-3 . 5	1.0	-2.1	1.8	-1.1	6•0 -	-1.1
Floor Level		3.6	4.3	7.1	7.8	8.1	7.8	6.8	4.7
*Reference **L = Left, (plane frc 3 = Cente	om rear bu èr, R = Ri	umper of ght sid	f car. le of oc	cupant	seating position	ls.		

4 CAR INTERIOR PROFILES AND STATIC INTRUSION FOR MOVING TEST DEVICE TEST TABLE 4-12.

.

VEHICLE: 1975 Ford Torino 4-door Sedan

-	ې ۲	u :	чŢ	eft Fror Occupant	t	At String Dotentioneter	Rie	ght Froi Occupant	t t
Location	(in.)	(in.)	* * 1	C**	R**	Centerline	х * Г	C**	R**
		Pre-test	: Profi	le (Dist	tance fi	com R.P in.)			
Dash Level	115	39.4	14.0	14.6	14.5	14.6	14.5	14.4	14.0
Knee Level	115	24.5	19.6	19.4	19.4	18.9	22.3	22.1	21.8
Floor Level	128	19.1	25.3	25.0	24.6	20.1	24.0	24.6	24.1
		Post-tes	st Prof	ile (Dis	stance f	rom R.P in.)			
Dash Level	115	38.4	11.8	12.3	12.7	13.3	13.4	13.4	13.4
Knee Level	115	26.3	19.5	19.0	19.3	18.6	22.1	22.2	21.3
Floor Level	128	19.1	22.8	21.8	20.3	15.8	20.9	21.1	21.7
		Poe	st-test	Static	Intrusi	ion (in.)			
Dash Level		-1.0	2.2	2.3	1.8	1.3	1.1	. 1.0	0.6
Knee Level		1.8	0.1	0.4	0.1	0.3	0.1	-0.1	0.5
Floor Level		0	2.5	3.2	4.3	4.3	3.1	3.5	2.4
*Reference **L = Left,	plane fro C = Cento	$\begin{array}{llllllllllllllllllllllllllllllllllll$	umper o ight si	f car. de of oc	ccupant	seating positio	.su		

	TABLE	4-13.	STEERING	WHEEL DI	SPLACEMENT	VALUES	
VEHICLE:	1975	Ford	Torino 4-d	loor sedan			
<u> </u>				Displacem	ent <u>(in.)</u>		
1 1	-	(Fixe	Test 3 ed Test Dev	vice)	(Movin	Test 4 ng Test De	evice)
Wheel Location	•	X*	Y*	Z *	<u>X*</u>	<u>Y*</u>	Z*
Тор		+1.8	-2.5	-3.6	-2.8	+2.3	-3.4
Hub		-2.3	+0.1	-1.3	-2.1	-1.9	-2.4
Bottom		+2.3	+1.0	-1.3	0.0	-0.1	-2.7

*Reference for X, Y, Z measurements are the rear bumper (+ forward), vehicle centerline (+ right), and ground level (+ up), respectively.

areas that were struck by the occupants' heads were severely damaged. In the moving Test Device test the occupant compartment intrusion was less severe than in the fixed Test Device test due to the fact that some of the energy was used in pushing back the moving Test Device after impact. In the fixed Test Device test, the steering wheel rim was bent forward and downward by the left front occupant, which exposed the steering wheel hub. This was the cause of large pulses seen on data from the driver's chest. The left front occupant of Test 4 caused less damage to the occupant compartment compared to Test 3, again due to the energy transfer.

A summary of Ford accelerometer and string potentiometer data for both tests is given in Tables 4-14 through 4-19. Refer to Figure 3-1 for their locations in the vehicle. Compartment accelerometers and engine accelerometers were averaged to obtain a more representative picture of what was occurring at those locations. String potentiometer data was used to measure firewall intrusion in the occupant compartment. However, if the peak intrusion does not occur at the location where the measurement was taken, the readings will be low compared to the post-test static measurements.



Figure 4-9. Post-test Driver Compartment - Test 3.







Figure 4-11. Post-test Passenger Compartment - Test 3.



Figure 4-12. Post-test Passenger Compartment - Test 4.

VEHICLE: 1975	Ford 7	Corino 4	-door S	edan		
	Max Accele	kimum eration	Mini Velo	mum city	Maxi Displa	mum cement
Accelerometer Number	A _(G)	Time (msec)	V (mph)	Time (msec)	S (in.)	Time (msec)
lX	-45.0	65	-6.5	153	+46.2	105
12	+16.3	71	-3.1	141	-2.6	200
2X	-51.9	66	-6.6	151	+46.5	105
22	-19.0	88	-2.4	141	+1.6	88
ЗХ	-48.8	66	-6.2	142	+49.0	108
3Z	-50.0	70	-4.8	90	-5.5	200
4 X	-93.3	67	-8.6	173	+43.0	90
4 Z	+53.8	63	-1.2	40	+0.03	47
5X	-72.7	84	-7.8	147	+50.7	101
5 Z	-27.5	82	-3.7	97	-1.7	127
6X	-83.8	57	-3.1*	69	+33.7*	62
7X	-95.4	56	-3.4	161	+37.0*	110
8X	-48.7	81	-6.8	153	+47.0	106
8Y	-21.3	82	-2.2	87	-1.8	200
8Z	-47.1	83	-1.5	162	+3.3	152
9X	-87.4	52	-2.8*	171	34.0*	99
						-

TABLE 4-14. SUMMARY OF CAR ACCELEROMETER DATA FOR FIXED TEST DEVICE TEST 3

See Figure 3-1 for definition of accelerometer numbers. *Data invalid because of rotation of accelerometer.

TABLE 4-15. SUMMARY OF AVERAGED CAR ACCELEROMETER DATA FOR FIXED TEST DEVICE TEST 3

	Maxi	mum	Min:	imum	Max:	imum
	Accele	eration	Velo	ocity	Displa	acement
Accelerometer	A	Time	V	Time	S	Time
Number	(G)	(msec)	(mph)	(msec)	(in.)	(msec)
Average of 1X and 2X (Compartment)	-48.2	66	-6.6	152	46.3	105
Average of 6X and 9X (Engine)	-79.9	52	-2.6*	169	33.8*	67

Data invalid because of rotation of accelerometer.

TABLE 4	-16.	SUMMAN MOVING	RY OF CA G TEST D	AR ACCEL DEVICE T	EROMET EST 4	ER DATA	FOR
VEHICLE:	1975	Ford 7	Corino 4	-door S	edan		
		Max Accele	kimum eration	Mini Velo	mum city	Maxi Displa	mum cement
Accelerom Number	eter	A (G)	Time (msec)	V (mph)	Time (msec)	S (in.)	Time (msec)
lX		-44.6	61	-2.1	116	+25.6	89
12		-21.6	78	-2.1	90	+1.5	78
2X		-44.7	60	-1.7	114	+25.8	88
2Z		+26.1	61	-2.7	106	+1.9	83
2X		-49.4	57	-1.8	104	+27.2	80
3Z		-28.1	81	-2.2	119	+0.9	200
4x		-101.8	56	-4.4*	134	+24.4	63
4 Z		+87.5	52	-1.7	48	+8.5	200
5X		+88.3	54	+0.7*	89	+3.4*	200
5Z		-30.8	57	-2.9	59	+0.4	165
6X		-96.3	42	-12.2*	54	+18.3*	44
7X	-	-129.1	46	+3.7*	55	+43.8*	200
8X		-42.0	64	+0.5*	114	+37.4*	200
8Y		-18.6	56	-0.9	76	-0.8	172
8 Z		-34.0	67	-3.1	114	-2.8	200
9X	-	-141.4	40	-6.2*	53	+17.5	43

See Figure 3-1 for definition of accelerometer numbers. *Data questionable due to rotation of accelerometer.

TABLE 4-17. SUMMARY OF AVERAGED CAR ACCELEROMETER DATA FOR MOVING TEST DEVICE TEST 4

	Maxi	lmum	Min	imum	Max:	lmum
	Accele	eration	Velo	ocity	Displa	acement
Accelerometer	A	Time	V	Time	S	Time
Number	(G)	(msec)	(mph)	(msec)	(in.)	(msec)
Average of 1X and 2X (Compartment)	-44.6	61	-1.9	115	25.7	89
Average of 6X and 9X (Engine)	-116.6	40	-9.1*	54	17.9*	44

	TABLE	4-18.	SUMMAN POTENT FIXED	RY OF TIOMET TEST	CAR STRING ER DATA FOR DEVICE TEST	3
					Maximum D Displac	ynamic ement
Displaceme	ent Pot	entiom	eter		D	Time
(Number)		(Loca	tion)		<u>(in.)</u>	(msec)
SP7		Fire	wall		8.5	199
	TABLE	4-19.	SUMMAF POTENI MOVINC	Y OF IOMET TEST	CAR STRING ER DATA FOR DEVICE TEST	4
					Maximum D Displac	ynamic ement
Displaceme	ent Pot	entiome	eter		D	Time
(Number)		(Locat	ion)		(in.)	(msec)
SP7		Firew	vall		Data System	Failure

In Test 4, the string potentiometer data for the vehicle was lost because of the difficulty in placing the string potentiometer in an area that would not be disturbed during the crash impact.

In both tests, since the amount of crush was high, rotation of engine accelerometers (Nos. 6 and 9) occurred giving erroneous velocity and displacement peaks. In addition, displacement data from the accelerometer located at the front crossmember of the car (Location 7) was suspect, also due to the rotation of the accelerometer during impact.

4.3 TEST DEVICE SUMMARY

This section of the report presents a summary of data gathered from the fixed and moving Test Devices. This includes summaries of load cell, string potentiometer, strain gauge, and accelerometer data, and post-test honeycomb profiles for both fixed and moving Test Device tests.

Post-test Test Device configurations for fixed and moving Test Device tests are shown in Figures 4-13 and 4-14.

A summary of peak values of load cell data is shown in Table 4-20 for Test 3 and Table 4-21 for Test 4. These were the maximum measured forces for each load cell along with its corresponding time recorded during the event. Tables 4-22 and 4-23 present a summary of grouped load cell data for each test. The front face of the Test Device was divided into six areas of loading. These data show which areas of the car tended to be more aggressive. Load cell forces for individual load cells are shown in Figures 4-15 through 4-22. These plots also show the relative lateral symmetry of car data recorded with the Test Device face. Some load may have been lost during the period 50-63 msec in Test 3 and 28-53 msec in Test 4, due to load cell contact with the backing plate (A4, A5, A7, B4, B5, B7).

A load cell distribution at selected time intervals for the car/Test Device interface for each test is shown in Figures 4-23 through 4-28. These values are shown for forces over 1,000 pounds at a particular time segment. Any location with a value below 1,000 pounds was not considered an aggressive part of the car at that particular time frame. Calcomp plots of all load cell data by columns and grouped load cell summations are shown in Appendix B for Test 3 and Appendix C for Test 4.



Figure 4-13. Post-test Fixed Test Device Configuration - Test 3.





TABLE 4-20.	SUMN TESI	MARY (DEV)	OF MAX ICE TI	KIMUM EST 3	LOAD	CELL	DATA	FOR F	IXED	
Parameter	F	≷ight	Half	of Ca	ar		Left	Half d	of Ċai	<u>.</u>
Load Cell (No.)	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1
Force (klb)	0.35	4.57	2.23	1.79	2.11	1.92	2.16	2.25	4.37	0.56
Time (msec)	75	65	49	56	26	60	61	59	59	69
Load Cell (No.)	C10	C9	C8	C7	C6	C5*	C4	C3	C2	C1
Force (klb)	1.15 [^]	5.90	2.97	3.20	3.11	5.38	2.63	2.60	4.27	0.60
Time (msec)	28	63	61	61	55	61	56	21	67	50
Load Cell (No.)	B10	B9	B8	B7	B6	B5*	B4	B3	B2	B1
Force (klb)	1.84	2.94	2.93	**	5.13	5.25	9.54	2.64	2.78	1.32
Time (msec)	30	27	55	58	48	52	58	26	27	56
Load Cell (No.)	A10	A9	A8	A7	A6	A5	A4	A3	A2	Al
Force (klb)	1.05	2.39	2.70	8.50	5.43	3.09	8.56	2.58	2.89	1.07
Time (msec)	28	24	58	44	55	60	44	63	29	22

*Honeycomb module pulled off from impact with car. **12.36 (maximum measured force).

TABLE 4-21.	SUMN TESI	ARY (DEVI	OF MAX ICE TH	KIMUM EST 4	LOAD	CELL	ΟΑΤΑ Ι	FOR MO	OVING	
Parameter	F	Right	Half	of Ca	ar]	Left 1	Half d	of Ca	c
Load Cell (No.)	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1
Force (klb)	0.24	1.37	2.78	2.12	1.95	2.32	2.41	2.30	2.60	2.58*
Time (msec)	56	57	40	28	42	43	42	45	38	52
Load Cell (No.)	C10	C9	C8	C7	C6	C 5	C4	C3	C2	C1
Force (klb)	0.51	6.48	2.58	1.48	3.45	**	3.41	2.77	3.42	4.96
Time (msec)	37	25	17	50	44	44	44	22	23	24
Load Cell (No.)	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1
Force (klb)	0.89	3.28	3.29	5.76	5.10	8.18	9.47	2.69	2.89	2.26
Time (msec)	24	22	22	22	43	45	45	21	18	18
Load Cell (No.)	A10	A9	Λ8	A7	A6	A5	A4	A3	A2	A1
Force (klb)	0.41	6.40	2.82	6.31	3.75	7.23	8.28	2.13	5.81	1.89
Time (msec)	17	50	50	20	43	35	50	26	47	80
*Honeycomb mod	ule pu	ulled	off :	from :	impact	- with	car.			

**9.79 (maximum measured force).

TABLE 4-22.	SUMMARY OF GROUPED	LOAD CELL DATA	- TEST 3
Parameter	Right Side	Center of	Left Side
	of Car	Car	of Car
Load Cells (No.)	D8 - D10 &	D4 - D7 &	D1 - D3 &
	C8 - C10	C4 - C7	C1 - C3
Force (klb)	15.30	21.58	10.21
Time	64	61	59
Load Cells (No.)	B8 - B10 &	B4 - B7 &	Bl - B3 &
	A8 - A10	A4 - A7	Al - A3
Force (klb)	12.25	49.93	12.40
Time (msec)	· 26	52	28

TABLE 4-23.	SUMMARY OF GROUPED	LOAD CELL DATA	- TEST 4
Parameter	Right Side	Center of	Left Side
	of Car	Car	Of Car
Load Cells (No.)	D8 - D10 &	D4 - D7 &	D1 - D3 &
	C8 - C10	C4 - C7	C1 - C3
Force (klb)	8.66	$\begin{array}{r} 26.07 \\ 44 \end{array}$	12.05
Time	25		23
Load Cells (No.)	B8 - B10 &	B4 - B7 &	Bl - B3 &
	A8 - A10	A4 - A7	Al - A3
Force (klb)	12.85	49.92	13.74
Time (msec)	22	43	23

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In the fixed Test Device test, the maximum total load cell force recorded was 108,490 pounds at 56 milliseconds after impact and the maximum individual load cell force recorded was 12,360 pounds on module B7 at 58 milliseconds. This was caused mostly from the bumper guard on the passenger side of the vehicle rotating upwards. Most of the loads were caused by the bumper and the bumper guards hitting rows A and B simultaneously, with row D seeing small loads from the hood, and columns 1 and 10 seeing very small forces. Loads recorded on row C were caused by engine/ radiator area of the car. Modules B5 and C5 were pulled off the

Figure 4-15. Test Device Load Cell Forces on Row A for Test 8316-3.





12358 LB*

Figure 4-16. Test Device Load Cell Forces on Row B for Test 8316-3.

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Test Device Load Cell Forces on Row C for Test 8316-3. Figure 4-17.







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Figure 4-21. Test Device Load Cell Forces on Row C for Test 8316-4.









56 msec. Ford Torino/Fixed Test Device Load Distribution at 1975 Figure 4-24.



90 msec. 1975 Ford Torino/Fixed Test Device Load Distribution at Figure 4-25.



1975 Ford Torino/Moving Test Device Load Distribution at 23 msec. Figure 4-26.



1975 Ford Torino/Moving Test Device Load Distribution at 32 msec. Figure 4-27.



face of the Test Device when the hood latch grabbed the honeycomb material.

For the moving Test Device test, the total load cell force recorded was 99,940 pounds* at 43 milliseconds after impact and the maximum individual load cell force recorded was 9,790 pounds on module C5 at 44 milliseconds. Loads recorded during this test were smaller than those in Test 3, mainly because of the energy loss in causing the moving Test Device to rebound. As in Test 3, most of the loads were caused by the bumper and bumper guards on rows A and B, with row D seeing small loads from deformation of the hood. Honeycomb modules Cl, D2, and Al0 were sheared off of the Test Device face from impact. Module Dl was pulled off by deforming sheet metal of the car.

Accelerometer data recorded from the moving Test Device are given in Table 4-24. Accelerometers were located on the right and left frame members of the Test Device and were averaged to give acceleration, velocity, and displacement curves for the Test Device. This data was used in comparing the total force from both load cell and accelerometer data for both tests, which is presented in Tables 4-25 and 4-26.

String potentiometer and strain gauge data for each test are presented in Tables 4-27 through 4-30. String potentiometers were placed at selected locations on the Test Device to measure dynamic crush of the honeycomb. The displacement measured on the honeycomb is an indication of the dynamic crush at one particular point on the honeycomb modules, in all cases, the center of the module. Since the vehicle striking the honeycomb is not a uniformly flat surface, the crush measurement at the center of the module is not necessarily an indication of crush to the remainder of the aluminum honeycomb. Strain gauge data was used to see how typical loads would affect key structural members in bending on the Test Device. Figure 4-29 shows typical strain gauge curves for the *The actual force may have reached 169,000 pounds (see Figure 4-33).

TABI	LE 4-24. SUMM ACCE	ARY OF MOVIN	NG TEST DE NTA	VICE	
	Maximum Accelerati	Mir on Vel	nimum Locity	Max Displa	imum cement
Accelerometer Number	A Tim (G) (mse	e V c) (mph)	Time (msec)	S (in.)	Time (msec)
AlR	-41.5 41	-5.2	2 154	20.9	79
A2L	-44.7 45	-5.4	200	21.2	77
Average of AlR and A2L	-42.2 45	-5.3	3 156	21.1	78
	·				
TABLE 4-25.	COMPARISON OF ACCELEROMETEF	' TOTAL FORCE R DATA - FIXE	E FROM LOAI	D CELL AN VICE	D
Parameter	Test Device Force Data*	Test D Accele Dat	Device Pration	Engir Accele Dat	e/Car eration
Force (1b)	108,490	N	IA.	194,	900
Fime (msec)	56				66
*Sum of 40 lo **Average of t vice weight. ***Average of c average of e	ad cells. cest device ac ar accelerome angine acceler	celerometers ters 1 and 2 ometers 6 an	s 1 and 2 ? times ca: nd 9 times	times tes r weight engine w	plus plus eight
TABLE 4-26.	COMPARISON OF ACCELEROMETER	F TOTAL FORCE R DATA - MOVI	E FROM LOA ING TEST D	D CELL AN EVICE	ID
	Test Device	Test Accele	Device eration	Engir Accele	e/Car
Parameter	Force Data*	. Dat	_d	Dat	.a***
Parameter Force (lb)	Force Data* 99,940	Dat 168,	,900	169,	.a*** 700

vice weight.
***Average of car accelerometers 1 and 2 times car weight plus
average of engine accelerometers 6 and 9 times engine weight.

Displace	ment	Maximum Displac	Dynamic cement
Potention (Number	eter r)	D (in.)	Time (msec)
Individual	Units		
• SP1 @	A3	3.7	89
• SP2 @	A8	3.6	81
• SP3 @	В5	1.9	108
• SP4 @	C2	2.4	107
• SP5 @	C6	3.4	80
• SP6 @	С9	2.4	182

TABLE 4-27. SUMMARY OF FIXED TEST DEVICE STRING POTENTIOMETER DATA

TABLE 4	-28. SUMMARY OF	FIXED TEST DEVI	CE STRAIN (GAUGE DATA
Strai	n Gauge	Maximum Strain	Maximum	Maximum
(Number)	(Location)	<u>(µ in./in.)</u>	<u>(psi)*</u>	(msec)
SGl	Row B Front Beam	2343	70,290	61
SG2	Row C Front Beam	568	17,040	57

most highly stressed member. The maximum allowable (yield) strain was 3350 µin./in., which is quite adequate for the strain data recorded for this test. At the end of the test series involving the Ford vehicle, it was noted that small localized bending of the high strength horizontal beams of row B occurred where the load cells attach to the Test Device. The bending of the material was due to the fact that the aluminum impact plates were subjected to high torque loads when struck on the outer edges of the plate. For the next series of tests, the front face of row B beam will be rotated 180° in order to maintain a flat surface for the load cells.

Displacer	nent	Maximum Displa	Dynamic cement
Potentione (Number	eter	D (in.)	Time (msec)
Individual	Units		· · ·
• SP1 @	A3	3.9	141*
• SP2 @	A8	4.7	141
• SP3 @	В5	-3.6	162**
• SP4 @	C2	4.2	50
• SP5 @	C6	2.9	60
• SP6 @	C9	3.5	69
*			

TABLE 4-29. SUMMARY OF MOVING TEST DEVICE STRING POTENTIOMETER DATA

*Questionable data.

**Data system failure.

Strain	n Gauge	Maximum Strain	Maximum Stress	Maximum Timo
(Number)	(Location)	<u>(µ in./in.)</u>	<u>(psi)*</u>	(msec)
SGl	Row B Front Beam	2425	72,750	49
SG2	Row C Front Beam	848	25,440	46
SG3	Right Frame Rail	-554**	16,620	38



Figure 4-29. Strain Gauge Data - Row B Horizontal Beam.

The aluminum honeycomb crush profiles for fixed and moving Test Device tests are presented in Tables 4-31 and 4-32. Refer to Figures 4-13 and 4-14 for a view of the post-test configuration of the honeycomb. Most of the bottoming out of the honeycomb occurred at rows A and B, where it was struck by the bumper and bumper guards. In Test 3, honeycomb modules B5 and C5 were pulled off of the vehicle at rebound while modules C4 and C7 were pulled out by rotation of the bumper. In Test 4, modules C1, D2, and A10 sheared off the Test Device face at impact and module D1 was pulled off the Test Device face at rebound.

A comparison of dynamic crush from accelerometer data and film analysis for each test is shown in Figures 4-30 and 4-31. Since the vehicle does not act as a rigid body during the test, and vehicle accelerometer data is only representative of one location in an elastic body (at the B-pillar of the car), this data tends to be consistently higher than the data from film analysis. The data from film analysis is considered more accurate since a visual measurement of crush versus time is taken.

Total load cell force data and calculated inertia force from accelerometer data is shown in Figure 4-32 for Test 3 and Figure 4-33 for Test 4. Since the fixed Test Device is not instrumented with accelerometers, the inertia force was calculated using the car data, namely the vehicle's averaged accelerometer data along with its test weight. In this case, the engine and car mass were considered as separate masses, since their dynamics during the event are different. The total inertia force was calculated by using F = ma for the engine and car mass separately, and adding the two together. In the moving Test Device test, the inertia force can also be calculated using accelerometer data from the Test Device. In this case, the Test Device is considered a rigid body. Figure 4-34 shows the load cell force-deflection characteristics for both tests. The vehicle rate of stiffness as load is applied is given in Table 4-33.

FIXED TEST DEVICE HONEYCOME CRUSH PROFILE TABLE 4-31.

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VEHICLE: 1975 Ford Torino 4-door Sedan

 	Height Above		Dist of C	ance R enter	ight (in.)				Dist of C	ance L enter	eft* (in.)		
Location	(in.)	37.1	28.9	20.6	12.4	4.1	ษ	4.1	12.4	20.6	28.9	37.1	Average
Row D	34.3	-0.2	4.2	0.7	0.5	1.5	2.0	0.8	0.6	0.8	0.8	-0.2	
Row C	27.0	1•8	3.0	4.3	0.7	4.0	5.7	*	0.5	2.6	3.1	-0.3	2.5
Row B	19.8	0.6	2.6	3.9	ີ 2 • 2	l.0	3.7	* *	5.7	3.1	5.6	-0.3	3.1
Row A	12.5	-0.3	4.6	3.6	5.7	4.1	6.1	4.0	3.2	3.7	4.7	0.0	3.6
Column		10	6	ω	7	9		Ŀ,	4	С	2		
*The lef **Honeyco	t side o mb modul	f the es pul	test d led or	evice shear	is as . ed off	viewed of Tes	from 1 st Devi	the ca. ice fr	r driv om imp	er's p act of	ositio car.	u	

TABLE 4-32. MOVING TEST DEVICE HONEYCOMB CRUSH PROFILE

VEHICLE: 1975 Ford Torino 4-door Sedan

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	Height Above		Dist. of C	ance R enter	ight (in.)				Dist of C	ance L enter	eft* (in.)		
Location	(in.)	37.1	28.9	20.6	12.4	4.1	দ	4.1	12.4	20.6	28.9	37.1	Average
Row D	34.3	-1.8	-0.3	3.4	2.3	0	1.3	0.7	l.0	4.4	*	* *	1.2
Row C	27.0	-1.5	3 . 5	2.2	-0.4	2.3	ິຕ ຕ	4.2	2.8	2.0	3.4	*	2.2
Row B	19.8	1.3	0.3	1•3	1.0	0.5	2.7	0.4	5.2	2.5	3 . 3	3°3	2.0
Row A	12.5	*	4.4	4.3	3.2	3.8	2°2	4.1	4.3	4.0	4.6	2.6	4.1
Column		10	6	8	7	9		ம	4	m	2		
*ПНО]ОҒ	ע סייים + +	f the	+00+ Å	סייעם	ט מ יי ט יי	ידי מעים לד	from t	r po da	r driv	ar a	(. + . o (- F	

*The left side of the test device is as viewed from the car driver's position. **Honeycomb modules pulled or sheared off of Test Device from impact of car.

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150 71103205 (ACCELERATION DATA) TOTAL MUTUAL CRUSH (FILM ANALYSIS) CAR CRUSH [TOTAL MUTUAL CRUSH (FILM) MINUS HONEYCOMB CRUSH] Dynamic Crush During Collision for Fixed Test Device - Test 3. 125 100 TOTAL MUTUAL CRUSH ۱ TIME - MSEC 75 ŧ 50 I i ł 1 TORINO 1975 FORD 25 0 50 40 30 30 20 10 0

DYNAMIC_CRUSH - IN.

Figure 4-30.

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Dynamic Crush During Collision for Moving Test Device - Test 4. Figure 4-31.







Comparison of Load Cell Force-Deflection Characteristics for 1975 Ford Torino. Figure 4-34.



Rate (*) 3.49 3.12 For 30" Crush Peak Avg. 1 (klb) (klb) 3.51 108.5 52.4 46.9 99.3 FRONTAL STIFFNESS OF CARS AS A FUNCTION OF CRUSH DISTANCE Peak Avg. Rate (klb) (klb) (*) 3.46 For 24" Crush 42.1 41.5 86.1 86.1 з.99 3.57 Peak Avg. Rate (klb) (klb) (*) For 18" Crush 32.1 35.9 86.1 85.5 Rate (*) 2.95 2.59 For 12" Crush Peak Avg. (klb) (klb) 17.7 15.6 59.6 56.4 2.30 Rate (*) 1.18 For 6" Crush TABLE 4-33. Peak Avg. (klb) (klb) 6.9 3**.**5 16.0 9.9 *Rate in klb/in. Test Car 1 No. Model Ford Ford 4 m

Car interior intrusion is plotted against exterior dynamic crush of the vehicle in Figures 4-35 through 4-37. Dynamic interior crush was measured by means of a string potentiometer located along the centerline of the vehicle. A difficulty sometimes occurs during impact when outside influences interfere with the displacement of the string potentiometer, causing misleading data.

A crash pulse may be monitored on the Test Device face to determine the "hard" points on the vehicle. Figures 4-38 and 4-39 show where on the Test Device face the centroid of the total load cell force was acting, as a function of time.

4.4 OCCUPANT KINEMATICS

This section of the report presents the results of dummy response during the fixed and moving Test Device collisions. This includes peak values for each occupant's head, chest, and femur, restraint survival distance, and restraint system summaries.

In evaluating occupant response data, it must be remembered that, because of the high crash speeds, pulses measured by each occupant are very high and may exceed FMVSS 208 Standards. Figures 4-40 through 4-47 show pre-test and post-test configurations of the occupant for each test. A summary of occupant response data is presented in Table 4-34 with restraint system data presented in Table 4-35.

In both tests, the left front occupant's head and chest made contact with the steering wheel and dash panel. In Test 4, the damage to the steering wheel and dash panel was less severe than in Test 3. The driver's head in Test 3 had a maximum longitudinal displacement of 76.6 inches at t = 130 milliseconds, while in Test 4, the maximum longitudinal displacement was 47.3 inches at t = 111 milliseconds. Post-test observations showed that both driver femurs made contact with the knee bolsters, causing severe damage to the area. In both tests, the driver's chest struck the steering wheel



Car Interior Intrusion Versus Exterior Car Crush.

Figure 4-35.

INTERIOR DYNAMIC INTRUSION - IN.







Car Exterior Crush and Interior Intrusion Versus Time for Moving Test Device - Test 4. Figure 4-37.







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Figure 4-40. Pre-test Driver Position - Test 3.



Figure 4-41. Post-test Driver Position - Test 3.

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Figure 4-42. Pre-test Passenger Position - Test 3.







Figure 4-44. Pre-test Driver Position - Test 4.



Figure 4-45. Post-test Driver Position - Test 4.



Figure 4-46. Pre-test Passenger Position - Test 4.



Figure 4-47. Post-test Passenger Position - Test 4.
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	VEHICLE	E: 1975	Ford To	orino					• .
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		Fixed	Test De	evice (No	o. 3)	Moving	Test D	evice (No	b. 4)
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		Left E Occup	Front Dant	Right I Occupa	Front	Left F Occup	ront Dant	Right H	ront Int
HeadX -160.3 89 -102.7 107 -55.0 92 -126.5 91Y -30.4 114 $+42.6$ 108 -22.6 104 $+54.7$ 91Z $+98.2$ 100 $+62.2$ 111 $+64.6$ 101 $+58.0$ 91R* 112.2 106 113.0 109 75.4 102 106.0 107 HIC 1824 $94-116$ 1691 $88-122$ 765 $80-127$ 1211 $89-126$ Chest X -85.8 88 -49.5 100 -58.7 88 -36.4 87 X -85.8 88 -49.5 100 -58.7 88 -36.4 87 Y -42.1 93 $+38.5$ 100 -26.9 86 $+28.9$ 81 Z -10.7 125 $+25.3$ 91 -16.6 99 $+12.8$ 77 R* 84.5 90 58.8 98 58.8 89 40.5 90 SI 924 200 668 200 518 200 326 200 Maximum Value (1b) $msec$) $maximum$ Value (1b) $msec$) $maximum$ Value (1b) $maximum$ Value (1b) $maximum$ Value (1b) $maximum$ Value (1b) $maximum$ Value (1b) $maximum$ Value (1b) $maximum$ Value (1b) $maximum$ 		Maximum Value (G)	T (msec)	Maximum Value (G)	T (msec)	Maximum Value (G)	T (msec)	Maximum Value (G)	T (msec)
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Y -30.4 114 $+42.6$ 108 -22.6 104 $+54.7$ 9 Z $+98.2$ 100 $+62.2$ 111 $+64.6$ 101 $+58.0$ 93 R* 112.2 106 113.0 109 75.4 102 106.0 100 HIC 1824 $94-116$ 1691 $088-122$ 765 $080-127$ 1211 $089-127$ ChestX -85.8 88 -49.5 100 -58.7 88 -36.4 87 Y -42.1 93 $+38.5$ 100 -26.9 86 $+28.9$ 87 Z -10.7 125 $+25.3$ 91 -16.6 99 $+12.8$ 77 R* 84.5 90 58.8 98 58.8 89 40.5 97 SI 924 200 668 200 518 200 326 200 Maximum Value (1b)Maximum (msec)Maximum (1b)Maximum (msec)Maximum (1b)Maximum (msec)Femurs LF -1407 66 -807 101 -2169 74 -692 77	Х	-160.3	89	-102.7	107	-55.0	92	-126.5	91
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Y	-30.4	114	+42.6	108	-22.6	104	+54.7	91
R*112.2106113.010975.4102106.010HIC1824 @94-1161691 @88-122765 @80-1271211 @89-1ChestX-85.888-49.5100-58.788-36.487Y-42.193+38.5100-26.986+28.987Z-10.7125+25.391-16.699+12.877R*84.59058.89858.88940.590SI924 @200668 @200518 @200326 @200Maximum Value (lb)Maximum (msec)Maximum (lb)Maximum (msec)Maximum (lb)Maximum (msec)Maximum (lb)Maximum (msec)Femures LF-140766-807101-216974-6927	Z	+98.2	100	+62.2	111	+64.6	101	+58.0	98
HIC $1824 @ 94-116$ $1691 @ 88-122$ $765 @ 80-127$ $1211 @ 89-121 @ 89-127$ ChestX -85.8 88 -49.5 100 -58.7 88 -36.4 87 Y -42.1 93 $+38.5$ 100 -26.9 86 $+28.9$ 87 Z -10.7 125 $+25.3$ 91 -16.6 99 $+12.8$ 77 R* 84.5 90 58.8 98 58.8 89 40.5 97 SI $924 @ 200$ $668 @ 200$ $518 @ 200$ $326 @ 200$ Maximum Value (1b) $maximum(msec)$ $MaximumValue(1b)maximum(msec)MaximumValue(1b)maximum(msec)MaximumValue(1b)maximum(msec)MaximumValue(1b)maximum(msec)MaximumValue(1b)maximum(msec)MaximumValue(1b)maximum(msec)Maximum(msec)MaximumValue(1b)maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(1b)Maximum(msec)Maximum(1b)Maximum(msec)Maximum(1b)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum(msec)Maximum$	R*	112.2	106	113.0	109	75.4	102	106.0	109
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	HIC	1824 @	94-116	1691 @	88-122	765 @ 8	30-127	1211 [.] @	89-118
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	Chest								
Y -42.1 93 $+38.5$ 100 -26.9 86 $+28.9$ 8Z -10.7 125 $+25.3$ 91 -16.6 99 $+12.8$ 7R*84.59058.89858.88940.59SI924 @200668 @200518 @200326 @200Maximum Value (1b)T (msec)Maximum 	х́.	-85.8	88	-49.5	100	-58.7	88	-36.4	87
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	Y	-42.1	93	+38.5	100	-26.9	86	+28.9	88
R* 84.5 90 58.8 98 58.8 89 40.5 9 SI 924 @ 200 668 @ 200 518 @ 200 326 @ 200 Maximum Value (1b) Maxim Value (1b) Maximum Value (1b)	Z	-10.7	125	+25.3	91	-16.6	99	+12.8	75
SI 924 @ 200 668 @ 200 518 @ 200 326 @ 200 Maximum Value (1b) Maximum (1b) Maximum (1b) Maximum Value (1b) Maximum Value (1b) Maximum (1b) Maximum	R*	84.5	90	58.8	98	58.8	89	40.5	90
Maximum Value (1b)Maximum Value (1b)Maximum Value (1b)Maximum Value (msec)Maximum Value (1b)Maximum Value (msec)Femurs LF-140766-807101-216974-6927	SI	924 @	200	668 @	200	518 @	200	326 @	200
<u>Femurs</u> LF -1407 66 -807 101 -2169 74 -692 7		Maximum Value (1b)	T (msec)	Maximum Value (1b)	T (msec)	Maximum Value (1b)	T (msec)	Maximum Value (1b)	T (msec)
LF -1407 66 -807 101 -2169 74 -692 7	Femurs			·					
	LF	-1407	66	-807	101	-2169	74	-692	77
RT -1635 78 -1173 87 -1588 89 -609 4	RT	-1635	78	-1173	87	-1588	89	-609	45

2.4 .

TABLE 4-35. SUMMARY OF RESTRAINT	SYSTEM	Dž	ATA
VEHICLE: 1975 Ford Torino 4-door se	edan		
Fixed Test Device (No. 3)	Load @ (1b)	(1	Fime nsec)
Left Front Occupant			
Peak Shoulder Belt Load	1411	9	86
Peak Left Lap Belt Load	1297	0	86
Peak Right Lap Belt Load	1868	0	81
Right Front Occupant			
Peak Shoulder Belt Load	1761	0	110
Peak Left Lap Belt Load	2149	0	101*
Peak Right Lap Belt Load	1852	9	91
Moving Test Device (No. 4)			
Left Front Occupant			
Peak Shoulder Belt Load	1323	0	86
Peak Left Lap Belt Load	966	@	70
Peak Right Lap Belt Load	1753	6	73
Right Front Occupant			
Peak Shoulder Belt Load	1429	0	103
Peak Left Lap Belt Load	1678	0	80
Peak Right Lap Belt Load	1533	0	80
*Instrumentation failure >100 msec			

hub, which showed little sign of yielding and caused high acceleration values to appear. Since the energy transfer in Test 4 was different, the damage to the driver compartment was less severe and the occupant responses were less severe.

In each test, the right front passenger's head made contact with the dash panel. Post-test observations showed that the knees struck and completely destroyed the glove compartment area. In both tests, the dash panel became separated from the frame of the car from the impact. The passenger's chest loads were caused mainly by the shoulder belt restraint system. No visible contact was made with the passenger's chest in the occupant compartment.

Restraint Survival Distance (RSD) criteria is presented in Table 4-36. This value was used in efforts to determine relative vehicle crashworthiness. Values in this table reflect RSD values with and without a 7-millisecond shift. This shift is to account for crush of the honeycomb on the Test Device. The vehicle compartment deceleration pulse and restraint system pulse were used to compare available compartment space with the space necessary to decelerate the occupant. A critical element in calculating this value is the relative positioning of the dummy in the occupant compartment. Figures 4-48 through 4-51 show the pre-test and post-test occupant compartments for each test. Refer to Appendix D for an explanation of the methodology used to determine RSD values.

	TABLE 4-36.	SUMMARY OF	OCCUPA	NT RESTF	AINT S	URVIVA	L DIST	ANCE (RSD)		
			- +	ر م		AI (in	о (•	RS (in	о С.	RSI (in	* (•
NO.	Vehicle	Occupant	(msec)	(in.)	(in.)	Pre	Post	Pre	Post	Pre	Post
Υ	1975 Ford Torino	Driver	46.0	30.3	32.0	13.7	13.6	12.0	11.9	13.5	13.3
	4-door seaan	Passenger	46.0	30.4	32.0	13.9	13.4	12.3	11.8	13.7	I3.2
4	1975 Ford Torino	Driver	50.1	22.5	25.0	14.7	14.8	12.3	12.4	10.7	9.8
	4-door sedan	Passenger	50.1	22.3	20.5	14.3	14.1	11.7	11.5	9.5	8.4
ם מי מי מי מי	time when occupan displacement of c displacement of o	t velocity = ompartment fron	 compar from ini initia 	tment ve tial imp l impact	elocity bact to to t	ר - וו וו ר	-				
AID = RSD =	Available Interio Restraint Surviva	r Distance 1 Distance =	- AID -	(D _p - D _c	() t ()	ب ب			4		
NOTE: *Seve	AID and RDS are n-msec shift in ti	shown for pi me made to I	re- and RSD valu	post-cra e to coi	ish veh rrect f	icle g or cru	eometr sh of	y, res honeyc	pectiv omb of	ely. Test	









5.0 TEST FACILITIES AND EQUIPMENT

5.1 GENERAL

The impact tests in this program were conducted at the Monorail Impact Facility, shown in Figure 2-1. The barrier impact and midrange impact sites were used for the fixed Test Device/vehicle and moving Test Device/vehicle tests, respectively.

Table 5-1 describes the test equipment and its function as it applies to the test parameters.

TAI	BLE 5-1. TEST	r equipmi	ENT LIST AND FUNCTION
Item	Manufacturer	Model	Purpose
Timing Trap	Dynamic Science	None	Determine impact speed by fur- nishing a start and stop signal to recording oscillograph.
Oscillograph	Bell and Howell	5-134	Records timing start and stop signals from timing traps, cable drum drive rpm, and im- pact switch.
Speed Control	Dynamic Science	None	Precision control of cable drive drum rpm.
Beam Scales	Western	WP2000	Used to determine vehicle test weights.
High-speed Motion Picture Cameras	Photosonics	16-1B	Used for side, overhead, bar- rier, pit, and on-board film coverage as required.
Motion Picture Camera	Bolex	H-16	Panning and documentation.
Still Camera	Kowa	6	Documentary photo coverage.

TABLE	5-1. TEST EQ	UIPMENT	LIST AND FUNCTION (CONTD)
Item	Manufacturer	Model	Purpose
100 and 1000 Hz Time Code Generators	Dynamic Science	None	Furnish timing signal for high- speed cameras and a 1 milli- second timing for velocity de- termination.
Stop Watch	Brietling	None	Time for collection of fuel leak samples.
Containers		-	Collection for fuel leak sam- ples.
Graduated Cylinder	Kimes	-	Fuel volume measurement.
Calibrated Steel Rule	Starret	48 in.	Precision measurement of veloc- ity trap spacing.
Anthropo- morphic Dummies	Alderson	(GFE)	To ballast the vehicle and to gather occupant response data.
Dummy and Vehicle Acceler- ometers	Endevco	7233C	Measures acceleration.
String Pots	Celesco	PT-101- 15	Measures displacement
l2.5K Load Cells	Interface	1210 FS 1210 LT	Force on honeycomb modules.
3K Load Cell (Femur)	GSE	2435	Determines femur load forces.
3500-pound Load Cell (Belt)	LeBow	3419	Measures belt loads.
F.M. Multi- plexor Tape Recorder	Sangamo	Sabre III	Records instrumentation sig- nals.
Oscillograph	Bell and Howell	5-134	Records real-time quick-look data.
Signal Conditioner	Ectron	M140	Conditions instrument output signal for recording.

5.2 FACILITY AND EQUIPMENT DESCRIPTION

The following paragraphs briefly describe the track facility and equipment, their function, and mode of operation.

5.2.1 Test Track and Guidance System

The test track consists of 1,200 feet of asphalt pavement $(SN = 75 \pm 5)$, 14 feet in width. The length allows sufficient acceleration distance to accommodate impact speeds in excess of 60 mph with sufficient distance remaining to abort the test if necessary. Guidance for the test vehicle is provided by a sliding shoe attached to the vehicle. The sliding shoe rides on the monorail embedded in the test track. Prior to impact, the shoe is mechanically released from the test vehicle.

5.2.2 <u>Tow System and Velocity Control</u>

The tow system consists of a drum-driven endless cable powered by a pair of 390-cubic-inch engines driven in tandem driving a modified three-speed C-6 automatic truck transmission. The tow system can propel a 6,000-pound vehicle into the fixed barrier at 75 mph or two 4,000-pound vehicles into each other at a closing speed of 90 mph. Velocity control is achieved through a manually controlled throttle system. A visual readout of speed versus distance is provided and compared with the "ideal curve." Velocity control under ± 0.5 mph is realizable down to 20 mph and ± 2.0 percent down to zero mph.

5.2.3 Abort System

Automatic abort capability is provided through the vehicle service brakes which are actuated by releasing high-pressure air into the hydraulic system. Abort criteria consists of vehicle speed, data acquisition and instrumentation system readiness, and

stability of the vehicle on the test track. The first two criteria are automatically monitored by the test control system while the third criterion is visually monitored by the test conductor. Manual abort provisions are available to the test conductor. Upon verifying vehicle speed, the test control system automatically deactivates the abort system to preclude an inadvertent test abort immediately prior to impact.

5.2.4 Master Control System

The master control system used for impact tests controls and monitors all primary system functions that must operate throughout a predetermined interval during a test. This includes the starting and stopping of the FM multiplexer tape recorder, highspeed cameras, and oscillograph, and the control of the power winch which propels the test vehicle. The operations of the various devices is confirmed, including vehicle velocity and tape recorder speed synchronization, before it passes through a "commit" window. When the vehicle is committed, the abort system is disarmed, preventing an accidental abort after the point of no return is reached.

Any system malfunction, including improper vehicle velocity up to the commit window, generates an abort. The control system uses the pulse output from the IRIG time base generator as a clock with a manual push button defining time zero. The logic circuits compare pulse counts from time zero to preset values dialed in at the control panel. As each control circuit gets an equal comparison, that circuit is turned on. If the self-test circuit does not verify, the abort system is automatically activated. After a successful vehicle test, the last control circuit shuts the entire system down. The manual backup control system provides the test conductor with the option of manually aborting the test if the need arises.

5.2.5 Fixed Impact Barrier

The basic fixed impact barrier consists of a reinforced concrete structure, 6 feet high, 6 feet thick, and 12 feet wide, weighing approximately 100,000 pounds and complying with SAE J850. This barrier can be fitted with various modules including a flatfaced barrier adjustable to angles up to 45 degrees, as well as a pole barrier. This barrier system conforms to the definition of a "fixed collision barrier" as defined in Federal Register, Vol. 35, No. 135, page 11242 (July 14, 1970).

A camera pit is located immediately in front of the impact barrier and is 6 feet wide, 8 feet deep, and 20 feet long. The pit is covered with a metal grid which supports the vehicle as it passes over, yet allows photographing of the vehicle underside when required. Electrical outlets are provided for powering floodlights and high-speed cameras. A fixed overhead camera tower cantilevered over the barrier test site provides over-site photography.

5.2.6 Midrange Impact Site

The midrange test site consists of a 40-foot by 60-foot asphalt pad. Centrally located within this area is a camera pit constructed of reinforced concrete which is 6 feet wide, 8 feet deep, and 24 feet long. A metal grid covers the camera pit, allowing photographs to be taken of the vehicle underside. A movable overhead camera tower is provided for over-site photography.

5.2.7 High-speed Photography

Six high-speed 16mm cameras with 100 Hz timing marks and one panning camera are used for photographic test documentation. Precise field of view monitoring is accomplished by bore sighting with the vehicle at the impact site prior to the test.

APPENDIX A

CAR-TO-TEST DEVICE CRASH ANALYSIS

Prepared by:

Mark Beharrell Jack Beharrell Analysis Engineer Special Projects Department 5/8/78

- 1.0 DETERMINATION OF EQUIVALENT CLOSING SPEED FOR MOVING BARRIER COLLISION
 - Moving Barrier Collision:

$$\Delta V_{A} = \frac{W_{B}}{(W_{A} + W_{B})} [V_{A}(0) - V_{B}(0)] = \frac{W_{B}}{(W_{A} + W_{B})} [\Delta V(0)]$$
(1)

where

 $\frac{\Delta V_A}{\Delta V_A} = \frac{\text{velocity change of Vehicle A in moving}}{\text{barrier impact (mph)}}$

 W_A, W_B = weight of Vehicles A and B, respectively (1b)

 $V_A(0), V_B(0)$ = initial velocities of Vehicles A and B, respectfully (mph)

 $\Delta V(0) = initial closing velocity (mph)$

Fixed Barrier Collision:

$$V'_{A} = V'_{A}(0)$$

where

 $\Delta V_{\lambda}^{\prime}$ = velocity change in fixed barrier impact (mph) $V_{\Lambda}^{\prime}(0)$ = initial velocity of Vehicle' Λ (mph)

Δ

Equality Conditions

The desired equality condition (the same vehicle velocity change in the moving barrier and fixed barrier impacts) implies:

> $\Delta V_{\Lambda} = \Delta V_{\Lambda}^{\dagger}$ (3)

(2)

Therefore Equations (1) and (2) result in the following condition for the "equivalent" closing speed, $\Lambda V(0)$, for the moving barrier test:

$$\Delta V(0) = V_{\Lambda}(0) \left[\frac{W_{B}}{(W_{\Lambda} + W_{B})} \right]^{-1}$$
(4)

For $W_{\rm B}$ = 4000 lb, and $V_{\rm A}^{\dagger}(0)$ = 40 mph, Equation (4) becomes:

$$\Delta V(0) = 40 \left[\frac{4000}{(W_{\Lambda} + 4000)} \right]^{-1}$$
(5)

2.0 DERIVATION OF EQUATIONS OF MOTION

The vehicle-barrier impact was modeled as a system of two masses connected by a linear spring. m_2 represents the mass of the barrier test device; m_1 that of the car.



The displacements x_1 and x_2 are measured from the positions of static equilibrium. The equations of motion are:

$$m_1 \ddot{x}_1 + K (x_1 - x_2) = 0$$
 (1)

$$m_2 \ddot{x}_2 + K (x_2 - x_1) = 0$$
 (2)

Substitution of the solutions

 $x_1 = X_1 \cos \omega_n t$, $x_2 = X_2 \cos \omega_n t$

leads to the normal mode shape

$$\rho = \frac{X_2}{X_1} = \frac{K}{K - m_2 \omega_n^2} = \frac{-m_1 \omega_n^2 + K}{K}$$
(3)

The characteristic equation for the system has the solutions

$$\omega_{n_1}^2 = 0, \quad \omega_{n_2}^2 = K \left(\frac{m_1 + m_2}{m_1 m_2} \right)$$
 (4)

The solution $\omega_n = 0$ represents a lateral displacement of the system with no spring compression or extension.

The general solution of the equations (1) and (2) is of the form

$$x_1 = B_1 + B_2 t + B_3 \cos \omega_{n_2} t + B_4 \sin \omega_{n_2} t$$

$$x_2 = B_1 + B_2 t + B_3 \rho \cos \omega_n t + B_4 \rho \sin \omega_n t$$
 (5)

where $B_1 = \frac{x_{20} - \rho x_{10}}{1 - \rho}$, $B_3 = \frac{x_{10} - x_{20}}{1 - \rho}$ $B_2 = \frac{V_{20} - \rho V_{10}}{1 - \rho}$, $B_4 = \frac{V_{10} - V_{20}}{(1 - \rho) \omega_{n_2}}$ (6)

 x_{10} , V_{10} , x_{20} , V_{20} are the initial displacements and velocities of the vehicle and barrier, respectively. We may set $x_{10} = x_{20} = 0$; then $B_1 = B_3 = 0$. Differentiation of (5) with respect to time and substitution of (6) leads to the following relations for the displacements, velocities, and accelerations of the car and barrier:

$$x_{1} = \left(\frac{V_{20} - \rho V_{10}}{1 - \rho}\right) t + \left(\frac{V_{10} - V_{20}}{(1 - \rho) \omega_{n_{2}}}\right) \sin \omega_{n_{2}} t$$
$$x_{2} = \left(\frac{V_{20} - \rho V_{10}}{1 - \rho}\right) t + \left(\frac{V_{10} - V_{20}}{(1 - \rho) \omega_{n_{2}}}\right) \rho \sin \omega_{n_{2}} t$$
(7)

$$\dot{x}_{1} = \frac{\nabla_{20} - \rho \nabla_{10}}{1 - \rho} + \left(\frac{\nabla_{10} - \nabla_{20}}{1 - \rho}\right) \cos \omega_{n_{2}} t$$

$$\dot{x}_{2} = \frac{\nabla_{20} - \rho \nabla_{10}}{1 - \rho} + \left(\frac{\nabla_{10} - \nabla_{20}}{1 - \rho}\right) \rho \cos \omega_{n_{2}} t$$
(8)
$$\ddot{x}_{1} = -\left(\frac{\nabla_{10} - \nabla_{20}}{1 - \rho}\right) \omega_{n_{2}} \sin \omega_{n_{2}} t$$

$$\ddot{x}_{2} = -\left(\frac{V_{10} - V_{20}}{1 - \rho}\right) \rho \omega_{n_{2}} \sin \omega_{n_{2}} t$$
(9)

Using equations (3) and (4), the quantities ρ and 1- ρ become:

 $\rho = \frac{-m_1}{m_2}$

$$1 - \rho = \frac{m_1 + m_2}{m_2}$$
(10)

For the fixed barrier case, the above equations for ρ and $1-\rho$ reduce to $\rho=0$, $1-\rho = 1$, $\omega_n = (\frac{K}{m_1})^{1/2}$; then x, x, x become: $(m_2 = \omega, V_{20} = 0)$

$$x_{1} = V_{10} \left(\frac{m_{1}}{K}\right)^{1/2} \sin \left(\frac{K}{m_{1}}\right)^{1/2} t$$

$$x_{2} = 0$$

$$(11)$$

$$\dot{x}_{1} = V_{10} \cos \left(\frac{K}{m_{1}}\right)^{1/2} t$$

$$\dot{x}_{2} = 0$$

$$(12)$$

$$\ddot{x}_{1} = -V_{10} \left(\frac{K}{m_{1}}\right)^{1/2} \sin\left(\frac{K}{m_{1}}\right)^{1/2} t$$

$$\ddot{x}_{2} = 0$$
(13)

3.0 CALCULATION OF EQUIVALENT CLOSING VELOCITIES FOR SELECTED CRASH PARAMETERS

Maintaining selected crash parameters constant for both the fixed barrier and the moving barrier conditions, equivalent vehiclebarrier closing velocities were calculated. The applicable equations and some equivalent closing speeds are summarized in Table 1. Table 2 presents a summary of the times of occurrence for selected vehicle parameters. It should be noted that the closing speeds may be obtained by adjusting either the vehicle speed, the barrier speed, or both.

P is the parameter to be maintained constant.

Barred quantities refer to moving barrier case.

(1) P: Initial relative velocity of vehicle and barrier.

Fixed barrier case:

Initial relative velocity = $V_{10} - V_{20} = V_{10}$

Moving barrier case:

Initial relative velocity = $\overline{V}_{10} - \overline{V}_{20}$

The equivalent closing speed is then given by the equality:

$$\overline{V}_{10} - \overline{V}_{20} = V_{10}$$

(2) P: Maximum velocity change of vehicle. Velocity change = $\Delta V = V_{10} - x_1$ final

$$\therefore \Delta V = V_{10} - (\frac{V_{20} - \rho V_{10}}{1 - \rho})$$

$$= \frac{V_{10} - V_{20}}{1 - \rho}$$

Fixed barrier case:

$$\Delta V = V_{10}$$

Moving barrier case:

$$\overline{\Delta V} = \frac{(\overline{V}_{10} - \overline{V}_{20})}{(m_1 + m_2)} m_2$$

For $\Delta V = \overline{\Delta V}$

$$\overline{v}_{10} - \overline{v}_{20} = \left(\frac{m_1 + m_2}{m_2}\right) v_{10}$$

(3) P: Maximum momentum change of vehicle.

The condition here is

$$m_1 \Delta V = m_1 \overline{\Delta V}$$

Therefore the result is the same as in (2):

$$\overline{v}_{10} - \overline{v}_{20} = \left(\frac{m_1 + m_2}{m_2}\right) v_{10}$$

(4) P: Maximum passenger compartment acceleration (deceleration)

Fixed barrier case:

From equation (13)

$$|\ddot{x}_{1}|_{\max} = v_{10} (\frac{K}{m_{1}})^{1/2}$$

Moving barrier case:

From equation (9)

$$|\vec{x}_{1}|_{\max} = (\vec{v}_{10} - \vec{v}_{20}) \left[\frac{K (m_{1} + m_{2})}{m_{1} m_{2}} \right]^{1/2} \left(\frac{m_{2}}{m_{1} + m_{2}} \right)$$

Equating $|\ddot{x}_1|_{\max}$ and $|\ddot{\ddot{x}}_1|_{\max}$ gives

$$\overline{V}_{10} - \overline{V}_{20} = \left(\frac{m_1 + m_2}{m_2}\right)^{1/2} V_{10}$$

(5) P: Maximum spring crush

Maximum spring crush = $|x_1 - x_2|_{max}$

$$= \frac{V_{10} - V_{20}}{\omega_n}$$

Fixed barrier case:

Maximum crush = $V_{10} \left(\frac{m_1}{K}\right)^{1/2}$

Moving barrier case: •

Maximum crush =
$$(\overline{V}_{10} - \overline{V}_{20}) \left(\frac{m_1 m_2}{K(m_1 + m_2)} \right)^{1/2}$$

The equivalent closing speed for equality of maximum spring crush is then

$$\overline{v}_{10} - \overline{v}_{20} = \left(\frac{m_1 + m_2}{m_2}\right)^{1/2} v_{10}$$

(6) P: Maximum energy absorbed by vehicle.

This calculation is based upon the assumption that all the energy of spring compression represents energy absorbed by the vehicle.

Energy absorbed = $\frac{1}{2}$ K $(x_1 - x_2)^2$

Maximum energy absorbed is then given by the quantity $\frac{1}{2} \kappa \left[\left(\frac{V_{10} - V_{20}}{\omega_n} \right) \right]^2$

Fixed barrier case:

Maximum energy absorbed =
$$\frac{1}{2}$$
 K V₁₀

Moving barrier case:

Maximum energy absorbed = $\frac{1}{2} \frac{V}{V_{10}}$

$$\begin{bmatrix} (\overline{v}_{10} - \overline{v}_{20}) & (m_1 & m_2)^{1/2} \\ \hline (K(m_1 + & m_2))^{1/2} \end{bmatrix}^2$$

1 / 2

Equivalent closing speed for equal maximum energy absorption is then:

$$\overline{V}_{10} - \overline{V}_{20} = \left(\frac{m_1 + m_2}{m_2}\right)^{1/2} V_{10}$$

3.1 TIME OF OCCURRENCE OF MAXIMUM VELOCITY AND MOMENTUM CHANGE, MAXIMUM ACCELERATION, MAXIMUM SPRING CRUSH, AND MAXIMUM ENERGY ABSORPTION

From equations (7), (8), and (9), it is apparent that this time of occurrence is given by

$$\omega_n t = \frac{11}{2}$$

or $t = \frac{\pi}{2\omega_n}$

Fixed barrier case (t \equiv T)

 $T = \frac{II}{2} \left(\frac{m_1}{K}\right)^{1/2}$

Moving barrier case (t $\equiv \tau$)

$$\tau = \frac{\pi}{2} \left[\frac{m_1 m_2}{K(m_1 + m_2)} \right]^{1/2}$$

The ratio $\frac{\tau}{T} = \left(\frac{m_2}{m_1 + m_2}\right)^{1/2}$

Values for this ratio for several cars are given in Table 2.

4.0 DYNAMIC TEST CONDITIONS AND VEHICLE DATA

4.1 DEFINITIONS OF SYMBOLS

 $W_2 (m_2) = weight (mass) of barrier test device.$ $<math>W_1 (m_1) = weight (mass) of vehicle.$ $V_{10} = initial velocity of vehicle for fixed barrier case.$ $\overline{V}_{10} = initial velocity of vehicle for moving barrier case$ $\overline{V}_{20} = initial velocity of moving barrier.$

Κ = spring constant of vehicle crush structure. = time of occurrence of vehicle parameter maximum (fixed т barrier case). = time of occurrence of vehicle parameter (moving barrier τ case). = mode shape. ρ = natural frequency of system. ω_n 4.2 TEST CONDITIONS $W_2 = 4000$ pounds (moving barrier) $V_{20} = 0$

 $W_2 = \infty$ (fixed barrier)

4.3 VEHICLE DATA

Vehicle	Weight (1b)	Fixed Barrier Condition (mph)
Honda	2200	40
Ford	4550	40
Plymouth	4440	40
Volvo	3220	45

TABLE 1. EQUIVALENT CAR-TO-MOVI	NG TEST DEVICE CLOSING SPEEDS	FOR SELECTED CRASH PARAMETERS	SS
	Applicable Equations	Equivalent Closing Speeds $(\overline{V}_{10} - \overline{V}_{20})$ (mph)	
Crash Parameter Held Constant (1) Initial velocity of vehicle relative to initial veloc- ity of barrier	Moving Device = Fixed Device Parameter Parameter $\overline{V}_{10} - \overline{V}_{20} = V_{10}$	Honda Ford Plymouth Volvo 40.00 40.00 40.00 45.00	0 0
(2) Maximum vehicle velocitychange	$\overline{v}_{10} - \overline{v}_{20} = \left(\frac{m_1 + m_2}{m_2}\right) v_{10}$	62 00 85 50 84 40 81 22	
(3) Maximum vehicle momentumchange	$\overline{v}_{10} - \overline{v}_{20} = \left(\frac{m_1 + m_2}{m_2}\right) v_{10}$		
(4) Maximum compartment acceleration (decelera- tion)	$\overline{\mathbf{v}}_{10} - \overline{\mathbf{v}}_{20} = \left(\frac{\mathbf{m}_1 + \mathbf{m}_2}{\mathbf{m}_2}\right)^{1/2} \mathbf{v}_{10}$		
(5) Maximum spring crush	$\overline{\mathbf{v}}_{10} - \overline{\mathbf{v}}_{20} = \left(\frac{\mathbf{m}_1 + \mathbf{m}_2}{\mathbf{m}_2}\right)^{1/2} \mathbf{v}_{10}$	49.80 58.48 58.10 60.46	46
<pre>(6) Maximum energy absorbed by vehicle</pre>	$\overline{\mathbf{v}}_{10} - \overline{\mathbf{v}}_{20} = \left(\frac{\mathbf{m}_1 + \mathbf{m}_2}{\mathbf{m}_2}\right)^{1/2} \mathbf{v}_{10}$		
Note: m ₁ = mass of car; m ₂ = mas	s of test device.		1

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	<u>ae1*</u> .744	
	Plymouth .683	
AMETEI	Ford . 684	
RASH PAF	Ratio 803 . 803	
DR SELECTED C	$\frac{\text{Juations}}{\frac{1}{2}} = \frac{\pi}{2} \left(\frac{m_{1}}{K}\right)^{1/2}$	
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IME OF OCC	$\pi = \frac{\pi}{R} \frac{\text{Movir}}{1/2}$	
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APPENDIX B

CALCOMP PLOTS

TEST 3

1975 FORD TORINO-TO-FIXED TEST DEVICE





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N LEFT FRONT OCCUPANT CHEST SEVERITY INDEX
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APPENDIX C

CALCOMP PLOTS

TEST 4

1975 FORD TORINO-TO-MOVING TEST DEVICE



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	5+16+78	315/100 4006 8316-4 TSTDEV SP6 STRING POTENTIOMETER 6 DYNAMIC DISPLACEMENT LOAD CELL C9
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DSPLMT-INCHES		315/100 4006 8316-4 TSTDEV SP6 DYNAMIC DISPLACEMENT LOAD CELL C9
DSPLMT_INCHES		315/100 4006 8316-4 TSTDEV SP6









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APPENDIX D

CALCULATION OF RESTRAINT SURVIVAL DISTANCE (RSD)

Prepared by:

Jack Beharrell Analysis Engineer Special Projects Department May 8, 1978

APPENDIX D

CALCULATION OF RESTRAINT SURVIVAL DISTANCE (RSD)

1.0 METHODOLOGY FOR CALCULATION OF RSD

1.1 INTRODUCTION

A hypothetical air bag restraint system force-deflection characteristic is used in conjunction with barrier crash test results to calculate a relative crashworthiness parameter, the Restraint Survival Distance (RSD).

The RSD involves the occupant stroking distance (which includes the available vehicle interior space plus some portion of the vehicle front structure crush which provides occupant ridedown). The degree of vehicle structural ridedown is determined by the combination of the vehicle crash pulse characteristic and the restraint system force-deflection properties.

1.2 DETERMINATION OF RSD

The Restraint Survival Distance (RSD) is determined from the following relation:

 $RSD = AID - (D_p - D_c)(t = t^*)$

where: AID is the available interior occupant stroking distance based on vehicle interior dimensions

> t* is the time at which the occupant velocity equals compartment velocity

> Dp is the absolute displacement of the occupant from initial crash impact until t*

 D_C is the absolute displacement of the vehicle compartment from initial impact to t*. This displacement is determined from longitudinal vehicle accelerometer data at positions (1) and (2) for the driver and passenger, respectively (Figure D-1).







The absolute displacement of the occupant (D_p) is determined assuming the following restraint system deceleration pulse (hypothetical air bag system)



Integrating this pulse from 0 to t^* gives the occupant velocity history

$$\dot{D}_{p} = V_{i} - 43.47 + 2898t^{*} - 48300t^{*2}$$
 (.03 \leq t* \leq .05) (ft/sec)
 $\dot{D}_{p} = V_{i} + 77.28 - 1932t^{*}$ (t \geq .05) (ft/sec)

Integrating once more gives the occupant displacement history.

$$D_{p} = .4347 + (V_{i} - 43.47)t^{*} + 1449t^{*2} -$$

 $16100t^{*3}$ (.03 \leq t* \leq .05) (ft)

 $D_p = -1.5778 + (V_1 + 77.78)t^* - 966t^* (t \ge 0.05 \text{ sec}) (ft)$

 V_i is the velocity at impact.

The time t* is most easily obtained by plotting the compartment velocity (obtained from test accelerometer data) and superimposing this curve on that obtained from \dot{D}_p above. The time at which the curves cross gives t*. The corresponding compartment displacement is determined from the test accelerometer data. The occupant displacement at time t* is determined from the D_p relation above.

The Available Interior Distance (AID) is determined for both pre-test and post-test compartment geometries under the following assumptions:

- 1. Knee restraint is located 6 inches forward of occupant's knee (horizontal measurement) if there is sufficient room in the car. The occupant's knee point is located by drawing a line tangent to the knee surface and paral-lel to the knee-joint to ankle-joint line. (The Cal-span knee bar was a crushable honeycomb knee padding. It is part of the assumed passive air bag restraint system.) For the purposes of the AID calculation, the knee restraint is assumed to be 10 inches thick and capable of crushing 8 inches (both measurements are taken horizontally). The knee restraint remains stationary during the collision.
- 2. The knee will penetrate 8 inches into the restraint, or will translate to a point located 2 inches from the deformed firewall, whichever point is reached by the knee first. This translation is performed under the restriction that the bottom of the foot remains in contact with the sloping part of the firewall (or as close to this as possible). Pivoting therefore takes place about the occupant's ankle bone pivot point.
- 3. Having located the occupant's knees by the preceding sequence of steps, the occupant is rotated about the hip pivot point until either:

a. The head hits the header or windshield.

b. The chest hits the dash (steering column is ignored).

4. The AID is then the horizontal displacement of the chest C.G. from the initial seated position to the position when either 3a or 3b above occurs. The chest C.G. is located 14 inches above the hip pivot point and 4 inches forward of the back of the torso.

2.0 DSI-CALSPAN RSD COMPARISON

An evaluation was made of the similarities and differences between the Dynamic Science and Calspan (Reference 1) results of fixed-barrier frontal crash tests on presumably identical 1975 Honda CVCC's.

Basic to the calculation of the RSD are the occupant and passenger compartment velocity and displacement time histories. These are derived from the respective acceleration profiles.

Figures D-2 and D-3 show the left and right compartment acceleration, velocity, and displacement histories for the DSI and for the Calspan tests. Superimposed on the velocity and displacement curves are the occupant velocity and displacement curves for the DSI test conditions (initial velocity 40.83 mph). [The Calspan occupant response curves would differ very little from these, since both are calculated on the basis of the standardized passive restraint deceleration pulse. The Calspan initial velocity was 40.25 mph.]

It is apparent from the acceleration curves (Figures D-2 and D-3) that there is a lag in the DSI acceleration-time history. This is largely due to the difference in test configuration. The DSI fixed barrier includes a 6-inch-thick layer of aluminum honeycomb on the front face. In the DSI tests, initial impact is defined as the instant of vehicle-honeycomb contact, since the test instrumentation detects this contact.

The occupant velocity and displacement curves shown in Figures D-2 and D-3 were calculated on the basis of this initial time instant. However, the occupant velocity and displacement equations are obtained by integrating the restraint deceleration pulse, assuming the initial restraint deployment-triggering signal and bag deployment requires 30 milliseconds. This signal would occur



Figure D-2.

1975 Honda CVCC - Fixed Barrier Test Left Compartment.



Figure D-3.

1975 Honda CVCC - Fixed Barrier Test. Right Compartment.

in the DSI test some time later and thus air bag deployment would be correspondingly delayed.

For purposes of comparison, the RSD's were recalculated assuming a 7-millisecond delay in the DSI restraint deployment signal. This corresponds to a constant velocity traversal of about 5 inches of honeycomb, at 40 mph. This delay produced, changes in t*, the time at which occupant velocity equals compartment velocity, and a corresponding change in the quantity $(D_p - D_c)$ which appears in the RSD equation. The AID's are not affected, being dependent only upon compartment geometry. Table D-1 summarizes these results, along with the corresponding Calspan values.

TABLE D-1. COMPARISON (1975 HONDA (OF RSD's D CVCC-TO-FI	SI VERSUS XED BARRII	CALSPAN ER	_	
	Dr	Driver		Passenger	
	Pre	Post	Pre	Post	
DSI (D _p curves not shifted)	6.2	15.5	6.2	9.6	
DSI (D _p curves shifted 7 msec)	1.5	10.8	3.0	6.4	
Calspan	1.0	3.9	1.8	4.5	
All values are in inches.					

It is apparent that taking the triggering signal delay into account produces better correlation between the Calspan and DSI tests. It should be pointed out that the use of a 7-millisecond delay is somewhat arbitrary since the actual restraint deployment signal is generated on the basis of compartment deceleration. Comparison of the acceleration curves of Figures D-2 and D-3 suggests that a 7-millisecond delay is reasonable. However, the comparative results are a good indication of the care that must be taken to ensure equivalent test evaluation procedures.

REFERENCES

1. CLASSIFICATION OF AUTOMOBILE FRONTAL STIFFNESS/CRASHWORTHI-NESS BY IMPACT TESTING, DOT-HS-801-966, Calspan Corporation, August 1976.

a TALLEY INDUSTRIES Company

March 20, 1979

Mr. Carl Ragland (NRD-12) Contract Technical Manager National Highway Traffic Safety Administration Transpoint Building 2100 Second Street, S.W. Washington, D.C. 20590

Subject: Transmittal of Reproducible Test Report No. 2

Reference: Contract DOT-HS-7-01758, "Develop Test Methodology for Evaluating Crash Compatibilities and Aggressiveness"

Dear Carl:

As required by the referenced contract, we are enclosing the reproducible and eight copies of Test Report No. 2, covering the two Ford Torino tests:

Test 8316-3 Ford into Fixed Test Device @ 40.5 mph

Test 8316-4 Ford into Moving Test Device @ 59.1 mph

If you have any questions, please do not hesitate to contact me.

Sincerely,

Sol Davis Manager Special Projects Department

SD:bmv

Enclosures

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