

# A Numerical Model to Simulate Sediment Transport in the Vicinity of Coastal Structures

by

Marc Perlin and Robert G. Dean



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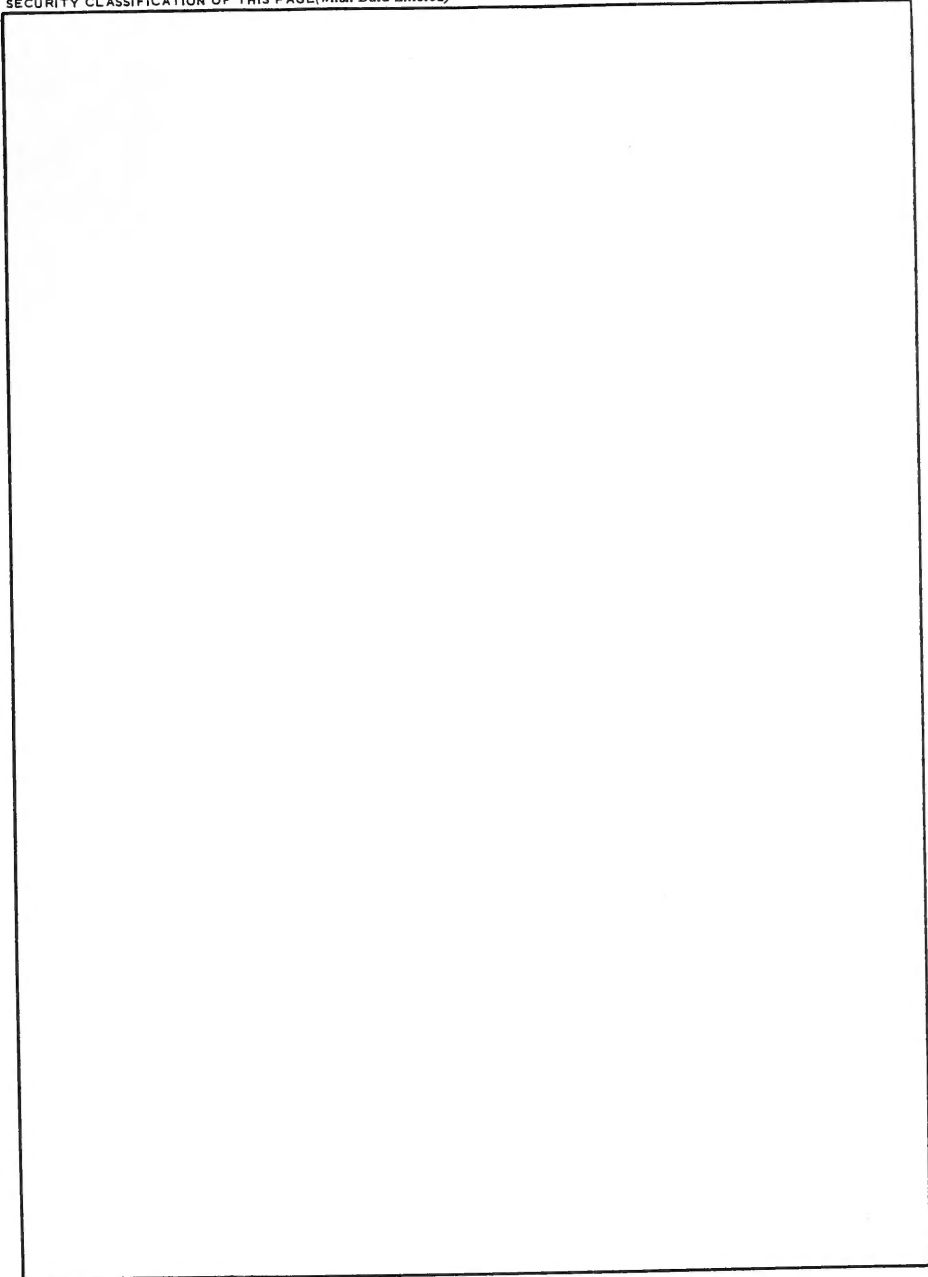
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## PREFACE

The purpose of this report is to provide coastal engineers and researchers with a numerical model which predicts sediment transport and the resulting bathymetry in the vicinity of coastal structures. The work was carried out under the U.S. Army Coastal Engineering Research Center's (CERC) Numerical Modeling of Shoreline Response to Coastal Structures work unit, Shore Protection and Restoration Program, Coastal Engineering Area of Civil Works Research and Development.

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Comments on this publication are invited.

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*Billy D Best, LTC, CE*  
For TED E. BISHOP  
Colonel, Corps of Engineers  
Commander and Director

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CONVERSION FACTORS, U.S. CUSTOMARY TO METRIC (SI) UNITS OF MEASUREMENT

U.S. customary units of measurement used in this report can be converted to metric (SI) units as follows:

Multiply	by	To obtain
inches	25.4	millimeters
	2.54	centimeters
square inches	6.452	square centimeters
cubic inches	16.39	cubic centimeters
feet	30.48	centimeters
	0.3048	meters
square feet	0.0929	square meters
cubic feet	0.0283	cubic meters
yards	0.9144	meters
square yards	0.836	square meters
cubic yards	0.7646	cubic meters
miles	1.6093	kilometers
square miles	259.0	hectares
knots	1.852	kilometers per hour
acres	0.4047	hectares
foot-pounds	1.3558	newton meters
millibars	$1.0197 \times 10^{-3}$	kilograms per square centimeter
ounces	28.35	grams
pounds	453.6	grams
	0.4536	kilograms
ton, long	1.0160	metric tons
ton, short	0.9072	metric tons
degrees (angle)	0.01745	radians
Fahrenheit degrees	5/9	Celsius degrees or Kelvins <sup>1</sup>

<sup>1</sup>To obtain Celsius (C) temperature readings from Fahrenheit (F) readings, use formula:  $C = (5/9) (F - 32)$ .

To obtain Kelvin (K) readings, use formula:  $K = (5/9) (F - 32) + 273.15$ .



# A NUMERICAL MODEL TO SIMULATE SEDIMENT TRANSPORT IN THE VICINITY OF COASTAL STRUCTURES

by  
Marc Perlin and Robert G. Dean

## I. INTRODUCTION

### 1. General.

The need for reliable predictions of shoreline response to man-made or natural modifications is increasing due to environmental concerns and the rising cost of remedial measures. The capability of numerical modeling in addressing problems of shoreline response has advanced with improvements in wave climatology, programs to better understand sediment transport relationships, and improvements in numerical modeling. In-situ and remote sensing technology for the measurement of directional wave characteristics has been developed and applied, primarily within the last two decades. In addition to providing the necessary climatology, the resulting measurements have provided the basis for evaluation and refinement of directional wave prediction procedures. Studies such as the Channel Islands Harbor Longshore Sand Transport Study (Bruno, et al., 1981) and the Nearshore Sediment Transport Study (NSTS) (Gable, 1979) have yielded a better understanding of surf zone dynamics and the resulting sediment transport. The increased capacities of large computers and reduced computing costs combined with improved numerical modeling algorithms have resulted in an extremely promising potential for the numerical modeling of shoreline problems.

Although it is doubtful that numerical modeling will ever replace completely the use of movable-bed physical models, the former type offers many advantages. The modeling of shoreline response is somewhat analogous to the problem of simulating storm surges in the coastal zone in which the scale effects and measurement difficulties essentially preclude physical modeling. For shorelines, the scale effects inherent in modeling sediment are well recognized and the costs of representing a substantial length of shoreline may be prohibitive. The laboratory representation of a realistic wave climate is at the forefront of technology.

The investigation of shoreline response can best proceed by several approaches, with each approach selected for the particular strengths which it offers. Field programs are costly, usually because of the considerable equipment and the extensive time required, but these programs are essential for quantifying the values of constants or parameters, the forms of which may be available from laboratory measurements or theoretical considerations. Laboratory studies occupy a special niche by allowing the wave conditions and independent variables to be controlled readily, experiments to be repeated, and selected measurements to be conducted. Although, as noted before, scale effects are present in laboratory measurements of sediment transport, the physics governing the process should be the same. However, the relative magnitudes of suspended versus bedload transport in the laboratory and field may differ. Laboratory studies can also provide an excellent base for evaluating certain aspects of a numerical model, including wave refraction and diffraction and the resulting shoreline patterns due to, for example, the placement of a littoral barrier. Numerical modeling offers the capability to

incorporate all the hydrodynamic wave-surf zone and sediment transport knowledge that is available from laboratory and field studies. Numerical modeling has the potential of providing accurate predictions of shoreline response to various structural and nourishment alternatives. Additionally, the possibility exists of employing numerical models and available field measurements to learn more about sediment transport mechanisms. In this latter mode, various candidate mechanisms or coefficients would be evaluated by determining the best match between measured and predicted shorelines and the bathymetry. Generally, this mode would require high-quality measurements of the forcing function (waves and nonwave-related currents) and the associated response (sediments) as well as the knowledge of appropriate conditions at the boundaries of the model.

The present report documents the development and application of an n-line numerical model to investigate bathymetric response to time-varying wave conditions and shoreline modification. The model includes both longshore and onshore-offshore sediment transport. Based on laboratory results, a new distribution of longshore sediment transport across the surf zone is used. The wave climate is specified on the model boundaries which do not need to extend to deep water. Efficient algorithms are employed for representing wave refraction and diffraction. The equation of sediment continuity and transport are solved by a completely implicit algorithm which allows a large time-step. Specified sediment transport values or specified contour positions can be accommodated at the model boundaries. The model is suitable for investigating the shoreline response to a variety of modifications such as one or more groins, terminal structures, structures with variable permeability, and beach nourishment with or without terminal structures.

## 2. Study Objectives.

The objectives of the present study include (a) the documentation of state-of-the-art models, (b) the development and documentation of an improved model which includes the capability to represent n-contour lines and (c) the application of the model to several relevant coastal engineering problems.

## II. BACKGROUND

This discussion describes significant contributions which either address numerical modeling of shorelines directly or provide improved capability for modeling.

### 1. Wave Refraction (Noda, 1972).

Noda developed an algorithm for solving the following steady state equation for wave refraction

$$\vec{\nabla} \times \vec{k} = 0 \quad (1)$$

in which  $\vec{\nabla}$ , the horizontal vector differential operator, and  $\vec{k}$ , the wave number, are defined in terms of their components as

$$\vec{\nabla} = \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} \quad (2)$$

$$\vec{k} = \vec{i} k_x + \vec{j} k_y \quad (3)$$

where  $\vec{i}$  and  $\vec{j}$  are the unit vectors in the x and y directions respectively. Equation (1) can be expressed as

$$\frac{\partial(k \sin \theta)}{\partial x} = \frac{\partial(k \cos \theta)}{\partial y} \quad (4)$$

in which  $\theta$  is the direction of the vector wave number relative to the x-axis and  $k$  denotes  $|\vec{k}|$ . Noda expanded Equation (4) to the following form

$$k \cos \theta \frac{\partial \theta}{\partial x} + \sin \theta \frac{\partial k}{\partial x} = -k \sin \theta \frac{\partial \theta}{\partial y} + \cos \theta \frac{\partial k}{\partial y} \quad (5)$$

Since  $\frac{\partial k}{\partial x}$  and  $\frac{\partial k}{\partial y}$  are known from the angular frequency  $\sigma$ , the water depth  $h$ , and the dispersion equation

$$\sigma^2 = g k \tanh kh \quad (6)$$

Equation (5) can be solved numerically, although there are problems of directional stability. The primary advantage of Equation (5) is that it allows the wave direction  $\theta$  to be determined on a specified grid, compared to unspecified locations that would be obtained by, for example, wave ray tracing.

### 2. Crenulate Bays (LeBlond, 1972).

LeBlond attempted to model the evaluation of an initially straight shoreline between two headlands into a crenulate bay. The model constitutes a one-line (shoreline) representation. The transport equation employed related the total sediment transport to total water transport in the surf zone as predicted by the formulation provided by Longuet-Higgins (1970). The initial shoreline patterns resemble crenulate bays in nature; however, the predictions were found to be unstable for reasonably long periods of computational time and did not approach a realistic platform.

### 3. Crenulate Bays (Rea and Komar, 1975).

Rea and Komar employed a rather ingenious system of orthogonal grid cells to provide a cell which locally is displaced perpendicular to the general shoreline orientation. A one-line representation was employed. A simple and approximate representation of wave diffraction was employed. Although the model yielded reasonable results for the examples presented, the unique coordinate system would not be suitable for a general model as the coordinate system must be "tailored" to some degree to conform to the expected shoreline configurations.

#### 4. General One-line Shoreline Model (Price, Tomlinson, and Willis, 1972).

Price, Tomlinson, and Willis' formulation consists of the sediment continuity equation and the total sediment transport equation

$$Q_s = \frac{0.70 E_b (nC)_b \sin \alpha_b \cos \alpha_b}{\gamma_w (1 - p) (S_s - 1)} \quad (7)$$

in which  $E$  represents the wave energy density,  $(nC)$  the group velocity,  $\alpha$  the angle between the breaking wave front and the shoreline,  $\gamma_w$  the specific weight of water,  $p$  the in-place sediment porosity, and  $S_s$  the specific gravity of the sediment relative to the water in which it is immersed. The subscript "b" represents values at breaking.

Two formulations were presented by Price, Tomlinson, and Willis (1972). In the first, Equation (7) was substituted into the continuity equation and the results cast into a finite-difference form. In the second, the two equations were employed separately. The latter formulation was selected due to its simplicity and used for the results presented.

Computations were carried out for the case of beach response due to the placement of a long impermeable barrier. The total sediment transport equation by Komar (1969) was used and the planform was calculated at successive times. Refraction was apparently not accounted for in the numerical model. To verify the computations, a physical model study was carried out for the same conditions using crushed coal as the modeling material. The comparison was interpreted as good for up to 3 hours; however, for greater times, substantial differences occurred and these were interpreted as being due to wave refraction not being represented. The crushed coal was supplied to the model at the updrift end at a rate based on the Komar equation, and the results were interpreted as substantiating this relationship. However, the updrift end of the model beach receded substantially both in the numerical and physical models. In the physical model, this can only be interpreted as due to the Komar equation predictions being less than the actual transport rate, possibly due to the low specific gravity (1.35) of the crushed coal. The predicted recession of the updrift beach is puzzling, although it could be due to a problem in properly representing the updrift boundary condition.

Other one-line models for shoreline changes in the vicinity of coastal structures were developed by LeMehaute and Soldate (1977) and Perlin (1978). Perlin also developed a two-line model formulation, with one-line representing the shoreline and the second the offshore. Dragos (1981) developed an n-line model for bathymetric changes due to the presence of a littoral barrier.

### III. THE NUMERICAL MODEL

#### 1. Description.

There are several methods of modeling bathymetric changes due to the presence of a littoral barrier. An attempt can be made to either model the complete hydrodynamics and the resulting sediment transport or model using a combination of analytical and empirical sediment transport equations. The second method was chosen due to past relative success.

At least two methods of employing sediment transport equations exist: a fixed longshore and cross-shore grid system where the depth is allowed to vary or a fixed longshore and depth system where the cross-shore distance is allowed to change. Although it may seem somewhat awkward, the latter system was chosen for the model. This method allows the modeler to think of bathymetric changes due to a littoral barrier in terms of the effect on the contours; i.e., the contour realignment due to the structure's presence is observed. One limitation of this approach, at least as it was applied here, is that each depth contour must be single-valued; it is not possible to represent bars.

The next step in formulating the model was choosing the specific representation of the bathymetry. The model is an n-line representation of the surf zone in which the longshore direction  $x$  is divided into equal segments each  $\Delta x$  in length. The bathymetry is represented by n-contour lines, each a specified depth, which change in offshore location according to the equation of continuity. There are two components of sediment transport at each of the contour lines, a longshore component,  $Q_x$ , and an offshore component,  $Q_y$ . Figure 1 is a definition sketch showing the beach profile representation in a series of steps and the planform profile representation and notations used.

Implementation of the sediment transport equations requires knowledge of the wave field and the equilibrium offshore profile. A discussion of the refraction and diffraction schemes follows. The equilibrium profile is introduced when it is convenient. As an introduction to the logic used in the numerical model, a flow chart is presented in Figure 2.

#### 2. Refraction.

A refraction scheme compatible with variable  $\Delta y$ 's was required because of the variable distance to fixed depth contours (as opposed to the more usual fixed grid system where a grid center has a longshore and offshore coordinate with a variable depth). One of the benefits of the n-line model is the ease with which the response of the contours to a particular wave and structure condition can be visualized. A fixed grid system and an interpolation scheme could have been used to obtain the wave field; however, this would have reduced accuracy and increased computation time. The scheme developed also saves computation time because it does not use differential products terms.

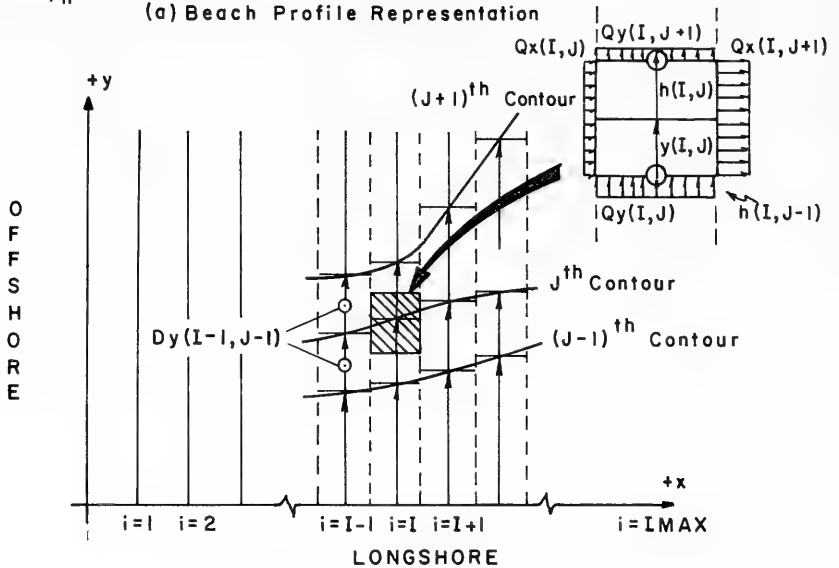
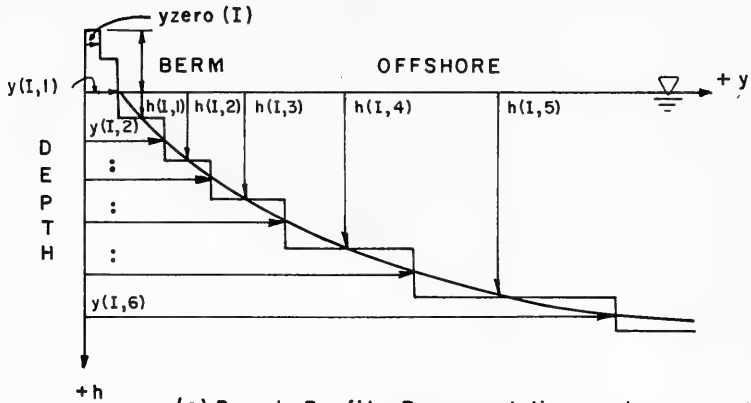


Figure 1. Definition sketch.

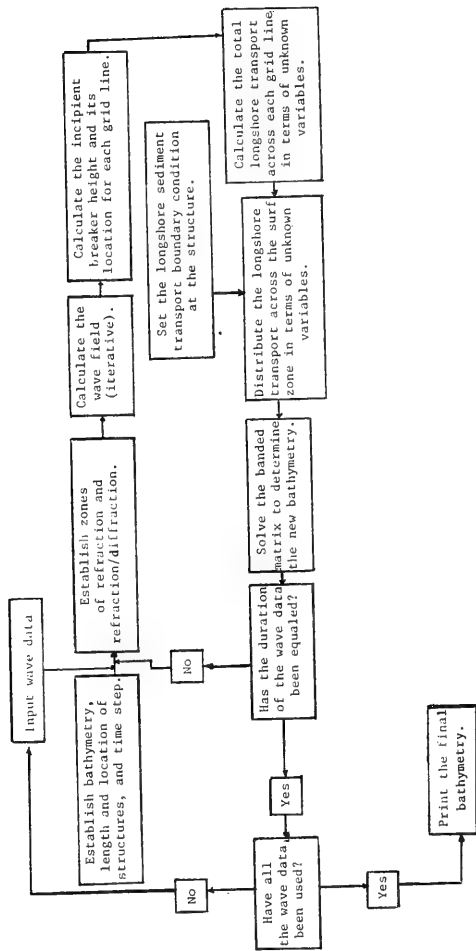


Figure 2. Flow chart.

The first of the governing equations used is the conservation of waves equation

$$\frac{d\sigma}{dt} + \vec{\nabla}_H \times \vec{k} = 0 \quad (8)$$

where  $\vec{\nabla}_H$  is the horizontal differential operator equal to  $\vec{i}(\partial/\partial x) + \vec{j}(\partial/\partial y)$  in which  $\vec{i}$  and  $\vec{j}$  are the unit vectors in the x and y directions, respectively, and x is the longshore direction, with positive to the right when facing the water, y the offshore direction, with positive seaward, and z the vertical coordinate, with positive defined as upwards. For the steady-state case, equation (8) yields

$$\frac{\partial}{\partial x} (k_y) - \frac{\partial}{\partial y} (k_x) = 0 \quad (9)$$

where  $k_x$  and  $k_y$  are the wave number projections in the respective directions. Defining  $\theta$  as the angle k makes with the y-axis positive in the counter-clockwise direction, the equation can be written in final form as

$$\frac{\partial}{\partial x} (k \cos \theta) = \frac{\partial}{\partial y} (k \sin \theta) \quad (10)$$

where  $\theta = \alpha + \pi$  (in radians). Noda (1972) and others have developed numerical solutions to expanded forms of equation (10). In the present study, equation (10) was initially central-differenced in the x-direction and forward-differenced in the y-direction with Snell's law used to specify the boundary conditions on the offshore boundary and one of the sides (i.e., the side of the wave angle approach). However, a numerical problem arose. The argument of the arcsine exceeded +1.0 for large  $\Delta y/\Delta x$ . To overcome this problem, a dissipative interface was used on the forward-difference term (after Abbott, 1979). The final finite-differenced form of equation (10) is

$$\theta_{i,j}^{n+1} = \sin^{-1} \left\{ \frac{1}{k_{i,j}} \left[ \tau(k \sin \theta)_{i-1,j+1} + (1-2\tau)(k \sin \theta)_{i,j+1} \right. \right. \\ \left. \left. + \tau(k \sin \theta)_{i+1,j+1} - \frac{\Delta y}{2\Delta x} \left( (k \cos \theta)_{i-1,j}^{\frac{1}{2}} - (k \cos \theta)_{i-1,j} \right) \right] \right\} \quad (11)$$

where  $\tau$  has been taken as 0.25. The past  $\theta_{i,j}^n$  and the present  $\theta_{i,j}^n$  wave angles are numerically averaged to give the  $\theta_{i,j}$ . Newton's method is used to compute the wave number via the linear wave theory dispersion relation. In addition, numerical smoothing is used at the conclusion of the wave field calculation. This approximates in an ad hoc manner diffractive effects (lateral transfer of wave energy along the wave) which exist in nature but have been omitted due to use of the equation for refraction (equation 8). The smoothing routine is

$$\theta_{i,j} = \frac{1}{4} \theta_{i-1,j} + \frac{1}{2} \theta_{i,j} + \frac{1}{4} \theta_{i+1,j} \quad (12)$$



The second governing equation used in the refraction scheme is conservation of energy. Neglecting dissipation of energy due to friction, percolation, and turbulence, this equation can be expressed as

$$\vec{\nabla} \cdot (E \vec{C}_G) = 0 \quad (13)$$

where  $E$  is the average energy per unit surface area and  $\vec{C}_G$  the group velocity of the wave train. Performing the operation indicated and replacing  $\vec{C}_G$  by its components ( $C_G \sin \theta$ ) and ( $C_G \cos \theta$ ) results in the following:

$$\frac{\partial}{\partial x} (E C_G \sin \theta) + \frac{\partial}{\partial y} (E C_G \cos \theta) = 0 \quad (14)$$

Assuming linear theory,

$$E = \frac{\rho g H^2}{8} \quad (15a)$$

where  $\rho$  is the mass density of water,  $g$  the gravitational constant, and  $H$  the wave height. Dividing the equation by  $\frac{\rho g}{8}$ , finite-differencing and weighting the forward-differenced term as before, and solving for the wave height, results in the following:

$$H_{i,j}^{n+1} = \left\{ \frac{1}{(C_G \cos \theta)_{i,j}} \left[ (\tau)(H^2 C_G \cos \theta)_{i-1,j+1} + (1-2\tau)(H^2 C_G \cos \theta)_{i,j+1} \right. \right. \\ \left. \left. + (\tau)(H^2 C_G \cos \theta)_{i+1,j+1} + \frac{\Delta y}{2\Delta x} [(H^2 C_G \sin \theta)_{i+1,j} - (H^2 C_G \sin \theta)_{i-1,j}] \right] \right\}^{1/2} \quad (15b)$$

This equation is also solved by iterative techniques and the  $H_{i,j}^{n+1}$  and  $H_{i,j}^n$  are averaged at the conclusion of each iteration.

$C_G$  is determined by the linear wave theory relationship

$$C_G = \frac{C}{2} \left( 1 + \frac{2kh}{\sinh 2kh} \right) \quad (16)$$

where  $h$  is the water depth,  $k$  the wave number, and  $C$  the wave celerity. Wave height boundary conditions are input along the same boundaries as the wave angles using linear theory shoaling and refraction coefficients. The  $\theta$ 's have been previously determined. In both equations (11) and (15) for a variable grid system, the points  $(i+1, j)$  and  $(i-1, j)$  need to be determined (i.e., because the  $y$  coordinates are not fixed, adjacent values with the same subscripts can be farther or closer to shore, therefore interpolation must be used). The actual values are found by searching the  $(i+1)$  and  $(i-1)$  cross-shore lines, finding the adjacent values in the positive and negative  $y$ -direction, and interpolating to determine the value.

### 3. Diffraction.

The diffraction solution (in the lee of the structure) used in the model is based on the method of Penny and Price (1952). Assumptions used in this method include a semi-infinite breakwater, which is infinitesimally thin, linear wave theory and constant depth. A definition sketch for wave diffraction is shown in Figure 3. The quantity THETA0 represents the angle of wave incidence relative to the jetty axis, ANGLE represents the angle from the jetty at the point where the diffraction coefficient is to be computed, and RAD is the radial distance. The radial distance is then cast into a dimensionless parameter, RHOND (=  $2\pi$  RAD/L), where L is the wavelength. This is equivalent to multiplying the radial distance by the wave number k.

The diffraction coefficient AMP is expressed as the modulus of the diffracted wave

$$AMP = (\text{Sum 1})^2 + (\text{Sum 2})^2 \quad (17)$$

where

$$\begin{aligned} \text{Sum 1} = & [\cos (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0})))] \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right) + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0})))] \cdot \left(-\frac{1}{2} (S - C_F)\right) + \\ & [\cos (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0})))] \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right) + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0})))] \cdot \left(\frac{1}{2} - (S - C_F)\right) \quad (18) \end{aligned}$$

$$\begin{aligned} \text{Sum 2} = & [\cos (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0})))] \cdot \left(-\frac{1}{2} (S - C_F)\right) + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}-\text{THETA0})))] \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right) + \\ & [\cos (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0})))] \cdot \left(-\frac{1}{2} (S - C_F)\right) + \\ & [\sin (\text{RHOND} (\cos (\text{ANGLE}+\text{THETA0})))] \cdot \left(\frac{1}{2} (1.0 + C_F + S)\right) \quad (19) \end{aligned}$$

In Equations (18) and (19),  $C_F$  and  $S$  represent Fresnel integrals and are computed in the model by means of an approximation after Abramowitz and Stegun (1965).

Having obtained AMP, the wave height at the location in question is simply the product of the specified partially refracted incident wave height and AMP. The angle of the wave crest is computed assuming a circular wave front along any radial; this angle is then refracted using Snell's law.

Throughout the refraction and diffraction schemes, the local wave heights are limited by the value,  $0.78 \times \text{depth}$ .

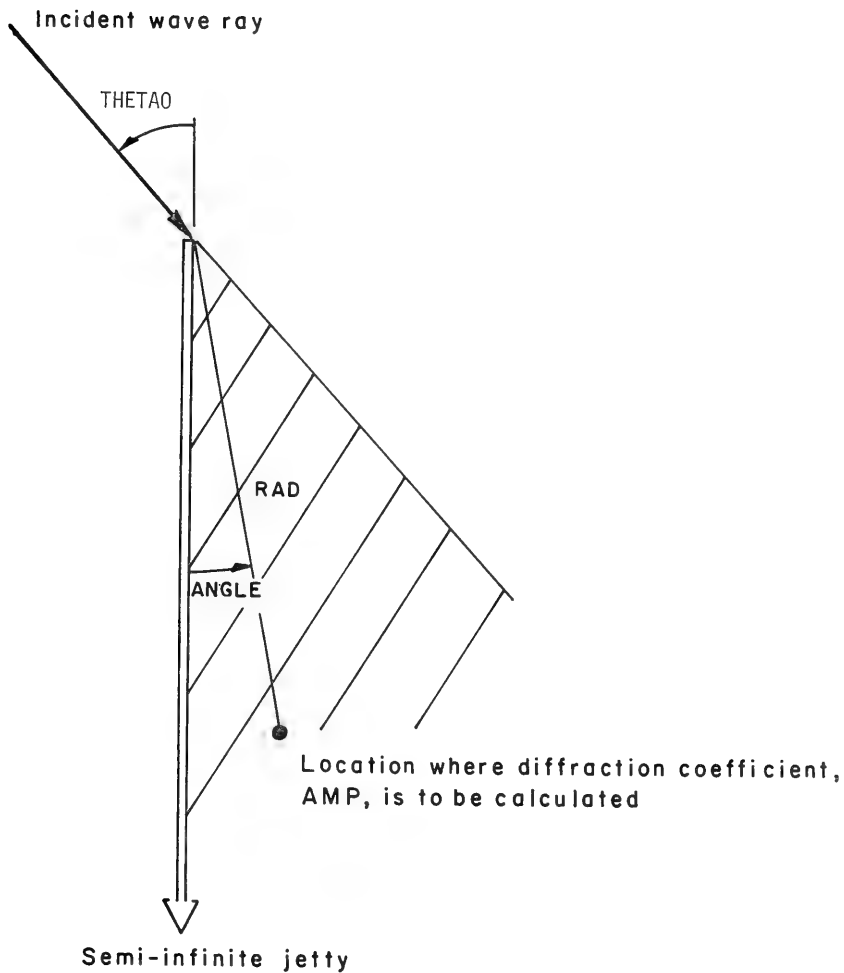


Figure 3. Definition sketch for wave diffraction.

#### 4. Sand Transport Model.

a. Governing Equations. Three basic equations are used to simulate the sediment transport and bathymetry changes according to the wave field. The equation of continuity

$$\frac{\partial y}{\partial t} + \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} = 0 \quad (20)$$

requires as input, knowledge of the longshore and cross-shore components of sediment transport. The total transport alongshore has been measured by several investigators and many equations exist; however, the distribution of the transport across the surf zone is not well known. Fulford (1982) based on laboratory data from Savage (1959), developed a distribution of longshore sediment transport across the surf zone for the case of straight and parallel contours. Fulford's use of Savages experiment was based on two assumptions: 1) the structure must be a total littoral barrier and 2) onshore-offshore sediment transport could be neglected. Test 5-57 was chosen because the two criteria were nearly met. Savage reported that the groin acted as a total littoral barrier for the first 35 hours of the test (i.e., no bypassing occurred prior to 35 hours). This does not mean that no onshore-offshore transport occurred because as the profile steepens on the updrift side, onshore-offshore transport does occur. However, it was assumed to be negligible. In addition, the initial profile had been molded to an equilibrium profile via 150 hours of waves. Thus, the two criteria required to develop an inferred longshore distribution of sediment transport were nearly satisfied. This distribution is shown as a dashline in Figure 4. The smaller "maximum" is believed to be an extraneous effect of a groin downdrift from the location in the experiment where the data were taken. Therefore, this feature was replaced by a monotonically decreasing, smooth curve as shown by the "altered" curve. To analytically represent this distribution, a function of the following form was chosen

$$q_x (y) = (B) (y)^{n-1} e^{-(y)^n} \quad (21)$$

This type of equation is convenient because it is easily integrable, and by properly choosing the constant, B, the integral of the equation from zero to infinity can be required to equal a particular value. This too is highly desirable because, as was done in the model, the integral is set equal to one and then multiplying by the value of the well-known longshore transport equation, the value of the transport at any location across the surf zone can be determined. Further investigation suggested a value of  $n = 3$  to produce a curve similar to Fulford's curve. A more general form of the equation which allows more flexibility and curve fitting is

$$q_x (y) = B(y + a)^2 e^{\left\{ -\left[ \frac{y + a}{cy + b} \right] \right\}^3} \quad (22)$$

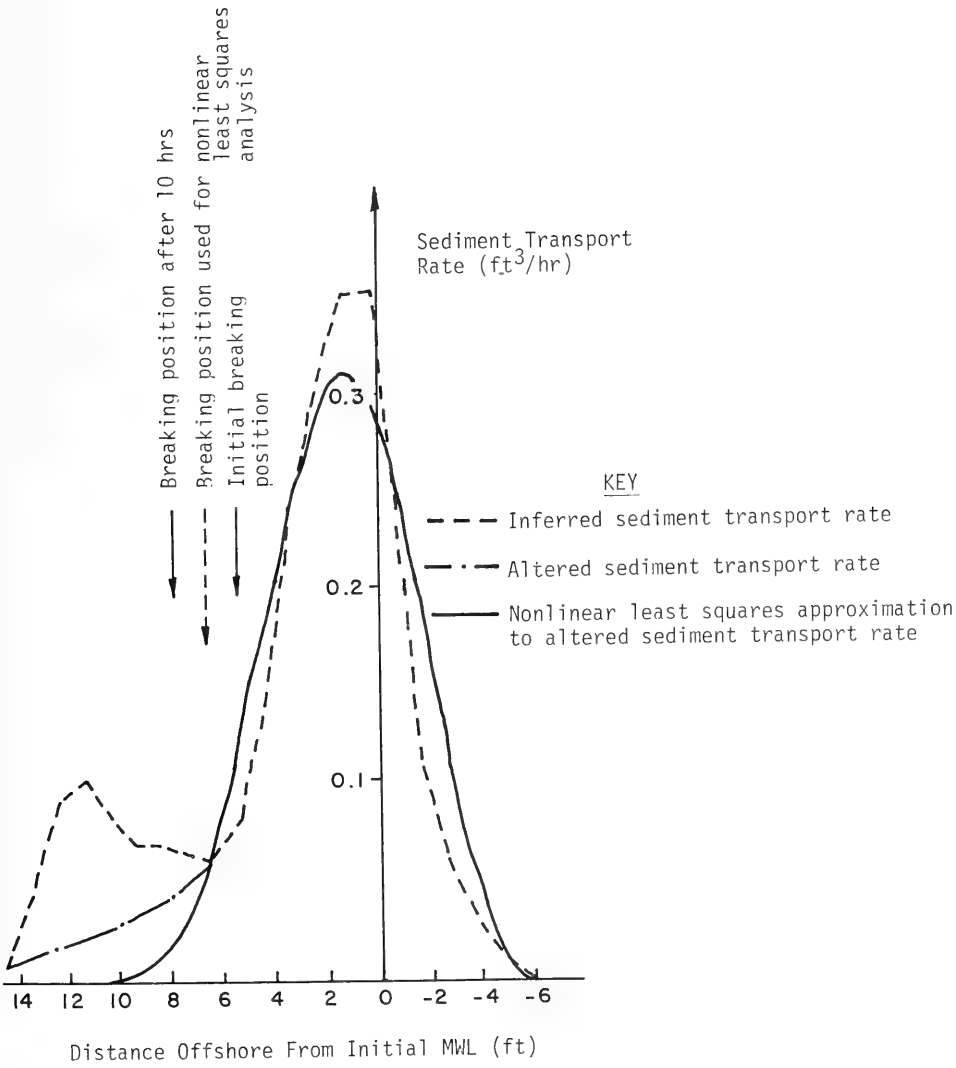


Figure 4. Distribution of sediment transport across the surf zone.

where  $y_b$  = distance to the point of breaking

$a$  = constant to allow sediment transport above mean water line (MWL) (swash transport or transport in region of wave setup) to be represented

$c$  = a constant establishing the width of the curve (to be determined)

$$B = \frac{3}{c^3 y_b^3} \quad (\text{causes } \int_0^{\infty} q_x(y) dy = 1.0)$$

Based on Fulford's (1982) results and considering  $a$  to be proportional to the breaking height divided by the beach slope, the constant of proportionality was determined to be unity; i.e.,  $a = h_b / (\partial h / \partial y)$ . Using equation (22) and a digitized version of the curve shown in Figure 4, a nonlinear least squares regression was carried out to determine the value of  $c$ . A Taylor's series expansion of the form

$$f^{k+1}(c, y) = f^k(c, y) + \frac{\partial f}{\partial c} \Delta c \quad (23)$$

where  $k$  and  $k+1$  represent the number of the iteration carried out. Least squares regression minimizes the square of the difference between observed and predicted values with respect to a change in the parameter being computed, or

$$\frac{\partial}{\partial (\Delta c)} \left\{ \sum_{n=1}^N \left[ f_{OBS} - \left( f^k(c, y) + \frac{\partial f}{\partial c} \Delta c \right) \right]^2 \right\} = 0 \quad (24)$$

where  $f_{OBS}$  represents the observed values, which in this case is  $q_x(y)_{OBS}$ . Carrying out the differentiation indicated and manipulating terms,  $\Delta c$  can be solved in terms of known quantities.

An iterative procedure was then used by updating the values of  $f^k(c, y)$ ,  $\partial f / \partial c$ , and  $c$  until an acceptably small change in  $c$  results. For the data herein, the value of  $c$  was determined to be 1.25. The final form of sediment transport of a  $y$  location in the surf zone results for a shoreline with straight and parallel contours, as

$$q_x(y) = \frac{3}{(1.25)^3 (y_b)^3} (y + a)^2 e^{-[(y + a)/(1.25 y_b)]^3} \quad (25)$$

This equation, which is also presented in Figure 4, predicts the relative transport at point y. To obtain the fraction of transport between two y coordinates, the integral of equation (25), from  $y_1$  to  $y_2$ , must be used.

$$Q_{xND} = Q_x \int_{y_1}^{y_2} q_x(y) dy = e^{-[(y_1 + a)/(1.25 y_b)]^3} - e^{-[(y_2 + a)/(1.25 y_b)]^3} \quad (26)$$

$Q_x[ND]$  is dimensionless; therefore, to compute a value in, say, cubic feet per second, it must be multiplied by the total transport along a perpendicular to the shoreline obtained from the total longshore transport equation used in the model

$$Q = C' H_b^{5/2} \sin(2\alpha_b) \quad (27)$$

See Appendix A for a discussion of the constant  $C'$ . It is noted that the transformation of  $q_x(y)$  to  $q_x(h)$  can be effected by multiplying by the one-dimensional Jacobian ( $\Delta y/\Delta h$ ). This latter form ( $q_x(h)$ ) is more useful here because the present model simulates the changes in contour position ( $\Delta y$ ) rather than changes by depth ( $\Delta h$ ).

In the numerical model,  $Q_x(I,J)$  (see Fig. 1) is determined using equation (26) except for the shoreline contour,  $J=1$ , and the farthest offshore contour simulated,  $J = JMAX$ . The shoreline contour longshore transport,  $Q_x(I,1)$ , in order to include swash transport, uses equation (16); however, the first term is set equal to 1.0. The seawardmost contour transport,  $Q_x(I,JMAX)$ , in order to include any longshore transport not yet accounted for, neglects the second term of equation (26) (i.e., it accounts for transport from  $y(I,JMAX)$  to infinity). The dimensionless numbers are then multiplied by  $Q$  determined from equation (27). This method is based on parallel contours which may not exist. In order to compensate for the nonparallel nature of the contours (note that refraction does account for it as far as the wave field is concerned), the term  $\sin(2\alpha_b)$  of equation (27) is replaced by  $\sin(2\alpha_l)$  shoreward of the breakpoint, where  $\alpha_l$  represents the angle between the "local" wave angle and the "local" contour. It can be argued that for a spilling breaker, the remaining surf zone at any point "sees" a total transport similar to equation (27), where  $\alpha_b$  and  $H_b$  are the local values. The problem is that the constant of proportionality was determined for the entire surf zone and for nearly straight and parallel contours. This not being the case, the equation was altered on intuitive grounds to reflect the fact that the contours are no longer straight and parallel.

The second input required by the continuity equation to predict the bathymetric changes is the cross-shore sediment transport. The governing equation for onshore-offshore transport (after Bakker, 1968) is

$$Q_{y_{i,j}} = \Delta x C_{OFF_{i,j}} \left[ y_{i,j-1} - y_{i,j} + W_{EQ_{i,j}} \right] \quad (28)$$

where  $C_{OFF}$  is an activity factor (inside the surf zone =  $10^{-5}$  feet per second for the prototype simulation herein,  $10^{-4}$  feet per second for the physical model simulation) (see App. A. for a discussion) and  $W_{EQ}(i,j)$  is the positive equilibrium profile distance between  $y(i,j)$  and  $y(i,j-1)$ , determined from the equilibrium profile used in the numerical model  $h = Ay^{2/3}$  (Dean, 1977). See Appendix A for discussion of the value of A. The physical interpretation of equation (28) is that as this profile steepens (flattens), sediment is transported offshore (onshore).

b. Methods of Solution. Three separate finite-difference techniques were used to solve the equations:

- (1) Explicit longshore-continuity and explicit cross-shore continuity;
- (2) Implicit longshore-continuity and explicit cross-shore continuity for half a time-step then vice versa; and
- (3) Implicit longshore-cross-shore continuity.

An explicit formulation was first developed which used the refraction scheme, the distribution of longshore sediment transport across the surf zone, and the onshore-offshore sediment transport equation. Problems in addition to the usual ones which are encountered with explicit methods (e.g., computation time and cost) were immediately realized. In the explicit method, both transport computations are based on the former values of the contour locations and are completely uncoupled. Stability of an explicit scheme requires a small time-step. In addition, the noncoupled nature of the equations, in some cases, resulted in crossing of the contours due to the transport computed.

It is logical to assume that an implicit formulation of the longshore transport equation used as input to the continuity equation along with the explicit onshore-offshore transport component would help the numerical stability (on the other half time-step, the longshore component would be computed explicitly and the onshore-offshore transport equation would be solved implicitly with the continuity equation). Although this scheme would be superior to the explicit procedure, it still would be susceptible to crossing contours. It should be noted that the magnitude of the coefficient used in the onshore-offshore equation is very important to the extent that the simulation models natural phenomena. If the coefficient is very small or vanishes, sediment will not move offshore and contours will cross because of the variation in the distribution of longshore sediment transport across the surf zone. If the coefficient is too large, the onshore-offshore transport, may become large enough that on a particular time step, an offshore contour



would move too far shoreward, thereby crossing an inshore contour or vice versa. Once the contours cross, not only does the bathymetry become unrealistic, but mathematically, the equation which computes the longshore distribution across the surf zone changes signs at some locations and the entire model becomes physically unrealistic.

To circumvent these problems, an implicit scheme that simultaneously solves the three governing equations, was developed. Utilizing equation (26), and the one-dimensional Jacobian ( $\Delta y/\Delta h$ ) to convert to  $Q_x(h)$ , the total longshore transport equation (27), the following equation is obtained,

$$Q_{X_{i,j}} = \left\{ \exp \left( - \left( \frac{(h_{i,j-1})^{3/2} + H_{b_i} A^{3/2}}{1.25 h_{b_i}} \right)^3 \right) - \exp \left( - \left( \frac{(h_{i,j})^{3/2} + H_{b_i} A^{3/2}}{1.25 h_{b_i}} \right)^3 \right) \right\} \times \left( C' H_{b_i,j}^{5/2} \right) \times \sin (2\theta - 2\alpha_c) \quad (29)$$

$Q_X(i,j)$  represents the sediment transport between depths  $h(i,j)$  and  $h(i,j-1)$  (see Fig. 1). The term in brackets represents the normalized distribution of longshore transport between  $h(i,j)$  and  $h(i,j-1)$ ;  $\theta$  is the averaged wave angle at the location of  $Q_X(i,j)$  and  $\alpha_c$  is the local contour orientation angle. Defining everything except  $\sin (2\theta - 2\alpha_c)$  as  $v(i,j)$  and using a superscript to denote a time step, this equation can be written

$$Q_{X_{i,j}}^{n+1} = v_{i,j} \sin (2\theta - 2\alpha_c^{n+1}) \quad (30)$$

The assumption has been made that the wave field ( $H$  and  $\theta$ ) do not vary during the bathymetric changes over the time-step. Using the following trigonometric identities,

$$\sin (2a - 2b) = \sin 2a \cos 2b - \cos 2a \sin 2b \quad (31a)$$

$$\cos 2a = 2 \cos^2 a - 1 \quad (31b)$$

$$\sin 2a = 2 \sin a \cos a \quad (31c)$$

and recognizing that the following expression is an approximation

$$\sin (\alpha_c^{n+1})_{i,j} \approx \frac{\frac{1}{2} (y_{i,j}^{n+1} - y_{i-1,j}^{n+1} + y_{i,j}^n - y_{i-1,j}^n)}{\left( (\Delta x)^2 + (y_{i,j} - y_{i-1,j})^2 \right)^{1/2}} \quad (32)$$

along with assuming that the change in the denominator is small for a reasonable time-step (the numerator has been averaged over the  $n^{\text{th}}$  and  $n + 1^{\text{th}}$  time-steps), equation (30) results in

$$Q_{x_{i,j}}^{n+1} + (S3)_{i,j} y_{i,j}^{n+1} - (S3)_{i,j} y_{i-1,j}^{n+1} = (RHS1)_{i,j}^n \quad (33)$$

where  $(S3)_{i,j} = \left(\frac{1}{2}\right) (v_{i,j}) \cos(2\theta) (2 \cos \alpha_c) \frac{1}{(\Delta x^2 + \Delta y^2)^{1/2}}$

$$(RHS1)_{i,j}^n = (v_{i,j}) (2 \sin \theta \cos \theta) (\cos^2 \alpha_c - 1) - (S3)_{i,j} (y_{i,j}^n - y_{i-1,j}^n)$$

Here it has also been assumed that  $\cos^2 \alpha_c$  does not change over the time step. Equation (33) is the final form of the longshore sediment transport equation prior to its use in conjunction with the other equations.

Averaging  $y$  values on the  $n^{\text{th}}$  and  $(n+1)^{\text{th}}$  time-steps, equation (29) can be rewritten as

$$Q_{y_{i,j}} = \text{Const6}_{i,j} \left\{ \frac{1}{2} \left( y_{i,j-1}^{n+1} + y_{i,j-1}^n - y_{i,j}^{n+1} - y_{i,j}^n \right) + W_{EQ_{i,j}} \right\} \quad (34)$$

where  $\text{Const6}(i,j) = C_{OFF}(i,j) \cdot \Delta x$ . This is the final form on the onshore-offshore sediment transport equation.

The equation of continuity, finite-differenced for the  $n^{\text{th}}$  and  $(n+1)^{\text{th}}$  time-steps, can be written as

$$\frac{y_{i,j}^{n+1} - y_{i,j}^n}{\Delta t} = \frac{1}{2\Delta x \Delta h} \left\{ Q_{x_{i,j}}^{n+1} + Q_{x_{i,j}}^n - Q_{x_{i+1,j}}^{n+1} - Q_{x_{i+1,j}}^n + Q_{y_{i,j}}^{n+1} + Q_{y_{i,j}}^n - Q_{y_{i,j+1}}^{n+1} - Q_{y_{i,j+1}}^n \right\} \quad (35)$$

Defining  $R_{i,j}$  as  $1/(2\Delta x \Delta h)$ , inserting equations (33) and (34) into equation (35), and transferring all known quantities for the  $n^{\text{th}}$  time-step to the right-hand side of the equation result in

$$y_{i,j}^{n+1} + (\Delta t R_{i,j}) S3_{i,j} y_{i,j}^{n+1} - (\Delta t R_{i,j}) S3_{i,j} y_{i-1,j}^{n+1} - (\Delta t R_{i,j}) S3_{i+1,j} y_{i+1,j}^{n+1}$$

$$+ (\Delta t R_{i,j}) S3_{i+1,j} y_{i,j}^{n+1} - (\Delta t R_{i,j} \text{Const6}_{i,j}) \left( \frac{1}{2} [ y_{i,j-1}^{n+1} - y_{i,j}^{n+1} ] \right)$$

$$+ (\Delta t R_{i,j} \text{Const6}_{i,j+1}) \left( \frac{1}{2} [ y_{i,j}^{n+1} - y_{i,j+1}^{n+1} ] \right) = (AWARE)_{i,j} \quad (36)$$

Equation (36) can be rewritten as

$$(1 + U + V + Z1 + Z2) y_{i,j}^{n+1} - (U)y_{i-1,j}^{n+1} - (V)y_{i+1,j}^{n+1} - (Z1)y_{i,j-1}^{n+1} - (Z2)y_{i,j+1}^{n+1} = (AWARE)_{i,j} \quad (37)$$

where

$$U = \Delta t R_{i,j} S3_{i,j}$$

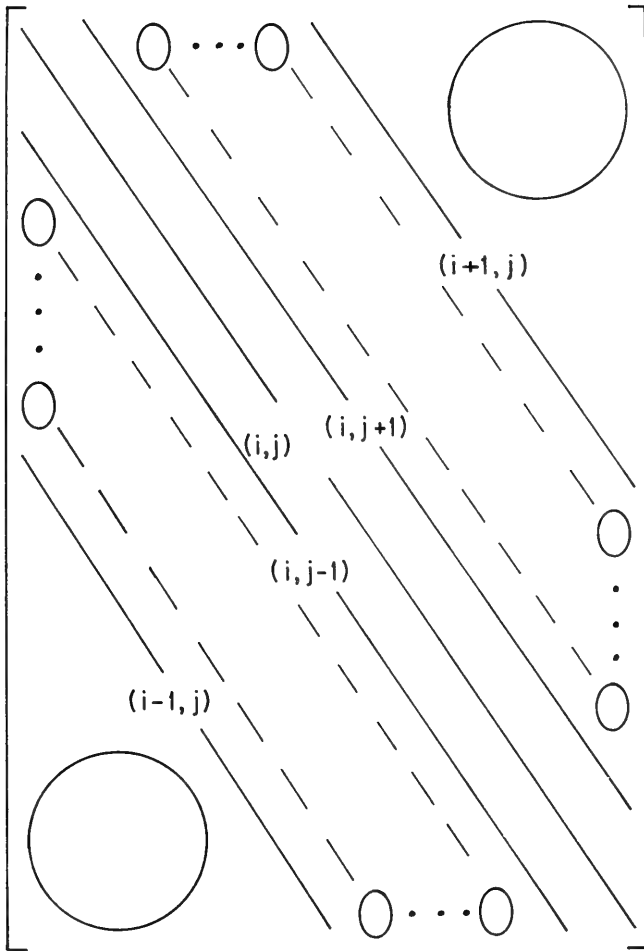
$$V = \Delta t R_{i,j} S3_{i+1,j}$$

$$Z1 = \left(\frac{\Delta t}{2}\right) R_{i,j} \text{Const6}_{i,j}$$

$$Z2 = \left(\frac{\Delta t}{2}\right) R_{i,j} \text{Const6}_{i,j+1}$$

Equation (37) is a weighted, centered scheme in which  $y_{i,j}^{n+1}$  is computed using a weighting of itself and its four adjacent grid "neighbors". The weighting factors (U, V, Z1, and Z2) are functions of the wave climate, the slope between contours, and the variables included in the original formulation. An investigation of a small gridded system demonstrated that by writing simultaneous equations, one for each  $y_{i,j}$ , a banded matrix results. This matrix can be solved by LEQT1B, one of the available routines from the International Math and Statistics Library (IMSL). A schematic representation of the matrix A which results from the matrix equation  $[A][y] = [B]$  is presented in Figure 5. In this schematic, the large zeros represent triangular corner sections of all zeros and the 0...0 represents bands of zeros, the number of which is dependent on the number of contours simulated (the number of zero bands between either remote nonzero bands and the tridiagonal nonzero bands equals two less than the number of contours modeled (in both the upper and lower codiagonals of the matrix)). An inspection of the subscripts in equation (29) yields the reason the zero bands are required. The more j values (contours) used, the more y grids there are along any perpendicular to shore. This causes zeros to appear in the matrix between bands as the weighting factors await being used to operate on  $y^{n+1}(i-1,j)$  and  $y^{n+1}(i+1,j)$ . For this reason, the expense of simulating an increasing number of contours is exponential. The LEQT1B routine, utilizes banded storage and saves both storage and computation time; however, the routine has no special way of handling the interior zero bands. One refinement which would save computation time would be to develop an algorithm to solve and store the matrix by taking advantage of these inner zero bands; however, it is beyond the scope of this project.

Of course, the matrix requires boundary values on longshore extremities and on both onshore and offshore boundaries. The longshore boundary conditions are treated by modeling a sufficient stretch of shoreline so that effects of a structure's presence are minimal. The y values along these boundaries can therefore be fixed at their initial locations. In the onshore-offshore direction, boundaries are treated quite differently. The



Note: Size of matrix full storage mode  
 $[(IMAX-2)(JMAX) \times (IMAX-2)(JMAX)]$   
 Size of matrix banded storage mode  
 $[(IMAX-2)(JMAX) \times (2JMAX + 1)]$

Figure 5. Schematic representation of banded matrix if not stored in banded storage mode.

berm and beach face are assumed to move in conjunction with the shoreline position. The required sediment transport is then computed by the change in position of the shoreline. The two equations are

$$y_{i,0}^{n+1} = y_{i,0}^n + [y_{i,1}^{n+1} - y_{i,1}^n] \quad (38a)$$

$$Q_{y_{i,1}}^{n+1} = - \left[ \frac{\text{Berm } \Delta x}{\Delta t} \right] [y_{i,1}^{n+1} - y_{i,1}^n] \quad (38b)$$

The offshore boundary is treated by keeping  $y^{n+1}(i,j_{\text{max}})$  (the contour beyond the last simulated contour) fixed, until the angle of repose is exceeded. Then, the  $y^{n+1}(i,j_{\text{max}}+1)$  is reset (at the conclusion of the  $n+1$  time-step) to a position such that the slope equals the angle of repose. Note that  $y^{n+1}(i,0)$  is represented in the program by YZERO<sub>i</sub>.

There are also no-flow boundary conditions required at each of the structures being modeled. These are imposed on the adjacent  $y$ -grid points which are located downdrift (i.e., in the shadow zone) of the structure and shoreward of the structures' seaward extremities. They are imposed by setting  $S3_{i,j}$  of equation (33) and  $\text{DISTR}_{i,j}$  (the term in square brackets in equation (29)) equal to zero, thereby causing  $Q_X(i,j)$  to be zero (i.e., the no-sediment flow condition). This boundary condition is imposed automatically for every shore-perpendicular structure.

It was found that even with the implicit formulation, high frequency oscillations occurred in the  $y$  values immediately updrift and downdrift of the structure. The solution did not "blow up"; however, on larger time-steps "sloshing" (oscillating) did occur. Part of this problem was due to the boundary condition at the structure which had been such that either no sand was allowed along a contour line or the sand determined by the equations was allowed to be transported. Because of the very large angle which existed around the tip of the structure when a contour first exceeded the length of the structure, very large amounts of sediment transport were predicted. In the nature where analog sand transport rather than digitized transport occurs, this does not happen. Therefore, the boundary condition was altered to constantly allow sand transport around the end of the structure in proportion to that part of the contour representation which exceeded the structure (i.e., the transport was calculated for the location at tip of the structure as if the structure was not there and then a proportion of this value was allowed to bypass). Although the transport around the tip of the structure is based on the values from the past time-step, it more closely simulated the natural phenomenon.

Additionally, a dissipative interface is used on the  $y$  values as follows:

$$y_{i,j} = (\tau) y_{i-1,j} + (1 - 2\tau) y_{i,j} + (\tau) y_{i+1,j} \quad (39)$$

where  $\tau$  was again taken as 0.25. It is noted that only high frequency oscillations in  $y$  are affected by the use of equation (39); the total sum of  $y$  values is not affected. Also, in all the dissipative interface

schemes used, if a boundary point is being computed, either a forward-difference or a backward-difference of equation (39) is used (after Abbott, 1979):

$$\text{Backward: } y_{i,j} = (\tau)y_{i-1,j} + (1 - \tau)y_{i,j} \quad (40a)$$

$$\text{Forward: } y_{i,j} = (\tau)y_{i+1,j} + (1 - \tau)y_{i,j} \quad (40b)$$

#### IV. SIMULATIONS AND VERIFICATION

Several simulations were run; two were attempts at verifying the numerical model, the others were run to gain insight. Because a complete data set does not exist, only the available data are compared. The first modeling effort was to simulate the physical model tests of Savage (1959). A second set of cases was run for shore-perpendicular structures. Next, an effort was made to model sediment transport in the vicinity of a hypothetical dredge disposal site in the 11- to 14-foot depths off Oregon Inlet. Finally, the Channel Islands Harbor Longshore Transport Study (Bruno, et al., 1981) was modeled. Bathymetric changes were closely monitored during this study; however, the wave climate (H,  $\theta$ , T) used was determined from the Littoral Environmental Observation (LEO) data and uncertainties exist as to the accuracy of the data.

##### 1. Simulation of Savage's Physical Model Tests.

The numerical model was used to simulate one of the physical model tests of Savage (1959). Test 5-57 was simulated numerically for a 10-hour period. In this physical model, the mean sediment size was 0.22 millimeters, the wave height averaged 0.25 feet, the wave period was 1.5 second, the wave angle was 30° (at a depth of 2.3 feet), and the groin was approximately 9.5 feet from still water to its seaward limit.  $C_{OFF}$  was held constant at  $10^{-4}$  feet per second throughout the profile for this simulation. The offshore profile is presented in Savage (1959). Figure 6 represents three of the eight contours simulated. Note that the initial 0.3- and 0.5-foot-depth contours, in the numerical representation are too far seaward by approximately 2 feet. This is due to the  $h = Ay^{2/3}$  equation as compared to the equilibrium physical model profile. Realizing this, it is the shape of the contour which must be used as an indication of the numerical model predictions. The general trend of the contours is similar, although the numerical model contours are displaced farther seaward as expected. The major differences are in the diffraction zone.

##### 2. Several Runs Using Shore Perpendicular Structures to Demonstrate Effects of Altering Some of the Pertinent Parameters.

In the following simulations, the models were run until their near-equilibrium values were achieved. Coefficient  $C_{OFF}$  was not a function of depth (beyond the surf zone) but was held constant throughout the simulated area. Important variables are as shown in the figures. Only one wave condition ( $H_0 = 3$  feet,  $T = 7$  seconds, and a deepwater wave angle  $\alpha_0$

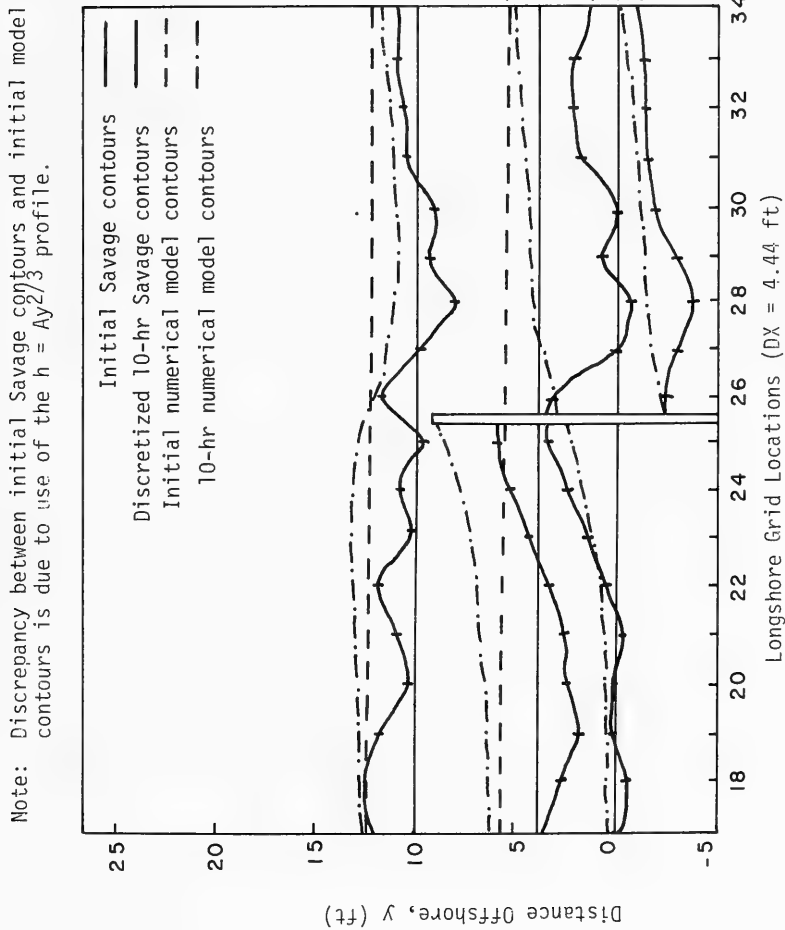


Figure 6. Simulation of the physical model of Savage (1959).

of 60°) was used as input for all four cases. Case 4.2a used an equilibrium shape factor A of 0.0899 and one groin. Case 4.2b was similar to 4.2a with the only modification being, that the A value was changed to 0.1486. In this way, a direct comparison was made based only on the shape of the equilibrium profile. Cases 4.2c and 4.2d used A-values of 0.0899 and 0.1486, respectively, but this time three shore-perpendicular, evenly spaced structures were simulated.

a. Comparison of Cases 4.2a and 4.2b. The most obvious difference between Figures 7 and 8 is the volume of sand impounded updrift and eroded downdrift. This is due to blockage of more of the active transport zone in the second case (i.e., a shorter groin is required for an equivalent performance on a steeper beach). The next obvious difference is the size of the perturbation which exists in the offshore contours. Clearly, case 4.2b is more perturbed and this is expected because larger offshore transports occur due to the steepening on the updrift side. Conversely, this means less sediment is initially bypassed (and along with the downdrift requirement for larger volumes of sand) causes larger erosional features in case 4.2b. Another interesting feature is the downdrift fillet which occurs in the third, fourth, and fifth contours. The fillet is due to the shape of the sixth contour which occurs because of the inability of the wave to transport more sediment (due to the reduction in wave height and angle in the diffraction shadow zone). The remaining difference is also due to the volume of sediment being impounded; i.e., the distance and extent of change the presence of the groin causes upcoast and downcoast.

b. Comparison of Cases 4.2c and 4.2d. The variations between cases 4.2c and 4.2d are very similar to the differences between cases 4.2a and 4.2b as would be expected with a groin field (here, three groins) as compared with a single groin (see Figs. 9 and 10). There is, however, one additional feature which can be attributed to the additional groins. Note that in the direction of littoral drift, the size of the fillet is decreasing. This is due to the updrift beach having an uninterrupted supply of sediment while the downdrift groin compartments are supplied sand at a rate determined by the bypassing. Part of this feature may also be due to the system not having attained complete equilibrium.

The effects of the fixed boundary conditions are evident on all cases run. In these example cases, the boundaries are clearly too close to the structure to provide a proper representation of the fillet contours.

### 3. Simulations of Sediment Transport of Dredge Disposal in the Vicinity of Oregon Inlet.

Hypothetical dredge disposal movement in the nearshore but beyond what is normally the surf zone at Oregon Inlet's adjacent beach to the south was modeled. In order to do these simulations, the program was altered such that for every  $n^{\text{th}}$  iteration (time periods), the contours were shifted seaward to simulate the addition of dredged sediment disposal. The program presented in Appendix B does require slight modification to simulate this situation.

In general, the fifth and sixth contours were shifted seaward on a monthly basis to simulate the disposal of 121,000 cubic yards of sediment.



Note: J=7 and 8 contours not shown

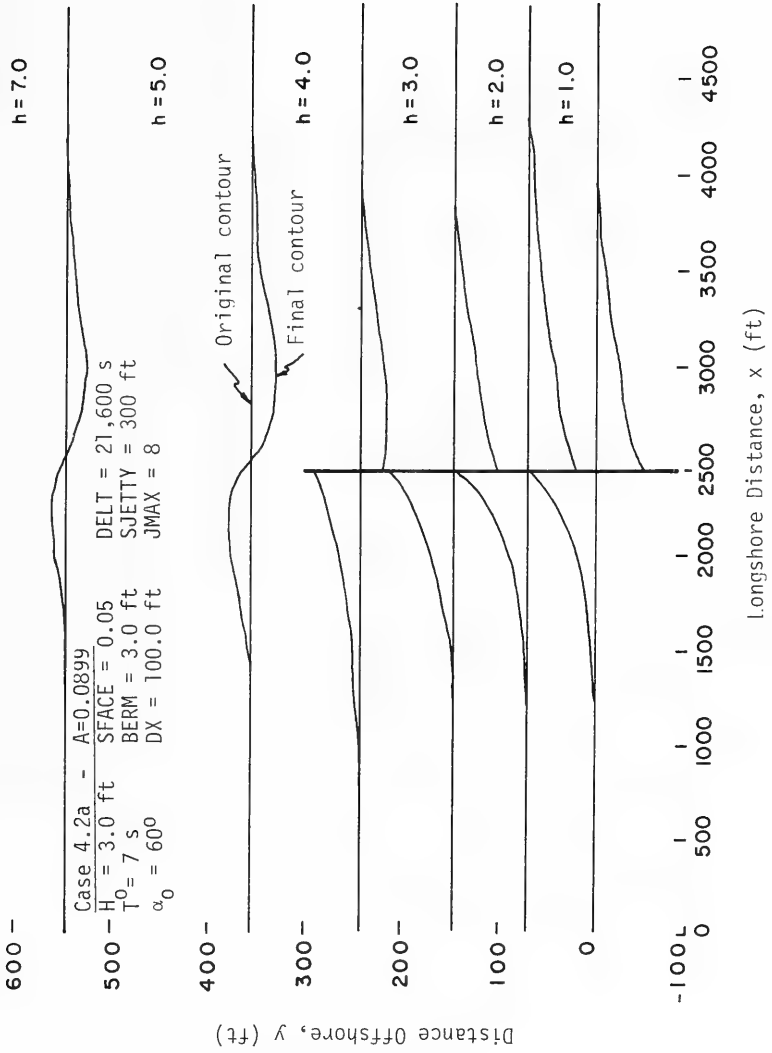


Figure 7. Equilibrium planform, case 4.2a.

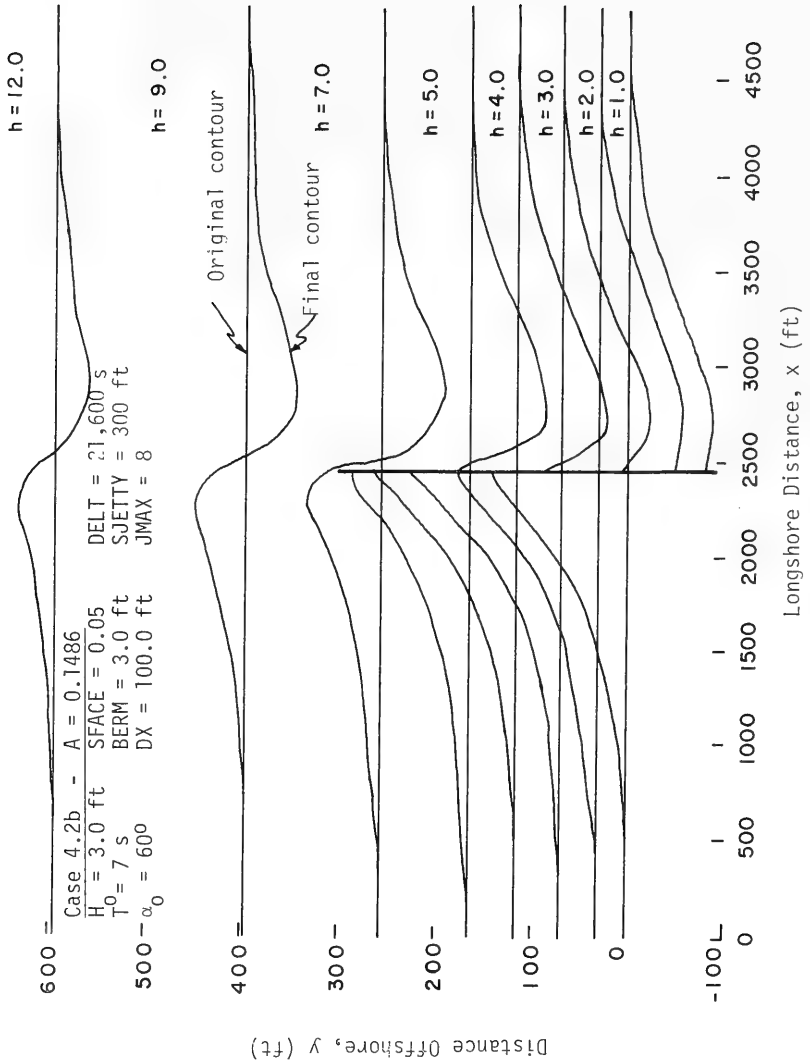


Figure 8. Equilibrium planform, case 4.2b.

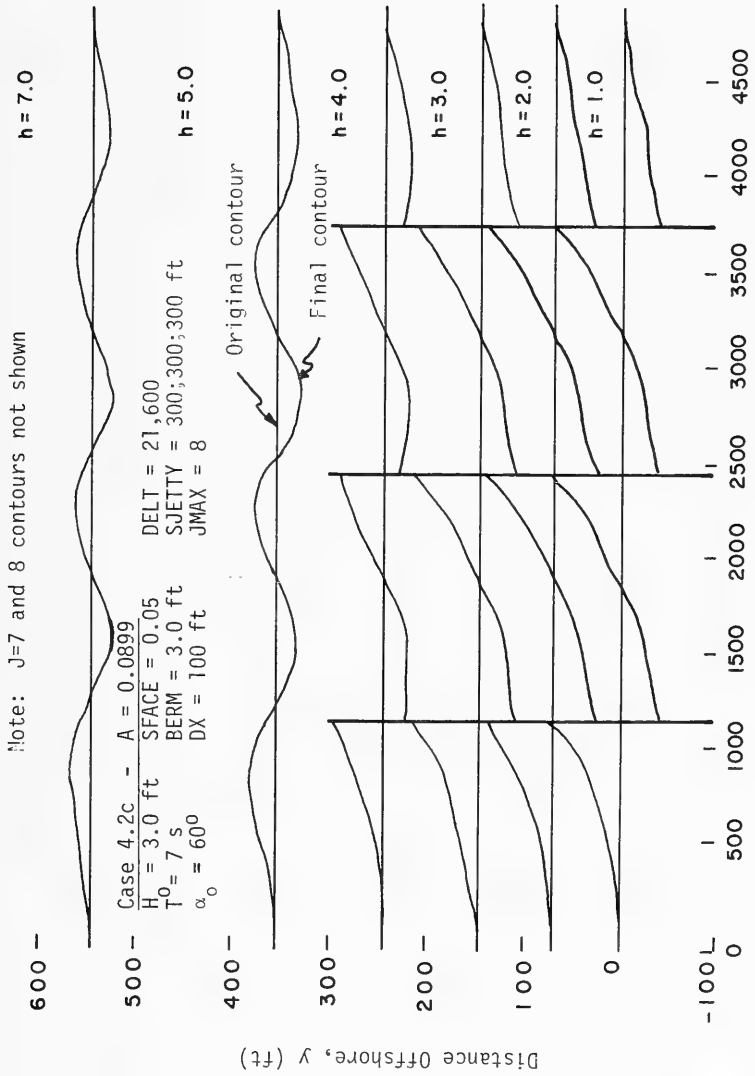


Figure 9. Equilibrium planform, case 4.2c.

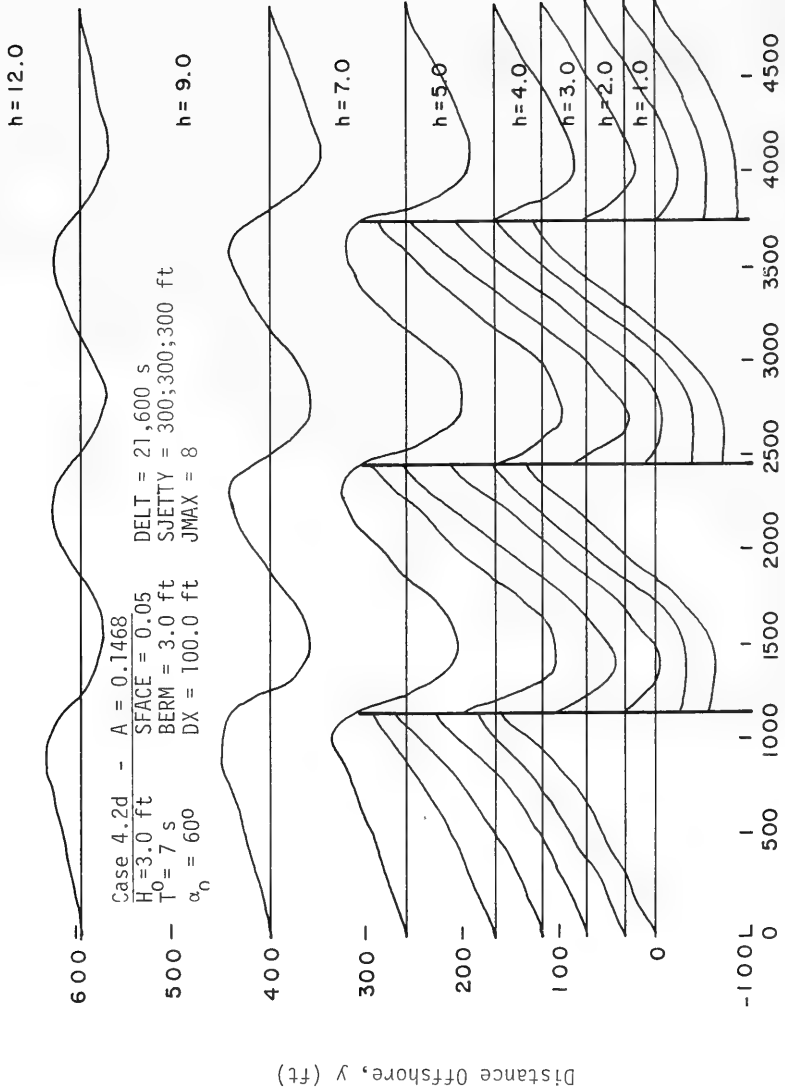


Figure 10. Equilibrium platform, case 4.2d.

In all these simulations, the following variables were held constant: (a) a time-step of 3 hours, (b) a shoreline length of 10,000 feet, (c) a longshore space-step of 200 feet, (d) an A value of  $0.15 \text{ foot}^{1/3}$  for the equilibrium profile (see Fig. 11), (e) a berm height of 5.3 feet with a beach face slope of 0.05, and (f) a duration of 1 year. The wave climate was provided by the U.S. Army Engineer Waterways Experiment Station Wave Information Study (WIS) 1975 data and was initiated at different times of the year as indicated in the specific cases below. All simulations, prior to any addition of sediment, used the bathymetry shown in Figure 12. The shoreline (relative to mean low water, MLW) was scaled from a bathymetry-topography survey provided by the U. S. Army Engineer District, Wilmington. The initial offshore bathymetry was computed according to the equilibrium profile and the 0-foot contour; i.e., the profile was shifted seaward or landward, accordingly, (see App. C.) The boundary profiles were fixed throughout the simulations. The variation of COFF outside the surf zone was used because of the importance of the time rate of change in this simulation. Table 1 presents the percentage of sediment which moves out of the control volume (i.e., imaginary boundaries around the area where sediment was added) directly onshore and the percentage of sediment remaining in the control volume at the conclusion of the simulation for each of the cases. In addition, a seventh (case 3) and eighth (case 4) were modeled. In Case 3, the only difference was that sediment was placed at the 11- and 14-foot contours. Case 4, however, was quite different and will be described in detail later. It has a 20,000-foot shoreline, a longshore space-step of 400 feet, and sediment was added on a weekly basis. Also, the resolution in the profile was better.

#### a. Specific Cases.

(1) Case 2.a. In order to provide insight for the interpretation of the other modeling efforts, a simulation of the shoreline evolution using the January to December WIS time series, with no addition of sediment, was carried out. As expected, the contours almost attain an equilibrium planform shape (i.e., straight and parallel between the fixed end profiles; they do not, however, become aligned parallel to the base line because of the end conditions). Because of the scales involved, alongshore versus onshore-offshore, plotting the contours without distortion does not yield much information. Appendix C provides a listing of the final contours for all the cases modeled.

(2) Case 2.b. The only difference between cases 2.a and 2.b is the suppression of the WIS wave angle which was set equal to zero (i.e., wave crest approach is shore-parallel at the offshore boundary of the model). This does not cause the longshore sediment transport to vanish completely. There are still local gradients in the contours which cause refraction and relative angles between wave crest and contour, thereby driving the longshore sediment transport (even if refraction was not considered, the local angle between the wave crest and contour would cause sediment transport). Note the larger onshore transport (Table 1) for this case compared with Case 2.a. This is due to the reduction in longshore transport caused by the wave angle of  $0^\circ$ . The model still tries to smooth the contour lines; however, more of the smoothing for the present case must be done by onshore-offshore transport.

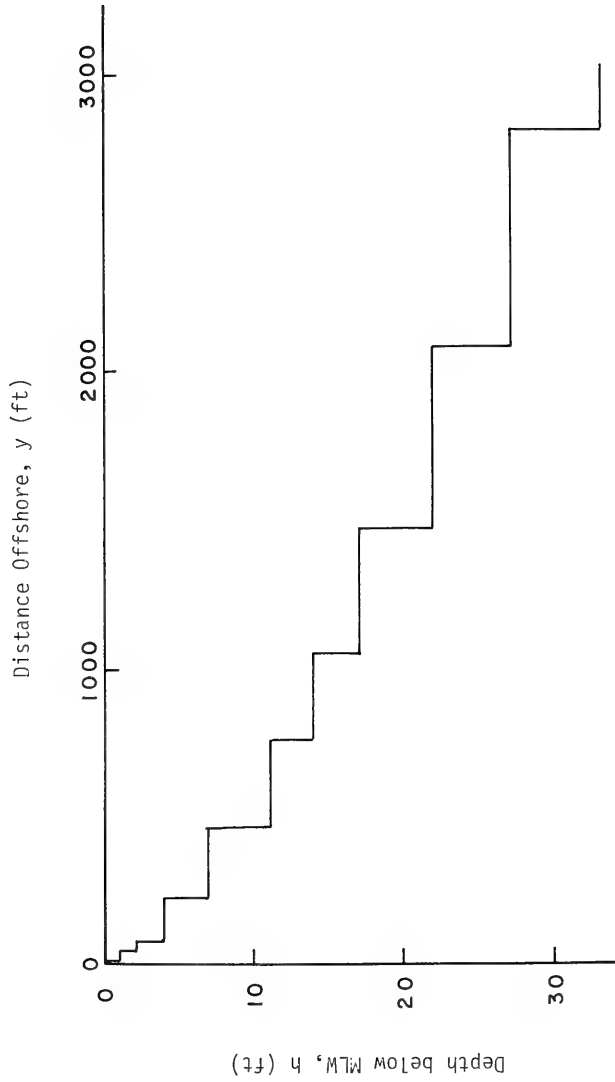


Figure 11. Stepped version of equilibrium profile used in the Oregon Inlet modeling,  $h = Ay^2/3$  ( $A = 0.15 \text{ feet}^{-1/3}$ ).

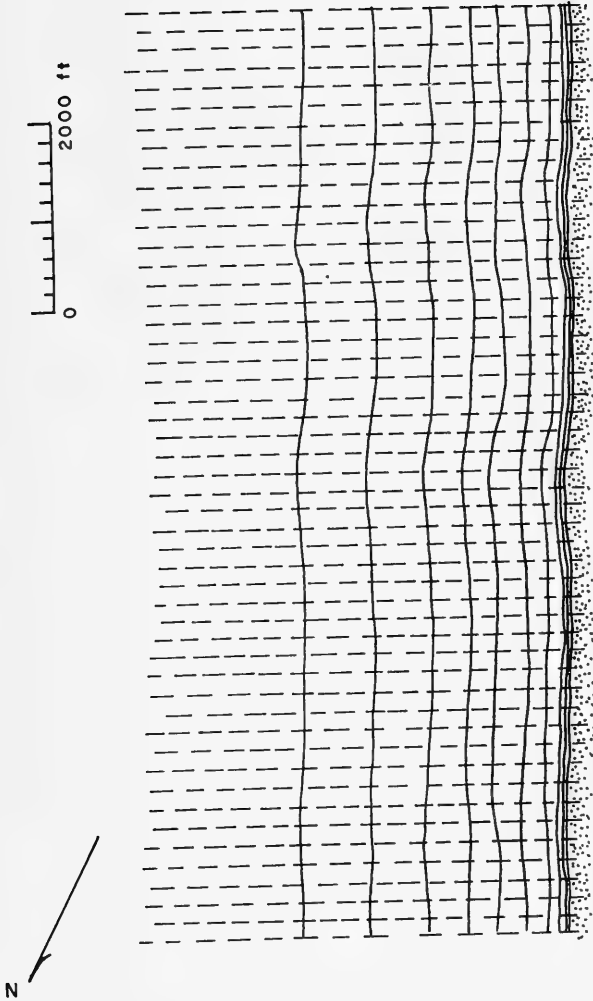


Figure 12. Initial contours used in the numerical model for all the Oregon Inlet simulations. (The scale for case 4 was twice the scale shown.)

Table 1. Summary of results at Oregon Inlet.

Case No.	Description	Pct Onshore out of control volume	Pct Remaining in control volume
2.a	No sediment added, WIS waves Jan. - Dec.	Onshore Movement (992 yd <sup>3</sup> )	Increase (14,148 yd <sup>3</sup> )
2.b	No sediment added, WIS waves ( $\alpha = 0^\circ$ ) Jan. - Dec.	Onshore Movement (1624 yd <sup>3</sup> )	Increase (9,356 yd <sup>3</sup> )
2.c1	121,000 yd <sup>3</sup> added monthly, WIS waves Jan - Dec.	31.7 (460,264 yd <sup>3</sup> )	38.6 (559,984 yd <sup>3</sup> )
2.c2	121,000 yd <sup>3</sup> added monthly, WIS waves Apr. - Mar.	32.1 (466,160 yd <sup>3</sup> )	36.9 (535,392 yd <sup>3</sup> )
2.c3	121,000 yd <sup>3</sup> added monthly, WIS waves July - June.	28.6 (415,784 yd <sup>3</sup> )	47.0 (682,088 yd <sup>3</sup> )
2.c4	121,000 yd <sup>3</sup> added monthly, WIS waves Oct. - Sept.	27.2 (395,556 yd <sup>3</sup> )	46.8 (670,848 yd <sup>3</sup> )
3	121,000 yd <sup>3</sup> added monthly at the 11- and 14-foot contours WIS waves, Jan. - Dec.	8.9 * (32,164 yd <sup>3</sup> )	78.0 (283,016 yd <sup>3</sup> )
4	27,923 yd <sup>3</sup> added weekly on the 7-8-, 9-, and 10-foot contours, WIS waves Jan. - Dec.	19.0 (275,796 yd <sup>3</sup> )	47.4 (687,525 yd <sup>3</sup> )

\* After 17 weeks, the addition of sand caused contours to cross. Prior sediment added was 363,000 yd<sup>3</sup>. Problem was rectified; however, case was not rerun.



(3) Case 2.c1. In this simulation, sediment is added to the system each month. It was simulated by advancing the 7- and 11-foot contours on a monthly basis to represent 121,000 cubic yards per month. Specifically, the sand volumes were "tapered" starting at the center of the nourished area over a distance of + 2,700 feet from the center. Table 2 presents the monthly  $\Delta y$  values for the blocks between the 7- to 11-foot contours and the 11- to-14 foot contours. Figure 13 shows the planform  $\Delta y$  values added monthly. WIS waves were used with the sequence being the normal calendar year, January through December.

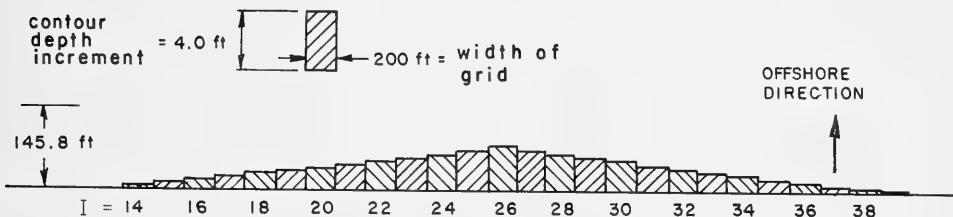


Figure 13. Monthly incremental values of  $\Delta y$  due to dredge disposal illustrated for the block between 7- and 11-foot contours.

The initial and final fifth and sixth contours have been plotted in Figures 14 and 15. The first figure has no distortion; the second is distorted 10 to 1. The simulation predicts that 31.7 percent of the dredge disposal will move shoreward out of the control volume. An additional 29.7 percent efflux occurs in the offshore and longshore directions, leaving only 38.6 percent of the total amount of sediment added remaining in the control volume. It is not clear what quantity of the sediment leaving in the longshore direction would reach shore. It is conceivable that most of this sediment would eventually reach the surf zone. The rate at which this material would move ashore would be expected to be slower than the rate at which the large mounds would move ashore because the deviation of the profile from equilibrium is much less.

(4) Cases 2.c2, 2.c3, and 2.c4. The next three simulations were the same as 2.c1 except the time series of wave events has been seasonally altered. Cases 2.c2, 2.c3 and 2.c4 use the 1975 wave climate from April through March, July through June, and October through September, respectively. The maximum variation is about 5 percent for the sediment volume moving onshore, and about 10 percent for the volume remaining. The variation in the

Table 2. Monthly values of  $\Delta y$  for the steps located between the 7- to 10-foot contours and the 11- to 14-foot contours.

Value of I	Monthly $\Delta y$ value (ft) for steps between	
	7- and 11-foot contours	11- and 14-foot contours
26	145.8	194.4
25,27	135.4	180.5
24,28	125.0	166.6
23,29	114.6	152.7
22,30	104.1	138.9
21,31	93.7	125.0
20,32	83.3	111.1
19,33	72.9	97.2
18,34	62.5	83.3
17,35	52.1	69.4
16,36	41.7	55.5
15,37	31.2	41.7
14,38	20.8	27.8
13,39	10.4	13.9
All Others	0	0

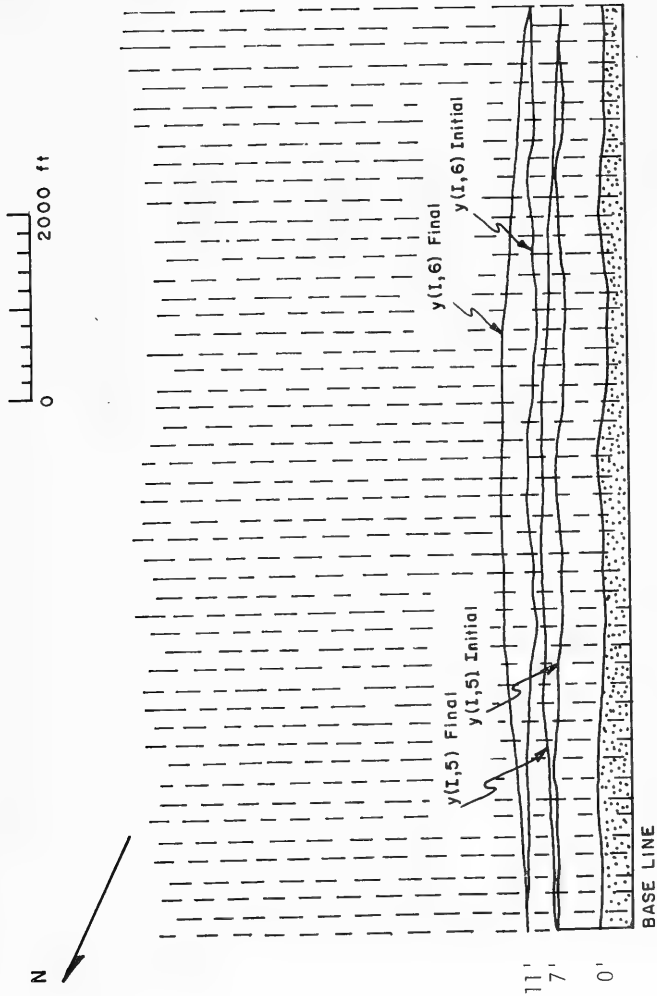


Figure 14. Initial and final 7- and 11-foot contours (no distortion).

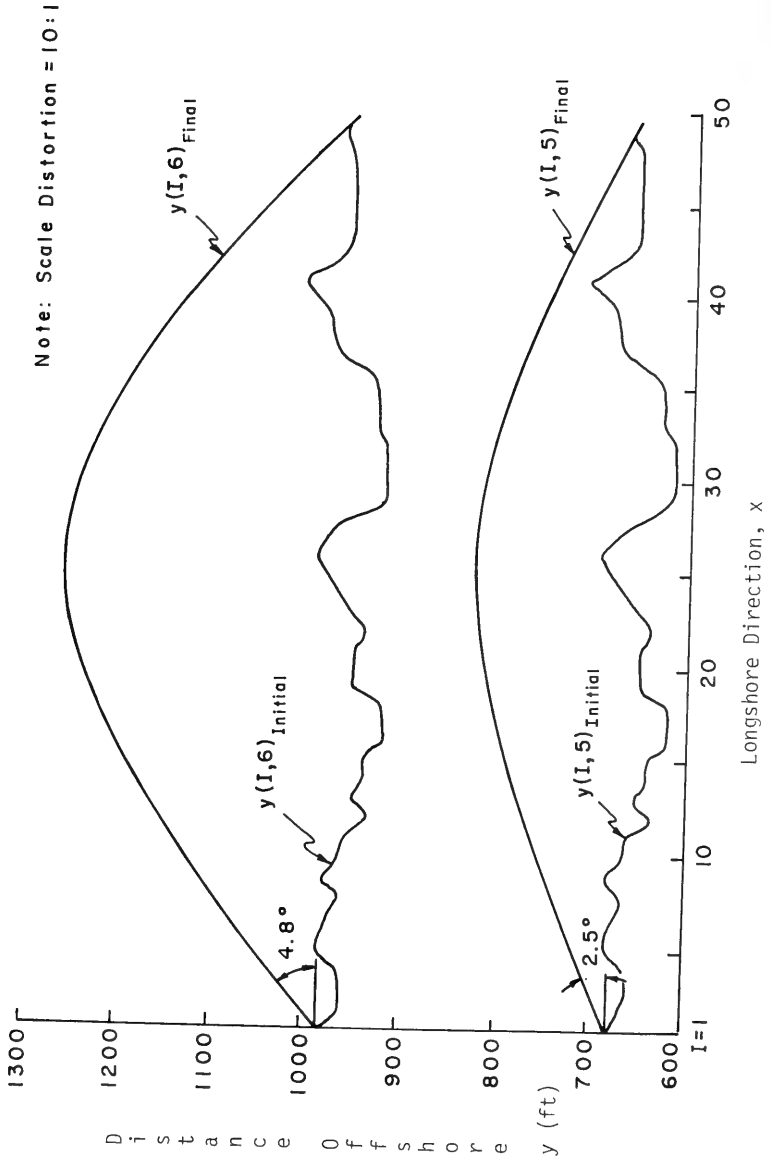


Figure 15. Initial and final contours for case 2.c1 [ $y(I,5)$  and  $y(I,6)$ ].

quantity moving onshore could be caused by waves that first tend to move more sediment longshore; then, the waves that transport more sediment onshore have a less out-of-equilibrium profile to cause movement upon. The variation in percentage remaining is due to the variation of the time series of the wave climate, with the last month in the simulation being especially important.

(5) Case 3. Instead of extending the 7- and 11-foot contours monthly to simulate the disposal of dredged sediments, the 11- and 14-foot contours were extended (194.4 feet each at the center of the disposal area). This case was modeled because the larger available dredge could not dump in more shallow water. The reduction and increase in the percent of onshore volume and the percent volume remaining (8.9 percent and 78.0 percent, respectively) demonstrate the sensitivity of the depths investigated. Qualitatively, these depths are the depths to which offshore bars occur along the Atlantic U.S. coast.

(6) Case 4. Further investigation of the disposal process demonstrated the need for an 11,000-foot shore-parallel disposal length with the sediment placed at the 11-foot contour building to about 7 feet. It was decided to model this physical situation also. The total shoreline length was changed to 20,000 feet, and the space step to 400 feet; the length of the disposal area in the longshore direction was increased to 10,800 feet. The resolution in the vicinity of the depths of the dump was improved by adding the additional contours and the profile is shown in Figure 16. As in the other seven cases, 1,452,000 cubic yards was added annually to the system; however, the addition was accomplished on a weekly basis (27,923 cubic yards per week). Sediment was still added by extending the contours seaward, but rather than placing one-fourth of the sediment at each of the four contours, the volumes were determined based on the trapezoidal cross section shown in Figure 17. This cross section more closely resembles the disposal mound formed by hopper dredging. The incremental values Figure 18 show, in planform, the extension of the contours to simulate the weekly sediment addition at the 8-foot contour.

A schematic illustration of the sediment transported from the nourished region is presented in Appendix C. Nineteen percent of the sediment added moved directly onshore out of the control volume.

b. Conclusions for the Movement of Disposed Sediment in the Vicinity of Oregon Inlet. The computer simulations, tempered with engineering judgment, demonstrate that between 15 and 35 percent of the material added to the 7- and 11-foot contours, or to the 7- 8- 9-, and 10-foot contours would be transported into the nearshore transport system during the first year. If the disposal process was continued, the system would approach steady state in terms of the volume of deposited material residing offshore.

For the case of sediment addition at the 11- and 14-foot contours, the computer simulations, tempered with engineering judgment, show that between 5 and 25 percent of the material added would be transported into the nearshore transport system during the first year.

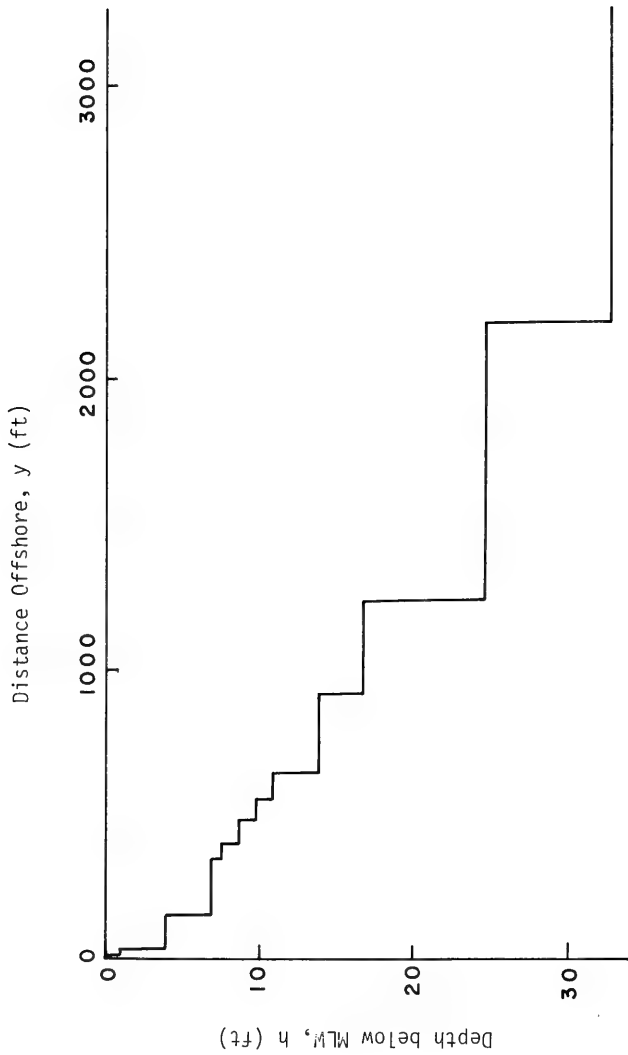


Figure 16. Stepped version of equilibrium profile used in the Oregon Inlet modeling,  $h=Ay^{2/3}$  ( $A=0.15 \text{ feet}^{1/3}$ ), case 4. Note the resolution at 7, 8, 9, and 10 feet.

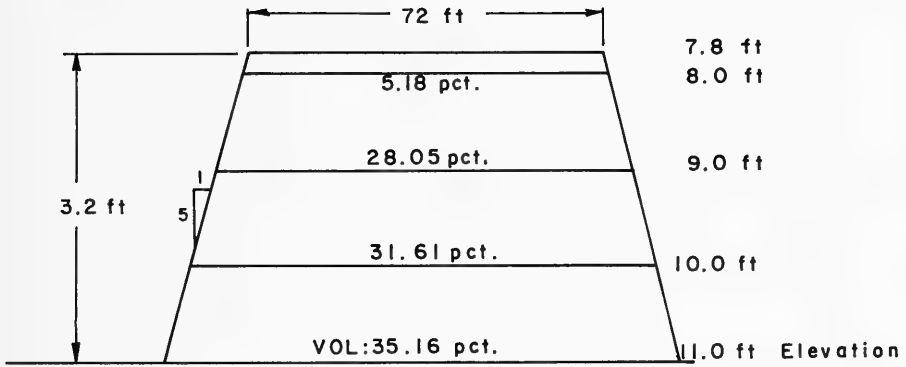


Figure 17. Shore-perpendicular cross section of disposal mound. The volumes represent the volume percentage of the trapezoidal section between contours and therefore, the quantity of sediment added to the 7-, 8-, 9-, and 10- foot contours.

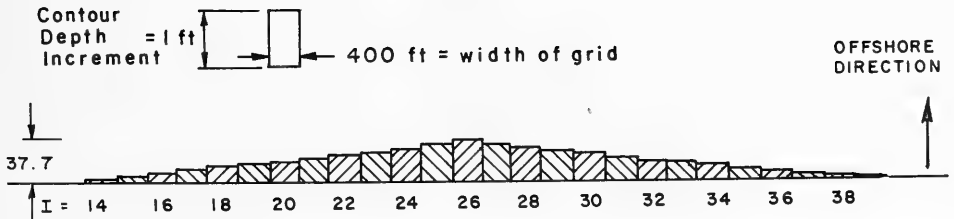


Figure 18. Incremental values of  $\Delta y$  due to dredge disposal, illustrated for the block between 8- and 9-foot contours (case 4).

#### 4. Simulation of the Longshore Sand Transport Study at Channel Islands Harbor, California.

The CIH Longshore Sand Transport Study (Bruno, et al., 1981) was the only field study found suitable for verification purposes. Wave data collected included the LEO data and a two pressure-sensor gage array. Although the pressure gages were not in operation throughout the study, it was expected that the data they produced would be superior to that of the LEO data. However, these data were not available in a reduced form, so the LEO data were used. An adjustment of  $11^\circ$  was made to the breaker angle to orient the angle with respect to the base line, rather than to the local shoreline orientation angle. Observations had been taken twice daily at three locations; the middle location was used (observer No. 5714). Waves which approached the shoreline at angles too large to have originated in a depth of 10 meters, according to Snell's law, were set equal to  $90^\circ$  at that depth (crest of wave perpendicular to the baseline). The 10-meter depth was chosen because it is the approximate depth at the tip of the offshore breakwater (for this reason, it was also chosen as the depth of the step beyond the  $y(I, J_{MAX} + 2)^{th}$  contour). It was assumed that each of the two daily observations occurred for 12 hours and using a time-step of 6 hours, this meant two time-steps per wave. In cases where parts of the wave data ( $H_b$ ,  $\alpha_b$ , or  $T$ ) were missed by the observer or were equal to zero, the data were ignored (no computations were made), but the time was included. Because the time rate of change is important for this simulation, the variation of  $C_{OFF}$  outside the break point was used.

The period chosen to model was 20 April through 1 December 1976. The initial survey was taken after dredging of the sediment trap and for this reason was known to be out of equilibrium. The bathymetric surveys were conducted using several methods, the most advanced being a Lighter Amphibious Resupply Cargo vessel (LARC) proceeding along shore-perpendicular lines (approximately in the vicinity of each survey station) taking fathometer readings every 10 seconds, with positioning systems trilaterating the vessel's position concurrently. These data were recorded on tape. The beach-face data were taken using standard surveying methods. Because the data fluctuated randomly about the stations, depending on the speed of the craft, the  $(x, y)$  coordinate positions had to be altered to fixed changes in  $x$  and  $y$ . This was accomplished using an interpolation routine. The  $x$  values were made to coincide with the stations used in the surveys, and the  $y$  values were determined at 100-foot intervals beginning from the base line. Stations 100+00 and 118+00 were located at the north jetty and termination of the detached breakwater, respectively (these correspond to  $I$  values of 16.5 and 34.5 in the model). See Figure 19.

Monotonic profiles of the form  $h = A(y - y_{del})^{2/3}$  were fit to the data along each station line. " $y_{del}$ " represents the zero location of the fitted shoreline, the value of which was unknown. Because dredging had been done in the lee of the breakwater, there was no reason to expect the  $A$  value to correspond to the value upcoast where the influence of the structure and the dredging was negligible. For this reason, the profiles of Stations 122+00 through 134+00 were evaluated separately to determine an  $A$  value for the equilibrium profile to be used in the numerical model. For the detailed method used (LaGrange Multipliers and Newton-Raphson Method for nonlinear



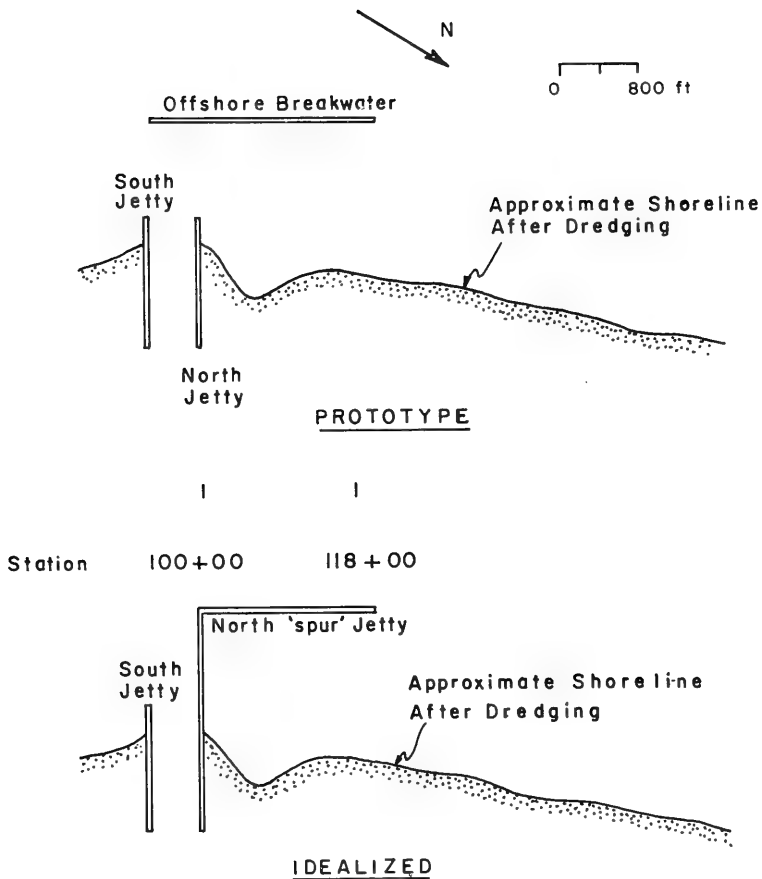


Figure 19. Idealized numerical model representation of offshore breakwater at Channel Islands Harbor, California.

equations) and the computer programs see Appendix D. The two values obtained for the surveys of 20 April and 1 December 1976 were averaged to obtain the value used in the model,  $A = 0.2606$ . Stations 101+00 through 121+00 were treated separately for the purpose of obtaining values with which to initialize those parts of the contours in the model and for comparison of the model predictions with the prototype values. Note that although the breakwater extends only to about Station 118+00, the influence of the structure and dredging extends beyond that location and so, although arbitrary, the 121+00 station was chosen as the dividing line. The initial and final values of the scaling parameter  $A$  for the profiles were 0.3233 and 0.3528, respectively. Because the initial shoreline is so irregular, a discontinuity between 121+00 and 122+00 is not evident.

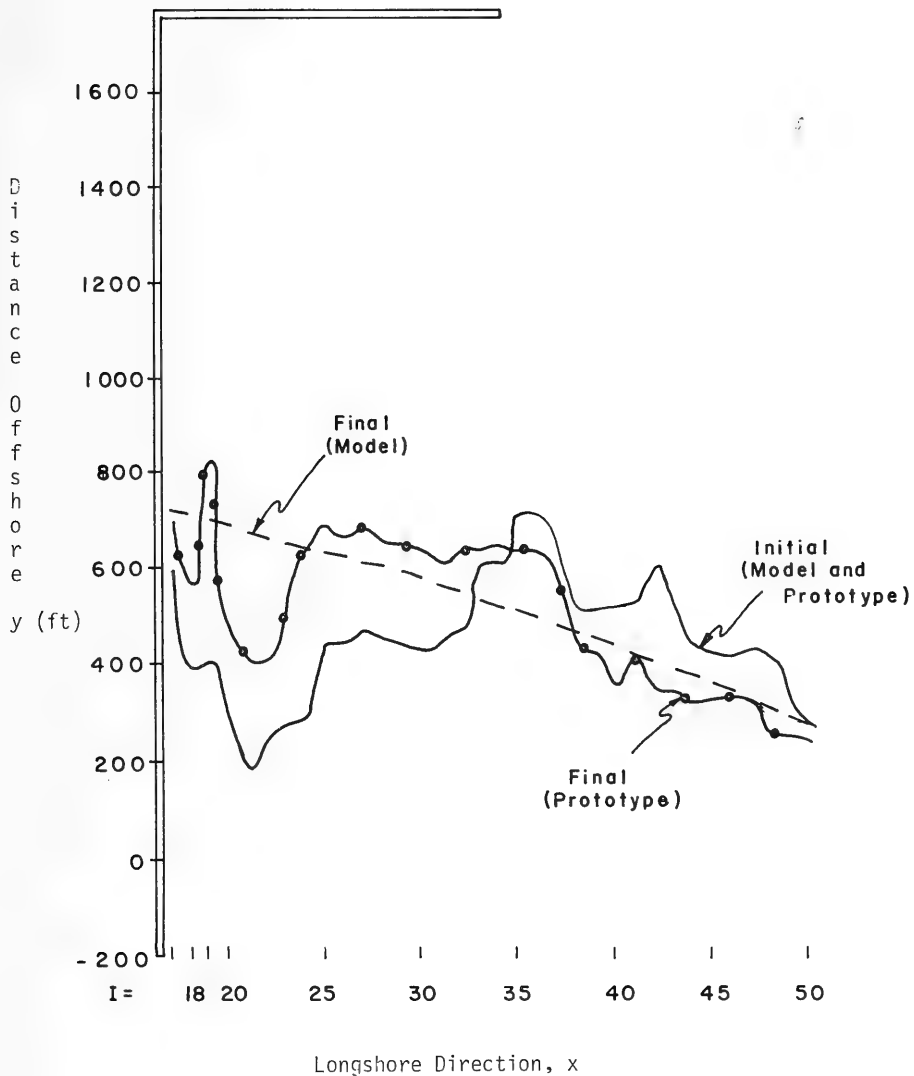
One further idealization was made. The jetty-breakwater system was idealized as shown in Figure 19. This was required to simplify the physical situation, and although waves, currents, and sediment do pass through the opening in the prototype, it is hoped that they are of secondary importance.

The results of the numerical modeling of Channel Islands Harbor are presented in Figures 20 and 21. The first figure presents the shoreline contour (depth = 0); the second figure presents the farthest offshore, modeled contour. In both cases, the initial shoreline represents the model and prototype (after fitting of the profiles). The initial shoreline contour is further offshore along the section of beach beyond the end of the breakwater, while in the lee of the breakwater, as would be expected after dredging, the shoreline is closer to the base line. The final prototype contour has undergone erosion along the reach beyond the tip of the structure, and accretion in the lee.

The model's shoreline contour has undergone similar changes, and on the average, represents the final prototype contour quite well. The  $JMAX^{th}$  contour has been displaced quite similarly to the shoreline contour with shoreward movement (erosion) along the reach beyond the tip of the breakwater and seaward movement (accretion) within. It appears that the final model's shoreline has predicted too much erosion and not enough accretion. Several parameters could be incorrect, with the onshore-offshore sediment transport rate coefficient,  $C_{OFF}$ , perhaps the most likely. Overall, the model seemed to predict reasonable values of the contours.

## V. SUMMARY AND RECOMMENDATIONS

Some of the parameters that the model does not include are important and should be mentioned. As stated previously, the model does not include bar formation. This is precluded by an n-line system. There are no provisions for water level fluctuations or currents. Improvement to the model could also be facilitated with better longshore and cross-shore sediment transport relationships. A more reliable equation for distribution of sediment transport across the surf zone would also be helpful (or further testing and calibration of the equation proposed herein). Finally, combining refraction and diffraction using equations to predict their combined effect would improve the wave field. The program was constructed such that improvement



Longshore Direction, x  
 Figure 20. CIH simulation of shoreline contour, 20 April - 1 December 1976 (from LEO data).

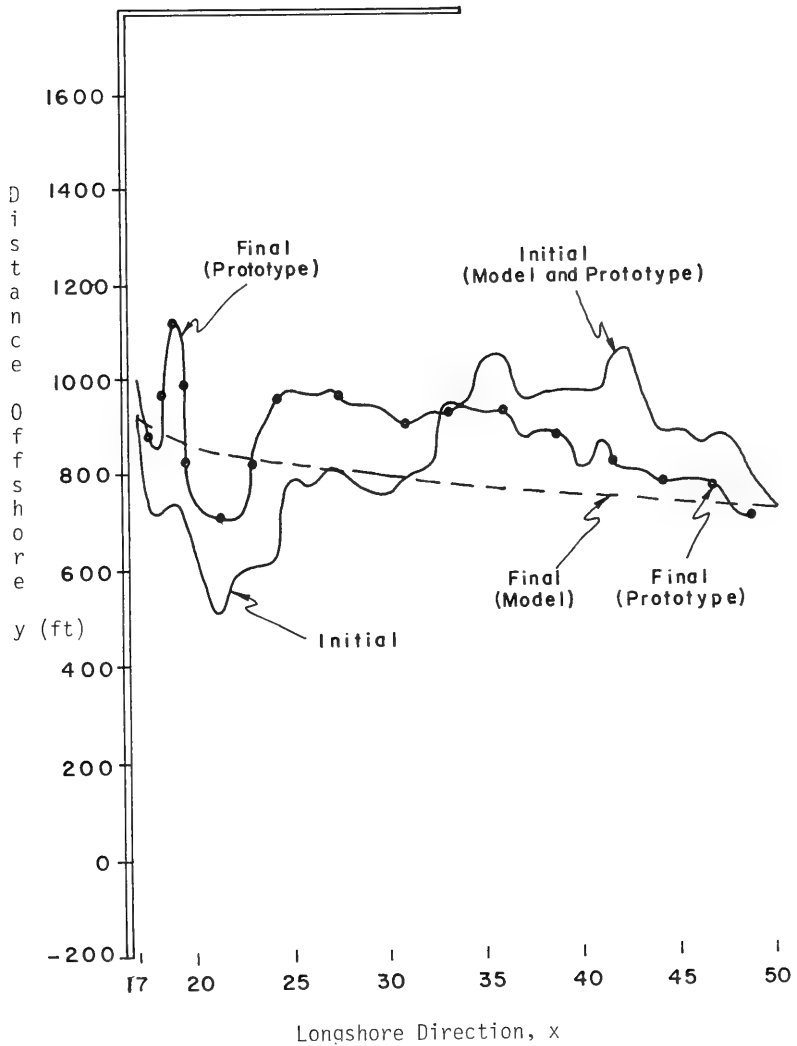


Figure 21. CIH simulation of (JMAX)<sup>th</sup> contour, 20 April - 1 December 1976 (from LEO data).

could be accomplished with minimum effort. Therefore, if a more suitable equation becomes available, the change of a subroutine should be sufficient for implementation of the equation.

Although the model is limited by the omission of the aforementioned parameters, it is reasonably correct. The ability to simulate various physical situations (shore-perpendicular structures, beach fills, breakwater and shore-perpendicular structures) has been demonstrated. In the CIH simulation where the data were first transformed to monotonically decreasing contours and LEO wave data were used, the model still predicts the prototype shoreline changes in a reasonable fashion.

Further research and model development should include exercising the model in a number of different situations. Several theoretical cases should be simulated, which if analyzed properly, would provide a tool for the coastal engineer. Combined refraction and diffraction should be included, if possible, along with any of the aforementioned parameters which have been omitted and for which relationships exist. Perhaps the most difficult problem to researchers working on modeling sediment transport in the vicinity of structures is the availability of field data. High-quality concurrent wave and bathymetric change data in the vicinity of coastal structures do not exist. One suggested field experiment is to monitor changes both updrift and downdrift of a jettied inlet which has a bypassing plant. Monitoring should begin immediately after bypassing, when the profiles are out of equilibrium. The recorded bathymetric and wave data would then provide data with which to calibrate, verify, and evaluate the existing models.

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## APPENDIX A

### DISCUSSION OF CONSTANTS AND SOME OF THE VARIABLES REQUIRED BY THE MODEL

Establishing the grid-contour system requires several variables. IMAX represents the number of cross-shore grid lines desired and JMAX the number of contours simulated. DX represents the spacing between the IMAX grid lines and DY the spacing between the contours. DX is a value which must be chosen along with IMAX and JMAX such that sufficient detail is obtained where necessary (e.g., in the shadow zone, if diffraction effects are believed to be very important, DX must be assigned a sufficiently small value so that at least some points lie within the shadow zone for the larger wave angles). DY is not a constant, but a dimensional array which is computed by the model according to the contour location. Once the depths of contours to be modeled are chosen, the initialization of DY and the y values are computed with the following equation after Dean, 1977

$$h = A y^{2/3} \quad (A-1)$$

where h is the depth, y is the offshore distance and A is the scaling parameter Dean gives values for A for several diameter sediments; however, if long-term beach profiles are available for the site being modeled, the modeler may want to choose a slightly different A value to more closely match the site-specific beach profile. Figure A-1 presents values of A versus diameter (after Moore, 1982). The model is programmed to input the h(I,J) values (depths as shown in Figure 1, called DEEP (I,J) in the program) read in the value of A (called ADEAN in program) and it then computes the y values. Also shown in Figure 1 is the height of the berm (BERM) and this value, along with the beach-face slope (SFACE), is required as program input and can be obtained from beach profile site data. Because the model does not include water level fluctuations such as tides, all values are to be referenced to a chosen datum. Other geometrical constants depending on the site include SJETTY (the length of the jetty), MMAX (the number of structures to be input), and IJET (M), M = 1,2,...MMAX (the smaller I value adjacent to the M<sup>th</sup> structure's location). If no structure is required, as in a beach fill, the value of SJETTY must be entered as 0.0, with MMAX and IJET (M) entered as 1 and (IMAX/2), respectively. As set up presently, the groin locations must be equally spaced.

One constant used throughout the program is the breaking wave criteria (CAPPA in the program) equal to 0.78. It is required in several different computations and always governs the maximum wave height allowed according to the depth.

Another group of variables assigned values within the program is the sediment and fluid properties. These include fluid mass density, sediment mass density, porosity, and the angle of repose (e.g., RHO = 1.99, RHOS = 5.14, POROS = 0.40, and REPOSE = 32°, respectively). The values can easily be changed to reflect site conditions.

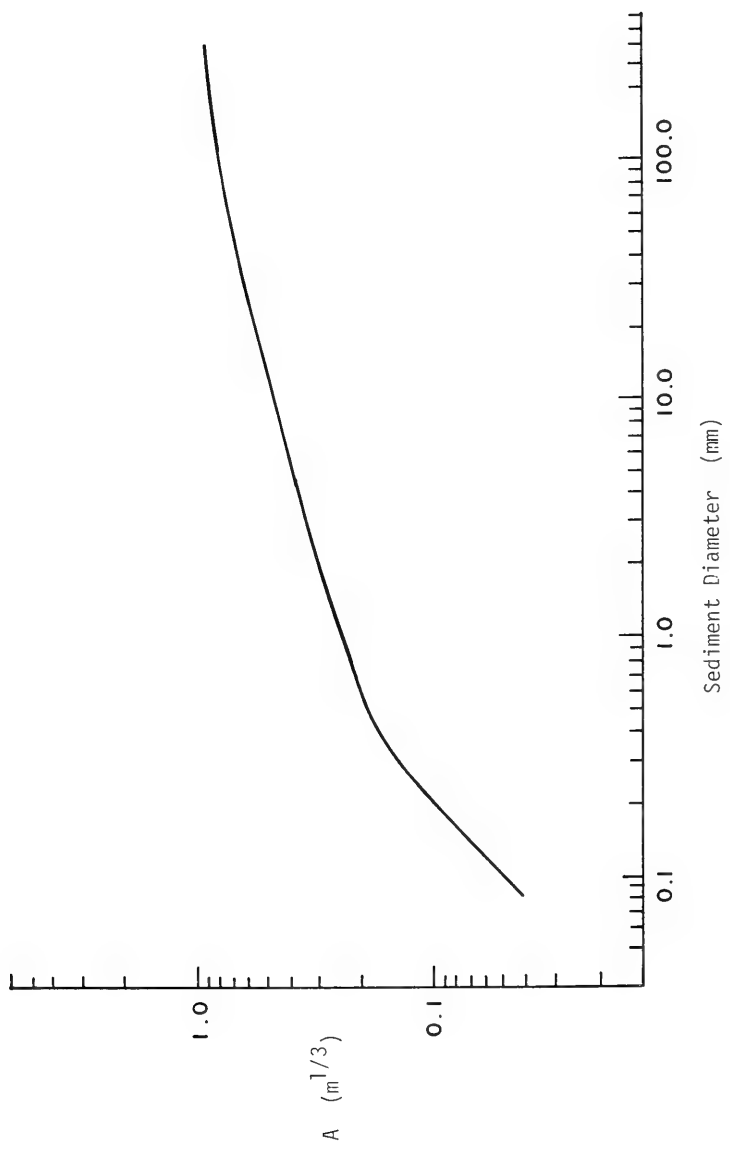


Figure A-1. A versus sediment diameter (after Moore, 1982).

Another very important set of constants is the constant chosen for the longshore and cross-shore components of sediment transport. Equation (27), the total longshore transport equation, contains the constant C' equal to

$$C' = \frac{K \rho_s (g)^{1/2}}{(\rho_s - \rho) (1 - p) (16) (\kappa)^{1/2}} \quad (A-2)$$

where

- K = 0.77 (Komar and Inman, 1970)
- g is the acceleration of gravity (32.17 ft/sec<sup>2</sup>)
- $\rho_s$  and  $\rho$  are the mass densities of the sediment and the seawater (5.14 and 1.99 slugs per cubic feet, respectively)
- p is the porosity (0.40), and
- $\kappa$  is taken as 0.78.

Using these values to compute C' (TKSI in the program), a value of 0.325 is obtained. It is stressed that if any of these values are different for the site to be modeled, they should be changed and the program will compute another value for C'.

The parameter C<sub>OFF</sub> is an "activity factor" which, based on earlier work primarily within the surf zone, was found to be

$$C_{OFF} = 10^{-5} \text{ ft/s,} \quad h < h_b$$

To generalize this concept for transport seaward of the surf zone, the wave energy dissipation per unit volume was utilized as a measure of mobilization of the bottom sediment. Inside the surf zone, the dominant wave energy dissipation is caused by wave breaking; outside the surf zone, the dominant mode of wave energy dissipation is due to bottom friction. These two components will be denoted by D<sub>1</sub> and D<sub>2</sub>, respectively.

(a) Energy Dissipation by Wave Breaking. The wave energy dissipation per unit volume by wave breaking, D<sub>1</sub>, is

$$D_1 = \frac{1}{h} \frac{\partial}{\partial y} (E C_G) \quad (A-3)$$

which, employing the spilling breaker assumption (H =  $\kappa h$ ) within the surf zone, can be shown to be

$$D_1 = \frac{5}{16} \rho g^{3/2} \kappa^2 h^{1/2} \frac{\partial h}{\partial y} \quad (A-4)$$

or

$$D_1 = \frac{5}{24} \rho g^{3/2} \kappa^2 A^{3/2} \quad (A-5)$$

in which A is the scale parameter in the equilibrium beach profile

$$h(y) = A y^{2/3} \quad (A-6)$$

(b) Energy Dissipation by Bottom Friction. The wave energy dissipation per unit volume due to bottom friction,  $D_2$ , is

$$D_2 = \frac{1}{h} \tau u_b = \frac{1}{h} \rho C_f \overline{|u_b| u_b^2} \quad (A-7)$$

in which  $C_f$  is a bottom friction coefficient,  $u_b$  is the bottom water particle velocity and the overbar indicates a time average. For linear waves, equation (A-7) can be reduced to

$$D_2 = \frac{1}{6\pi} \frac{\rho}{h} C_f \frac{H_c^3}{\sinh^3 kh} \quad (A-8)$$

The activity coefficient  $C_{OFF}$ , outside the surf zone, is expressed as

$$C_{OFF} = \frac{1}{\Gamma} \frac{D_2}{D_1} \times 10^{-5} \text{ ft/s}, \quad h > h_b \quad (A-9)$$

$$C_{OFF} = \frac{4}{5\Gamma} \frac{C_f \sigma^3}{g^{3/2} \kappa^2 A^{3/2} h} \left( \frac{H}{\sinh kh} \right)^3 \times 10^{-5} \quad (A-10)$$

in which  $\Gamma$  is a parameter relating the efficiency with which breaking wave energy (which occurs primarily near the water surface) mobilizes the sediment bottom ( $0 < \Gamma \leq 1$ ). Herein,  $\Gamma$  is taken to be one.

Figure A-2 presents an example of the variation of the activity coefficient versus relative depth for a particular wave period and deep water wave height. It is seen that the activity coefficient reduces rapidly with increasing depth.

The value of  $C_{OFF}$  for the physical modeling of Savage's (1959) data was taken as  $10^{-4}$  feet per second. Perlin (1978) presents some rationale for choosing a value of  $C_{OFF}$ ; however, very little testing has been done and none is based on actual field measurement.

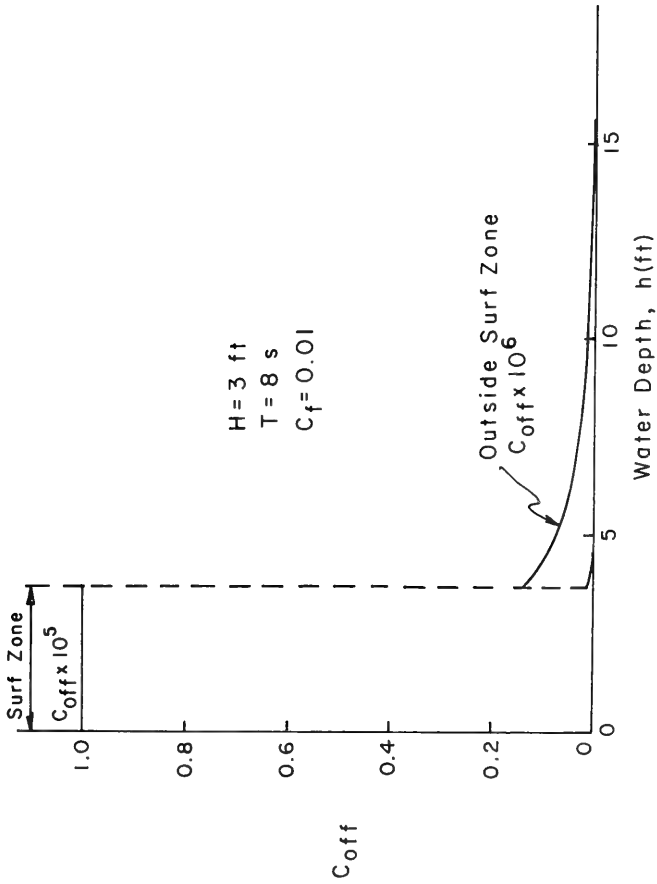


Figure A-2. Example of activity coefficient,  $C_{off}$  versus water depth,  $h$ , for particular wave conditions.

Finally, wave data are read into the program and the simulation begins. (For information regarding "Read Formats" for the various constants and variables, see Appendix E). Wave data required are wave height, wave period, wave angle relative to the x-axis of the model at a depth, WDEPTH and the duration of the wave climate (HS, T, ALPWIS, and a combination of NTIMES x DELT, respectively, in the model). As is always the case with numerical models, the time step and space steps are very important to both stability and accuracy. Time steps on the order of 3 to 6 hours (10,800 to 21,600 seconds) or less are recommended. However, the complexity of the bathymetry, variation and time series of the wave data, constants used (especially C<sub>OFF</sub>) along with several other factors, greatly influences the stability and accuracy of the results.

Table A-1 lists several of the important variables in the computer program.

Table A-1. List of important variables in the program

---

ABAND	The input banded matrix which stores the values from equation (37)
ADEAN	The value of the scaling parameter in the equilibrium beach profile
ALPHAS	The angle a contour makes with the x-direction base line (counter-clockwise is positive)
ALPWIS	The angle (-90° to +90°) the wave crest makes with the x-direction (counter-clockwise is positive)
AMP	The amplitude of the diffracted wave in the shadow zone
ANGGEN	The wave angle at a depth, WDEPTH
ANGLOC	The local contour orientation angle
AWARE	See equations (36) and (37)
BERM	The height of the berm above water level
BMATRIX	The matrix which, upon solution of the banded matrix problem yields the new y values
C	The wave celerity
CAPPA	The breaking wave index
CC	Constant which establishes the width of the distribution of sediment transport across the surf zone
CG	The group velocity throughout the wave field
CGEN	The linear wave theory celerity at a depth, WDEPTH

CGGEN	The linear wave theory group velocity at a depth, WDEPTH
CO	The deepwater, linear wave theory wave celerity
COFF	The onshore-offshore transport rate coefficient within the surf zone
CONST	The constant in the longshore sediment transport relationship (0.77)
CONST6	The space step, DX, multiplied by the activity coefficient
DEEP	The water depth at any grid location
DEEPB	The initial breaking depth along each profile (between adjacent profiles)
DEEPBI	The initial breaking depth along each profile (at each profile, rather than between them)
DELT	The time-step in seconds (DELT x NTIMES = wave condition duration)
DIAM	The mean diameter of the sediment particles
DISTR	See equations (36) and (37)
DX	The alongshore space-step in the x-direction (distance between I values)
DY	The onshore-offshore space-step in the y-direction as defined by the stepped profile
ELO	The deepwater, linear wave theory wavelength
ELTIP	The wavelength at the tip of the structure
EPS	The change in the wave number which is acceptably small
G	The acceleration of gravity (32.17 feet/second <sup>2</sup> )
GAMMA	The specific weight of seawater
H	The wave height throughout the wave field
HB	The maximum wave height which could exist throughout the wave field (where $H = 0.78 * h$ )
HBI	The initial breaking wave height along any profile at the y values rather than between them
HBQ	The initial breaking wave height along any profile, between adjacent profiles

HGEN	Average wave height at a depth, WDEPTH
HS	The significant wave height input
I	The longshore grid location
IBREAK	The leeward side of the initial breaker location J value
IJET	Represents the lesser I value adjacent to the structure (these must be evenly spaced alongshore)
IMAX	The total number of grid points in the x-direction (alongshore)
J	The offshore contour location
JMAX	The value of the seawardmost contour simulated
JUSE	(JMAX + 2) the seawardmost contour at which the wave field is calculated
J1	Landward contour of refraction zone
J2	Seaward contour of refraction zone
J1REF	Landward J values of boundary of refraction zone
J2REF	Seaward J values of boundary of refraction zone
MMAX	The number of shore-perpendicular structures to be simulated (present maximum of 16)
NITER	The counterindex in the refraction routine
NTIME	The counterindex in the time simulation "D0" loop
NTIMES	The number of iterations of time-step, DELT, for which a particular wave is simulated
NUNIV	The total number of time-steps simulated at any time
PI	The value of $\pi = 3.141592654$
POROS	The porosity of the sediment
QX	The longshore sediment transport rate at a specific location
QXTOT	The total alongshore sediment transport rate due to the height and angle of the initial breaking wave
QY	The onshore-offshore sediment transport rate at a specific location
R	See equations (36) and (37)



REPOSE	The angle of repose of the sediment
RHO	The mass density of seawater
RHOND	The dimensionless distance from the tip of structure where diffraction is initiated
RHOS	The mass density of sediment
RK	The wave number
S3	See equations (36) and (37)
SFACE	The slope of the shoreface
SJETTY	The length of the shore-perpendicular structure (from the base line)
SIGMA	The wave radian frequency
T	The wave period
TAU	The dissipative interface parameter
THETA	The wave angle throughout the wave field
THEATO	The wave angle at the tip of the structure
TKSI	The longshore sediment transport rate coefficient
TWOPI	Twice the value of $\pi$
U	See equations (36) and (37)
UCRIT	The critical velocity required to move the sediment according to the Sheid's diagram
V	See equations (36) and (37)
WDEPTH	The depth of water in meters to which the input wave conditions are to be transformed
WEQ	The equilibrium profile distance between contours as defined by the stepped profile
XCOOR	The x-coordinate where the wave field is to be calculated. Together with YCOOR, they determine whether the position is within or beyond the diffraction shadow zone
XDISTN	The location of the structure along the shoreline in feet
Y	The distance offshore to the contours

YCOOR      The y-coordinate where the wave field is to be calculated.  
            Together with XCOOR, they determine whether the position is within  
            or beyond the diffraction shadow zone

YDISS      The value of y after the use of the dissipative interface

YOLD        The previous value of y

YZERO      The berm contour location

Z1          See equation (37)

Z2          See equation (37)

APPENDIX B  
PROGRAM LISTING

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100 C* ***** PROGRAM IMPLICIT SEDTRAN
200 C*THIS PROGRAM IS SET-UP TO HANDLE MULTIPLE GROINS(M<=10).
300 COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
400 COMMON/AA/YZERO(60)
500 COMMON/BB/WEQ(60,20)
600 COMMON/B/ THETA(60,20),QXTOT(60), OLDANG(60,20), DY(60,20)
700 COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
800 COMMON/N USED/JUSE,T,CO,CGEN,CGGEN,ANGGEN,DX,BERM,THETA0(10),MMAX
900 COMMON/D/SIGMA,G,ELD,JMAX,IMAX,PI,TWOPI,PI02,HGEN,IJET(10),SJETTY
1000 COMMON/F/ADEAN,REPOSE,DIAM
1100 COMMON/AAA/DELT,NTIMES
1200 COMMON/COUNT/NUNIV
1300 COMMON/EXPL/QYEXP(60,20),YIMP(60,20)
1400 DIMENSION CHANGE(20),HC(10),TC(10)
1500 DIMENSION YORIG(60,20),YZEROD(60),SANGLE(20)
1600 NUNIV=0
1700 JMAX=8
1800 JUSE=JMAX+2
1900 IMAX=50
2000 PI=3.141592654
2100 TWOPI=PI*2.
2200 PI02=PI/2.0
2300 REPOSE=32.*TWOPI/360.
2400 WRITE(6,732)
2500 732 FORMAT('*****')
2600 WRITE(6,733)
2700 733 FORMAT(2X,'TO WHAT DEPTH ARE THE WAVES TO BE TRANSFORMED')
2800 C*WDEPTH MUST BE A DEPTH BEYOND THE END OF THE STRUCT, PREFERABLY AT
2900 C**DEEP(JMAX) OR GREATER(OR ELSE SNELL'S LAW OR SHOAL COULD BLOWUP IN
3000 C***DEEPER WATER. IT'S IN METERS HERE!
3100 READ(5,770) WDEPTH
3200 770 FORMAT(10X,F10.3)
3300 WDEPTH=WDEPTH*3.28084
3400 WRITE(6,762) WDEPTH
3500 762 FORMAT(2X,"THE DEPTH (IN FT) WAVES TRANSFORMED TO, WDEPTH= ",
3600 * F10.3)
3700 WRITE(6,732)
3800 WRITE(6,777)
3900 777 FORMAT(2X,"ITS TIME FOR SJETTY, BERM, SFACE, AND DIAM",/)
4000 C*SJETTY MUST BE MUCH LESS THAN Y(I,JMAX).
4100 READ(5,776) SJETTY,BERM,SFACE,DIAM
4200 776 FORMAT(2F10.3,F10.4,F10.3)
4300 WRITE(6,761) SJETTY
4400 761 FORMAT(2X,'THE LENGTH OF THE STRUCTURE, SJETTY= ',F10.3)
4500 WRITE(6,740) BERM
4600 740 FORMAT(2X,'THE HEIGHT OF THE BERM, BERM= ',F10.3)
4700 WRITE(6,739)SFACE
4800 739 FORMAT(2X,'THE SLOPE OF THE BEACH FACE, SFACE= ',F10.4)
4900 WRITE(6,738) DIAM
5000 738 FORMAT(2X,'THE SEDIMENT DIAMETER, DIAM= ',F10.3)
5100 WRITE(6,732)
5200 780 FORMAT(2X,'SUPPLY MMAX( THE NO. OF GROINS) AND THEIR I-LOC',/)
5300 UCRIT=16.3*SQRT(DIAM*0.00328)
5400 C*THE NO. OF MULTIPLE GROINS,MMAX MUST BE GIVEN THEIR X LOCATIONS.
5500 READ(5,779) MMAX
5600 779 FORMAT(I3)
5700 DD 760 M=1,MMAX
5800 C*IJET REPS LESSER I-VALUE ADJACENT TO STRUCTURE.
5900 760 READ(5,779) IJET(M)
6000 WRITE(6,759) (M,IJET(M),M=1,MMAX)
6100 759 FORMAT(2X,'THE NUMBER',I5,' GROIN IS LOCATED AT GRID',I5)
6200 WRITE(6,732)
6300 C*CONVERT TO RADIANS.
6400 C*FIRST MUST GIVE Y COORS POSITIONS AND DEPTHS.
6500 C*FIRST, MUST SET UP ALL OF THE DEEP-VALUES.
6600 WRITE(6,773)
6700 773 FORMAT(2X,"NOW ENTER THE VALUE OF ADEAN")
6800 READ(5,774)ADEAN
6900 774 FORMAT(F10.4)
7000 WRITE(6,749) ADEAN
7100 749 FORMAT(2X,'THE VALUE OF ADEAN= ',F10.4,' IN THE EQ. H=AY**2/3')
7200 WRITE(6,732)

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7300      WRITE(6,772)
7400      772 FORMAT(2X,"READ IN THE SPACE STEP,TIMESTEP",/)
7500      READ(5,775)   DX,DELTA
7600      775 FORMAT(2(F10.3))
7700      WRITE(6,737)   DX
7800      737 FORMAT(2X,'THE VALUE OF THE LONGSHORE SPACE-STEP, DX= ',F10.3)
7900      WRITE(6,736)   DELT
8000      736 FORMAT(2X,'THE TIME-STEP IN SECONDS, DELT= ',F10.3)
8100      DATA CHANGE/1.,2.,3.,5.,7.,11.,14.,17.,25.,32.808,10*0.0/
8200      DO 220 J=1,JMAX+2
8300      DO 220 I=1,IMAX
8400      220 DEEP(I,J)=CHANGE(J)
8500      DATA(HC(I),I=1,8)/1.87,0.5,0.35,.25,.21,.20,.19,.19/
8600      DATA(TC(I),I=1,8)/2.,3.,4.,6.,8.,10.,12.,14./
8700      DO 200 J=1,JMAX+2
8800      DO 200 I=1,IMAX
8900      200 Y(I,J+1)=(0.5*(DEEP(I,J+1)+DEEP(I,J)))/ADEAN)**1.5+Y(I,1)
9000      WRITE(6,732)
9100      C*****
9200      C*WE WILL ALWAYS REQUIRE Y(I,JMAX+2) TO COMPUTE DY AND YBAR.
9300      C*WE WILL ALWAYS REQUIRE DEEP(I,JMAX+2) TO COMP SEDIMENT TRANSPORT.
9400      C*****
9500      WRITE(6,734)
9600      734 FORMAT(2X,'THE BOUNDARY Y-VALUES, I=1,IMAX ARE AS FOLLOWS',/)
9700      WRITE(6,801)   (Y(1,J),J=1,JMAX+2)
9800      WRITE(6,801)   (Y(IMAX,J),J=1,JMAX+2)
9900      WRITE(6,732)
10000     WRITE(6,735)
10100     735 FORMAT(/,2X,'THE DEPTHS BETWEEN CONTOURS ARE AS FOLLOWS',/)
10200     WRITE(6,801)   (DEEP(1,J),J=1,JMAX+2)
10300     WRITE(6,732)
10400     801 FORMAT(2X,10(F8.2))
10500     DO 2 I=1,IMAX
10600     2 YZERO(I)=Y(I,1)-(BERM/SFACE)
10700     C*WILL COMPUTE THE EQUIL WIDTH BETWEEN CONTOURS, HERE.
10800     DO 1 I=1,IMAX
10900     WEQ(I,1)=Y(I,1)-YZERO(I)
11000     DO 1 J=1,JMAX
11100     IF(J.NE.1) GO TO 32
11200     YTEMP1=0.0
11300     GO TO 33
11400     32 YTEMP1=((0.5*(DEEP(I,J-1)+DEEP(I,J)))/ADEAN)**1.5
11500     33 YTEMP2=((0.5*(DEEP(I,J)+DEEP(I,J+1)))/ADEAN)**1.5
11600     WEQ(I,J+1)=YTEMP2-YTEMP1
11700     1 CONTINUE
11800     C*LET'S STORE THE ORIG VALUES TO COMPUTE VOL CHANGES OVER CONTOURS,LATER
11900     DO 796 I=1,IMAX+1
12000     YZERO0(I)=YZERO(I)
12100     DO 796 J=1,JMAX+2
12200     796 YORIG(I,J)=Y(I,J)
12300     C*****
12400     C*READ THE DISK FILE AND TRANSFORM PARAMETERS INTO MY UNITS.
12500     C*****
12600     C*ALL ADJUSTMENTS TO WAVE ANGLE,HEIGHT,CELERITY,GROUP VEL, WILL BE MADE
12700     C**HERE, AND THRUOUT THE REST OF THE PROG, THEY WILL BE AS IF OCCURRED
12800     C**AT WDEPTH!
12900     798 READ(5,799,END=1000) HS,T,ALPWIS
13000     799 FORMAT(10X,3F6.1)
13100     NTIMES=1
13200     NCHECK=NUNIV+NTIMES
13300     HGEN=0.707107*HS
13400     SIGMA=TWOP/1/T
13500     G=32.17
13600     CO=G*T/TWOP
13700     ELO=CO*T
13800     IF(T.LE.2.0) GO TO 797
13900     HCC=0.23
14000     DO 444 I=2,7
14100     T2=TC(I)
14200     IF(T.GT.T2) GO TO 444
14300     T1=TC(I-1)
14400     DELTAT=T2-T1

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14500      DT=(T-T1)/DELTA
14600      DTT=(T2-T)/DELT
14700      HCC=HC(I)*DT+HC(I-1)*DTT
14800      GO TO 446
14900      444 CONTINUE
15000      446 CONTINUE
15100      IF(HGEN.LT.HCC) GO TO 797
15200      ANGEN=ALPWIS*WFOPI/360.
15300      C*****
15400      CALL WVNUM(WDEPTH,T,DUMKK)
15500      C*ANGGEN,HGEN,CGEN,CGEN REPRESENT THE WAVE ANGLE,HEIGHT,CCELERITY AND
15600      C**GROUP VEL(RESPECT.) OF THE SPECIFIED WAVE INPUT AT A DEPTH, WDEPTH
15700      CALL WVNUM(11.0,T,DUMKKK)
15800      C11=WFOPI/(T*DUMKKK)
15900      CG11=0.5*C11*(1.+(2.*DUMKKK*11.0/SINH(2.*DUMKKK*11.0)))
16000      CGEN=WFOPI/(T*DUMKKK)
16100      CGGEN=0.5*CGEN*(1.+(2.*DUMKK*WDEPTH/SINH(2.*DUMKK*WDEPTH)))
16200      CALL TRANS
16300      797 IF(NCHECK.NE.NUNIV) NUNIV=NCHECK
16400      709 GO TO 798
16500      1000 CONTINUE
16600      STOP
16700      END
16800      C*****
16900      SUBROUTINE TRANS
17000      C*THIS SUBROUTINE WILL COMPUTE SEDIMENT TRANSPORT
17100      COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
17200      COMMON/AA/YZERO(60)
17300      COMMON/BB/WEQ(60,20)
17400      COMMON/B/ THETA(60,20),QXTOT(60), OLDANG(60,20), DY(60,20)
17500      COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
17600      COMMON/N USED/JUSE,T,CD,CGEN,CGEN,ANGGEN,DX,BERM,THETA0(10),MMAX
17700      COMMON/D/SIGMA,G,ELD,JMAX,IMAX,PI,WFOPI,PI02,HGEN,IJET(10),SJETTY
17800      COMMON/E/RHO,RHOS,POROS,CONST,TKSI
17900      COMMON/F/ADEAN,REPOSE,DIAM
18000      COMMON/G/IBREAK(60),HNONBR(20)
18100      COMMON/P/HBQ(60),DEEPB(60)
18200      COMMON/ZZZ/NTIME
18300      COMMON/AAA/DELT,NTIMES
18400      COMMON/COUNT/NUNIV
18500      DIMENSION YOLD(60,20),R(60,20),S(60,20),HC(60,20),QY(60,20),YDISS(
18600      * 60,20)
18700      DIMENSION RHS1(60,20),S3(60,20),THETAB(60,20),ANGLOC(60,20)
18800      DIMENSION DISTR(60,20),AWARE(60,20)
18900      C*****
19000      C*****
19100      C***** NOTE : SIZE OF ABAND AND XL HAVE TO BE CHANGED
19200      C***** ACCORDING TO JMAX+1+JMAX AND JMAX+1,RESPECT.
19300      C***** CHANGE REQ'D AT 7040 AND 18650
19400      C*****
19500      * ),BMATRX(432),ABAND(432.19),QX(60,20),XL(432,10),CONST6(60,20)
19600      COMMON/MP/ RKB(60),HBI(60),DEEPBI(60)
19700      COMMON/EXPL/QYEXP(60,20),YIMP(60,20)
19800      DIMENSION SANGLE(20)
19900      C*LET'S ZERO-OUT ALL OF THE DIMENSIONED MATRICES.
20000      DO 1000 J=1,JMAX+2
20100      SANGLE(J)=0.0
20200      DO 1000 I=1,IMAX+2
20300      YOLD(I,J)=0.0
20400      R(I,J)=0.0
20500      S(I,J)=0.0
20600      HC(I,J)=0.0
20700      QY(I,J)=0.0
20800      YDISS(I,J)=0.0
20900      RHS1(I,J)=0.0
21000      S3(I,J)=0.0
21100      THETAB(I,J)=0.0
21200      ANGLOC(I,J)=0.0
21300      DISTR(I,J)=0.0
21400      AWARE(I,J)=0.0
21500      QX(I,J)=0.0
21600      CONST6(I,J)=0.0

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21700      1000 CONTINUE
21800      RHO=1.99
21900      RHOS=5.14
22000      POROS=0.40
22100      CONST=0.77
22200      CAPPA=0.78
22300      TAU=0.25
22400      TKSI=(CONST*RHO*SQRT(G))/((RHOS-RHO)*(1.0-POROS))*16.0*SQRT(CAPPA)
22500 C* QX(I,J) IS THE TRANSPORT BETWEEN THE (I,J+1) AND (I,J) CONTOURS.
22600 C*THE 'DO 1 LOOP' SIMULATES TIME---TIME=DELTA*NTIMES.
22700      COFF=0.00001
22800      GAMMA=RHO*G
22900      DO 1 NTIME=1,NTIMES
23000      NUNIV=NUNIV+1
23100 C*THE MATRICES ABAND AND BMATRX MUST BE "ZEROED OUT"
23200      K=0
23300      DO 26 I=2,IMAX-1
23400      DO 26 J=1,JMAX
23500      K=K+1
23600      BMATRX(K)=0.0
23700      DO 26 L=1,JMAX+1+JMAX
23800      26 ABAND(K,L)=0.0
23900      XNTIME=1.0*(NTIME)
24000      CALL PREDIF
24100 C*SMOOTHING OF THE WAVE ANGLE,THETA, IS RE'D TO ACCT FOR DIFF EFFECTS.
24200      CALL SMOOTH(THETA,IMAX,JMAX,IJET,SJETTY,MMAX,Y)
24300      CALL QTRAN
24400 C*FIRST THE LONGSHORE SEDIMENT TRANSPORT WILL BE DISTRIBUTED
24500 C***ACROSS THE SURF ZONE...
24600      CC=1.25
24700 C***QX(I,J) WILL BE DETERMINED BY SUBTRACTING FROM THE INTEGRAL
24800 C**OF QX FROM DEEP(I,J-1) TO INFINITY, THE INTEGRAL OF QX FROM DEEP(I,J)
24900 C***TO INFINITY. IN THIS WAY THE SEDIMENT TRANS FROM JMAX OUT BEES
25000 C***INCLUDED IN QX(I,JMAX). TO INCLUDE THE SWASH TRANS, WHEN J=1
25100 C*WE WILL SUBTRACT FROM 2 TO INFINITY FROM 1.0
25200 C*LOOP FOR VALUES WHICH ARE HELD CONST AND STORED.
25300      THETAB(1,1)=0.5*(THETA(1,1)+0.0)
25400      R(1,1)=0.5/(DX*(DEEP(1,1)+BERM/2.))
25500      DO 290 I=2,IMAX
25600      R(I,1)=0.5/(DX*(DEEP(I,1)+BERM/2.))
25700 C* THETAB(I,1)=0.25*(THETA(I,1)+THETA(I-1,1)+0.0.)
25800      THETAB(I,1)=0.5*(THETA(I,1)+THETA(I-1,1))
25900 C*NO NEED TO COMPUTE PROP ANGLE AT STRUCTS BECAUSE QX =0.0 AT IJET(M)+1
26000      ANGLC(I,1)=ATAN((Y(I,1)-Y(I-1,1))/DX)
26100 C*HBQ(IJET(M)+1) IS PROPERLY SET IN THE SUBROUTINE QTRAN.
26200      DISTR(I,1)=1.0-EXP(-(DEEP(I,1)**1.5+HBQ(I)*ADEAN**1.5)/
26300      * ((C*DEEPB(I)**1.5)**3))
26400      DISTR(I,1)=DISTR(I,1)*TKSI*HBQ(I)**2.5
26500      DO 290 J=2,JMAX
26600      R(I,J)=0.5/(DX*(DEEP(I,J)-DEEP(I,J-1)))
26700      THETAB(I,J)=0.5*(THETA(I,J)+THETA(I-1,J))
26800      ANGLC(I,J)=ATAN((Y(I,J)-Y(I-1,J))/DX)
26900      DISTR(I,J)=EXP(-(DEEP(I,J-1)**1.5+HBQ(I)*ADEAN**1.5)/(C*DEEPB(I)
27000      * **1.5)**3)-EXP(-(DEEP(I,J)**1.5+HBQ(I)*ADEAN**1.5)/(C*
27100      * DEEPB(I)**1.5)**3))
27200      DISTR(I,J)=DISTR(I,J)*TKSI*HBQ(I)**2.5
27300      290 CONTINUE
27400      DO 301 J=1,JMAX
27500      DO 301 I=2,IMAX
27600      AWARE(I,J)=DELTA*R(I,J)*(QX(I,J)-QX(I+1,J)+QY(I,J)-QY(I,J+1))+Y(I,J)
27700      * )
27800      S1=2.*SIN(THETAB(I,J))*COS(THETAB(I,J))*(-1.+2.*COS(
27900      * ANGLC(I,J)))**2)
28000      S2=COS(2.*THETAB(I,J))*COS(ANGLC(I,J))/(SQRT(DX**2+
28100      * (Y(I,J)-Y(I-1,J))**2))
28200      S3(I,J)=S2*DISTR(I,J)
28300      IF(SJETTY.EQ.0.0) GO TO 302
28400      DO 325 M=1,MMAX
28500      IF(I.NE.IJET(M)+1) GO TO 325
28600      IF(THETA(M).GE.0.0) ISIDE=IJET(M)
28700      IF(THETA(M).LT.0.0) ISIDE=IJET(M)+1
28800      YSEA=0.5*(Y(ISIDE,J)+Y(ISIDE,J+1))
28900      YSHORE=0.5*(Y(ISIDE,J)+Y(ISIDE,J-1))

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29000      IF(YSEA.GT.SJETTY.AND.YSHORE.GT.SJETTY)   GO TO 302
29100      IF(YSEA.GT.SJETTY.AND.YSHORE.LE.SJETTY)   GO TO 298
29200 C*BECAUSE A NO FLOW B.C. IS USED ALONG THE STRUCT, NO ATTN WAS PAID
29300 C**TO GETTING PROPER VALUES OF ANGLLOC, THETAB,DISTR,ETC.
29400      S3(I,J)=0.0
29500      DISTR(I,J)=0.0
29600      GO TO 302
29700      325 CONTINUE
29800      GO TO 302
29900 C***ABOVE, ALL PARAMETERS(I.E.,S1,S2,S3,THETAB,DISTR,ANGLLOC)
30000 C***ARE COMPUTED AS IF THE STRUCT IS NOT THERE. THE B.C. AT THE
30100 C***STRUCT TIP ASSUMES QX COMPUTED AS IF NO STRUCT PRESENT AND THEN
30200 C***BYPASSES ACCORDING TO "RATIO".
30300      298 RATIO=(YSEA-SJETTY)/(YSEA-YSHORE)
30400      S3(I,J)=S3(I,J)*RATIO
30500      DISTR(I,J)=DISTR(I,J)*RATIO
30600      302 RHS1(I,J)=DISTR(I,J)*S1-S3(I,J)*(Y(I,J)-Y(I-1,J))
30700      301 CONTINUE
30800      CALL BREAK(IMAX,JMAX)
30900 C*TO DETERMINE DECAY OF CONST6(I,J),NEED WAVE NO. AT BREAKING.
31000      DO 754 I=1,IMAX+1
31100      754 CALL WVNUM(DEEPBI(I),T,RKB(I))
31200 C*USING SHIELD'S DIAG,Y AXIS=0.05 & (TAUO=RHO*C*U**2),GET UCRT(FT/SEC)
31300      UCRT=16.3*SQR(DIAM*.00328)
31400      DO 750 I=1,IMAX+1
31500      CONST6(I,1)=COFF*DX
31600      DO 750 J=2,JMAX+2
31700 C*CONST6(I,J) GOES W/ QY(I,J) WHICH IS ASSOC W/ DEEP(I,J-1)
31800      IF(DEEP(I,J-1).LE.DEEPBI(I))   GO TO 751
31900 C*HERE, MUST CAUSE COFF TO DECAY (WE'RE BEYOND SURF ZONE)
32000      UMAXB=HBI(I)*G*T*RKB(I)/(2.*TWOPI*COSH(RKB(I)*DEEPBI(I)))
32100      UMAX=H(I,J-1)*G*T*RK(I,J-1)/(2.*TWOPI*COSH(RK(I,J-1)*DEEP(I,J-1)))
32200      IF(UCRT.LT.UMAXB.AND.UCRT.LT.UMAXB)   GO TO 749
32300      CONST6(I,J)=0.0
32400      DO 750 J=2,JMAX+2
32500      749 TOP=0.01*H(I,J-1)**3*SIGMA**3/(SINH(RK(I,J-1)*DEEP(I,J-1))**3)
32600      BOT=DEEP(I,J-1)*(0.625*TWOPI*G**1.5*0.78**2*ADEAN**1.5+
32700      *(0.01*HBI(I)**3*SIGMA**3/(DEEPBI(I)*(SINH(RKB(I)*DEEPBI(I))**3)))
32800      CONST6(I,J)=DX*COFF*TOP/BOT
32900      GO TO 750
33000      751 CONST6(I,J)=COFF*DX
33100      750 CONTINUE
33200      K=0
33300 C**PUT INTO BANDED FORM USING THE ALGORITHM A(M,N)->B(M,NN) WHERE
33400 C***NN=KB+1-M+N(KB IS THE NUMBER OF LOWER CODIAGONALS(=JMAX,HERE)).
33500      DO 304 I=2,IMAX-1
33600      DO 304 J=1,JMAX
33700      K=K+1
33800      AWARE(I,J)=AWARE(I,J)+DELT*RHS1(I,J)*R(I,J)-DELT*R(I,J)*RHS1(I+1,J)
33900      * )+DELT*R(I,J)*CONST6(I,J)*WEQ(I,J)-DELT*R(I,J)*CONST6(I,J+1)*
34000      * WEQ(I,J+1)
34100      YDUM=YZERO(I)
34200      IF(J.NE.1)   YDUM=Y(I,J-1)
34300      AWARE(I,J)=AWARE(I,J)+DELT*R(I,J)*CONST6(I,J)*0.5*(YDUM-Y(I,J))
34400      * -DELT*R(I,J)*CONST6(I,J+1)*0.5*(Y(I,J)-Y(I,J+1))
34500      U=DELT*R(I,J)*S3(I,J)
34600      V=DELT*R(I,J)*S3(I+1,J)
34700      Z1=DELT*R(I,J)*CONST6(I,J)*0.5
34800      Z2=DELT*R(I,J)*CONST6(I,J+1)*0.5
34900 C*NOW WILL SET UP THE MATRICES ABAND AND BMATRIX.
35000      ABAND(K,JMAX+1)=1.0+U+V+Z1+Z2
35100      IF(I.NE.2)   GO TO 305
35200      AWARE(I,J)=AWARE(I,J)+U*Y(I-1,J)
35300      GO TO 310
35400      305 ABAND(K,1)=-U
35500      310 IF(I.NE.IMAX-1)   GO TO 306
35600      AWARE(I,J)=AWARE(I,J)+V*Y(IMAX,J)
35700      GO TO 311
35800      306 ABAND(K,JMAX+1+JMAX)=-V
35900      311 IF(J.NE.1)   GO TO 307
36000      ABAND(K,JMAX+1)=ABAND(K,JMAX+1)-Z1
36100      AWARE(I,1)=AWARE(I,1)+Z1*(YZERO(I)-Y(I,1))
36200      GO TO 312

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36300      307 ABAND(K,JMAX)=-Z1
36400      312 IF(J.NE.JMAX) GO TO 308
36500          AWARE(I,J)=AWARE(I,J)+Z2*Y(I,JMAX+1)
36600          GO TO 309
36700      308 ABAND(K,JMAX+2)=-Z2
36800      309 BMATRIX(K)=AWARE(I,J)
36900      304 CONTINUE
37000          KMAX=K
37100      C**CALL IMSL ROUTINE LEQT1B TO SOLVE THE BANDED MATRIX.
37200          CALL LEQT1B(ABAND,KMAX,JMAX,JMAX,432,BMATRIX,1,432,O,XL,IER)
37300      C*NOW, GIVE Y'S THEIR NEW VALUES STORING OLD VALUES IN YOLD.
37400          K=O
37500          DO 315 I=2,IMAX-1
37600              YOLD(I,JMAX+1)=Y(I,JMAX+1)
37700          DO 315 J= 1,JMAX
37800              K=K+1
37900              YOLD(I,J)=Y(I,J)
38000              Y(I,J)=BMATRIX(K)
38100      315 CONTINUE
38200          DO 320 J=1,JMAX+3
38300              YOLD(1,J)=Y(1,J)
38400      320 YOLD(IMAX,J)=Y(IMAX,J)
38500      C*WILL USE ABBOTT'S DISSIPATIVE INTERFACE TO RID HIGH FREQ OSCILLATIONS
38600          DO 650 J=1,JMAX
38700          DO 650 I=2,IMAX-1
38800              YDISS(I,J)=TAU*Y(I-1,J)+(1.-2.*TAU)*Y(I,J)+TAU*Y(I+1,J)
38900              IF(SJETTY.EQ.O.O) GO TO 650
39000          DO 649 M=1,MMAX
39100              IF(I.NE.IJET(M).AND.I.NE.IJET(M)+1) GO TO 649
39200              IF(Y(IJET(M),J).GT.SJETTY.OR.Y(IJET(M)+1,J).GT.SJETTY)GO TO 649
39300              IF(I.EQ.IJET(M))YDISS(I,J)=TAU*Y(I-1,J)+(1.-TAU)*Y(I,J)
39400              IF(I.EQ.(IJET(M)+1))YDISS(I,J)=TAU*Y(I+1,J)+(1.-TAU)*Y(I,J)
39500      649 CONTINUE
39600      650 CONTINUE
39700          DO 651 J=1,JMAX
39800          DO 651 I=2,IMAX-1
39900      651 Y(I,J)=YDISS(I,J)
40000      C*THIS LOOP WILL STORE THE IMPLICIT Y VALUES REQ'D TO COMP QY&QX
40100          DO 40 I=1,IMAX+1
40200          DO 40 J=1,JMAX+3
40300      40 YIMP(I,J)=Y(I,J)
40400      C*THIS LOOP WILL EXPLICITLY MOVE CONTOURS SEAWARD IF REPOSE EXCEEDED.
40500          KOUNT=O
40600          SLOPEM=TAN(O.9*REPOSE)
40700          DO 48 I=1,IMAX
40800      43 KOUNT=KOUNT+1
40900          IF(KOUNT.GT.50000) GO TO 41
41000      C*LET US COMPUTE ALL THE SLOPES(PSLOP) FOR EACH CHANGE IN DEPTH.
41100          DO 47 J=1,JMAX+1
41200          DUM=-BERM/2.O
41300          IF(J.NE.1) DUM=DEEP(I,J-1)
41400          DELH=O.5*(DEEP(I,J+1)+DEEP(I,J))-O.5*(DEEP(I,J)+DUM)
41500          PSLOP=DELH/(Y(I,J+1)-Y(I,J))
41600      47 SANGLE(J)=ATAN(PSLOP)
41700      C*FIND THE MIN NEG SLOPE ANGLE OR THEN THE POS SLOPE>REPOSE OR FORGET IT
41800          ASLOPM=-1.OE5O
41900          ASLOPP=O.O
42000          DO 46 J=1,JMAX+1
42100          IF(SANGLE(J).GT.O.O) GO TO 45
42200          IF(SANGLE(J).GT.ASLOPM)ASLOPM=SANGLE(J)
42300          IF(ASLOPM.EQ.SANGLE(J)) JM=J
42400          GO TO 46
42500      45 IF(SANGLE(J).GT.REPOSE.AND.SANGLE(J).GT.ASLOPP)ASLOPP=SANGLE(J)
42600          IF(ASLOPP.EQ.SANGLE(J)) JP=J
42700      46 CONTINUE
42800          IF(ASLOPM.EQ.-1.OE5O.AND.ASLOPP.EQ.O.O) GO TO 42
42900          IF(ASLOPM.EQ.-1.OE5O) GO TO 44
43000          DUM=-BERM/2.
43100          IF(JM.NE.1) DUM=DEEP(I,JM-1)
43200          ALTER=((O.5/SLOPEM*(DEEP(I,JM+1)-DUM))-(Y(I,JM+1)-Y(I,JM)))/
43300      * (1.O+((DEEP(I,JM+1)-DEEP(I,JM))/(DEEP(I,JM)-DUM)))
43400          Y(I,JM+1)=Y(I,JM+1)+ALTER

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43500      Y(I,JM)=Y(I,JM)-(ALTER*(DEEP(I,JM+1)-DEEP(I,JM))/(DEEP(I,JM)-DUM))
43600      QYEXP(I,JM+1)=QYEXP(I,JM+1)+DX/DELT*ALTER*(DEEP(I,JM+1)-DEEP(I,JM)
43700      *
43800      GO TO 43
43900  144  CONTINUE
44000      DUM=-BERM/2.
44100      IF(JP.NE.1) DUM=DEEP(I,JP-1)
44200      ALTER=(O.5/SLOPE*(DEEP(I,JP+1)-DUM)-(Y(I,JP+1)-Y(I,JP)))/
44300      * (1.O+((DEEP(I,JP+1)-DEEP(I,JP))/(DEEP(I,JP)-DUM)))
44400      Y(I,JP+1)=Y(I,JP+1)+ALTER
44500      Y(I,JP)=Y(I,JP)-(ALTER*(DEEP(I,JP+1)-DEEP(I,JP))/(DEEP(I,JP)-DUM))
44600      QYEXP(I,JP+1)=QYEXP(I,JP+1)+DX/DELT*ALTER*(DEEP(I,JP+1)-DEEP(I,JP)
44700      *
44800      GO TO 43
44900  42  WEQ(I,JMAX+1)=Y(I,JMAX+1)-Y(I,JMAX)
45000  48  CONTINUE
45100  C*IF WE GET SENT HERE, LOOP 444 WILL CATCH THE CROSSED CONTOURS.
45200  41  CONTINUE
45300  C*NOW WE CAN COMPUTE QX'S AND QY'S!
45400      DO 318 I=2,IMAX
45500  C*ALL IMPLIC AND EXPLIC MOVEMENT OF YZERO WILL BE TAKEN CARE OF HERE
45600      QY(I,1)=-BERM*DX*(Y(I,1)-YOLD(I,1))/DELT
45700      YZERO(I)=YZERO(I)+(Y(I,1)-YOLD(I,1))
45800  319  DO 318 J=1,JMAX
45900      QX(I,J)=RHS1(I,J)-S3(I,J)*YIMP(I,J)+S3(I,J)*YIMP(I-1,J)
46000  318  QY(I,J+1)=CONST6(I,J+1)*(O.5*(YIMP(I,J)+YOLD(I,J)-YIMP(I,J+1)
46100      * -YOLD(I,J+1))+WEQ(I,J+1))
46200      DO 323 J=1,JMAX
46300      QX(1,J)=QX(2,J)
46400  323  QX(IMAX+1,J)=QX(IMAX,J)
46500  C*TOTAL QYS WILL BE COMP FROM IMPLIC AND EXPLIC VALUES.THEN ZERO QYEXP
46600      DO 39 I=1,IMAX+1
46700      DO 39 J=1,JMAX+3
46800      QY(I,J)=QY(I,J)+QYEXP(I,J)
46900  39  QYEXP(I,J)=O.O
47000  C*THIS CHECK WILL BOMB THINGS OUT IF CONTOURS HAVE CROSSED.
47100      DO 444 II=1,IMAX
47200      DO 444 JJ=1,JMAX
47300  C*IF CONTOURS CROSS AT ANY TIME WANT PROGRAM TO STOP!
47400      IF(Y(II,JJ).LT.Y(II,JJ+1)) GO TO 444
47500      WRITE(6,103)
47600      WRITE(6,*) NUNIV
47700      DO 150 J=1,JMAX
47800  150  WRITE(6,100) (QX(I,J),I=1,IMAX)
47900      DO 151 J=1,JMAX
48000  151  WRITE(6,101) (QY(I,J),I=1,IMAX)
48100      DO 152 J=1,JMAX
48200  152  WRITE(6,100) (Y(I,J),I=1,IMAX)
48300  103  FORMAT(2X,'THE CONTOURS HAVE CROSSED AND SOMETHING IS WRONG',/)
48400      DO 19 J=1,JMAX
48500  19  WRITE(6,100) (YOLD(I,J),I=1,IMAX)
48600      GO TO 445
48700  444  CONTINUE
48800      WRITE(6,*) NUNIV
48900  C*THE FOLLOWING STATEMENT DETERMINES AT WHAT FREQ EVERYTHING IS WRITTEN!
49000      IF(MOD(NUNIV,10).NE.O) GO TO 1
49100  C*LET'S WRITE ALL OF IT OUT.
49200      WRITE(6,926) NUNIV
49300  926  FORMAT(2X,'THE TOTAL ELAPSED NUMBER OF TIME-STEPS. NUNIV= ',I5,/)
49400  800  FORMAT(2X,14(F8.4))
49500  C*
49600  C*900 WRITE(6,800) (THETA(I,J),J=1,JMAX)
49700  C*
49800  C*903 WRITE(6,801) DEEP(1,J)
49900  C*
50000  C*906 WRITE(6,800) (H(I,J),J=1,JMAX)
50100  C*
50200  C*755 WRITE(6,800) (CONST6(I,J),I=1,IMAX)
50300  801  FORMAT(2X,14(F8.2))
50400      WRITE(6,107)
50500  107  FORMAT(/,2X,'THE LONGSHORE TRANSPORTS,QX, FOLLOW')
50600      DO 15 J=1,JMAX
50700  15  WRITE(6,100) (QX(I,J),I=1,IMAX)

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50800      WRITE(6,108)
50900      108 FORMAT(/,2X,'THE ON-OFFSHORE TRANSPORTS, QY, FOLLOW')
51000      DO 17 J=1,JMAX
51100      17   WRITE(6,101) (QY(I,J),I=1,IMAX)
51200      WRITE(6,109)
51300      109 FORMAT(/,2X,'THE NEW CONTOUR VALUES, Y, FOLLOW')
51400      DO 18 J=1,JMAX
51500      18   WRITE(6,100) (Y(I,J),I=1,IMAX)
51600      100  FORMAT(2X,13(F9.3))
51700      101  FORMAT(2X,13(F9.4))
51800      1    CONTINUE
51900      RETURN
52000      GO TO 446
52100      445 STOP
52200      446 CONTINUE
52300      END
52400  C*****
52500      SUBROUTINE QTRAN
52600  C*THIS SUBROUTINE CALCS THE BREAKER HEIGHT FOR EACH
52700  C*OF THE I GRID LINES. METHOD--FINDS Y-LOCATIONS BEFORE AND AFTER
52800  C*BREAKING HAS OCCURRED BY 'REFRAC', THEN USES SHOALING TO GET THE
52900  C*HBQ. SNELL'S LAW IS USED FOR REFRACTION OVER THE SHORT DIST TO BREAKING
53000  C* QX(I,J) IS THE TRANS BETWEEN(I-1,J) AND (I,J) AT THE BLOCKCENT
53100      COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
53200      COMMON/AA/YZERO(60)
53300      COMMON/B/ THETA(60,20),QXTOT(60), OLDANG(60,20), DY(60,20)
53400      COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
53500      COMMON/N USED/JUSE,T,CD,CGEN,CGGEN,ANGGEN,DX,BERM,THETA0(10),MMAX
53600      COMMON/D/SIGMA,G,ELO,JMAX,IMAX,PI,TWOPI,PIO2,HGEN,IJET(10),SJETTY
53700      COMMON/G/IBREAK(60),HNONBR(20)
53800      COMMON/E/RHO,RHOS,POROS,CONST,TKSI
53900      COMMON/P/HBQ(60),DEEPB(60)
54000      CAPP=0.78
54100      DO 1 I=2,IMAX
54200      DO 2 JJ=1,JMAX
54300      J=JMAX-JJ+1
54400      HDUM=(H(I,J)+H(I-1,J))*0.5
54500      HBDUM=(HB(I,J)+HB(I-1,J))*0.5
54600  C*CAN ONLY USE COND ON ONE SIDE OF STRUCT. CAN'T AVG HERE!
54700      IF(SJETTY.EQ.0.0) GO TO 4
54800      DO 4 M=1,MMAX
54900      IF(I.NE.IJET(M)+1) GO TO 4
55000      IF(THETA0(M).GE.0.0) ISIDE=IJET(M)
55100      IF(THETA0(M).LT.0.0) ISIDE=IJET(M)+1
55200  C**B.C. AT STRUCT TIP ASSUMES QX COMP AS IF NO STRUCT IS PRESENT.
55300      YSEA=0.5*(Y(ISIDE,J)+Y(ISIDE,J+1))
55400      IF(YSEA.GT.SJETTY) GO TO 3
55500      HDUM=H(ISIDE,J)
55600      HBDUM=HB(ISIDE,J)
55700      GO TO 3
55800      4 CONTINUE
55900      3 IF(HDUM.NE.HBDUM) GO TO 2
56000      DEEPB(I)=((0.5*(H(I,J+1)+H(I-1,J+1)))*((0.5*(DEEP(I,J+1)
56100      * +DEEP(I-1,J+1)))*0.25)/CAPP)**0.8
56200      HBQ(I)=CAPP*DEEPB(I)
56300  C*HBQ(I) AND DEEPB(I) WILL BE COMPUTED ACCORDING TO THE WAVE DIR.
56400  C** AT THE STRUCTURE TIP,THETA0.
56500      IF(SJETTY.EQ.0.0) GO TO 1
56600      DO 6 M=1,MMAX
56700      IF(I.NE.IJET(M)+1) GO TO 6
56800  C**THE TRANSPORTING WAVES WILL BE COMPUTED USING THE WAVE TO PROP SIDE.
56900      IF(THETA0(M).GE.0.0) GO TO 11
57000      DEEPB(I)=(H(IJET(M)+1,J+1)*DEEP(IJET(M)+1,J+1)**0.25/CAPP)**0.8
57100      IBREAK(I)=IBREAK(IJET(M)+1)
57200      GO TO 12
57300      11 DEEPB(I)=(H(IJET(M),J+1)*DEEP(IJET(M),J+1)**0.25/CAPP)**0.8
57400      IBREAK(I)=IBREAK(IJET(M))
57500      12 HBQ(I)=DEEPB(I)*CAPP
57600      GO TO 1
57700      6 CONTINUE
57800      GO TO 1
57900      2 CONTINUE
58000      1 CONTINUE

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58100 C*IF THE OFFSHORE WAVE HT IS ZERO, NEVER GET TO HERE.
58200 C*HOWEVER IF THE H IS SUCH THAT IT WOULD BREAK INSHORE OF Y(I,2)
58300 C*DEEPB(I) WOULD STILL BE ZERO AND DISTR(I,J) WOULD BLOW-UP.
58400 DO 20 I=1,IMAX
58500 IF(DEEPB(I).GT.O.O) GO TO 20
58600 DEEPB(I)=(H(I,1)*DEEP(I,1)**0.25/CAPPA)**0.8
58700 HBQ(I)=CAPPA*DEEPB(I)
58800 20 CONTINUE
58900 HBQ(1)=HBQ(2)
59000 HBQ(IMAX+1)=HBQ(IMAX)
59100 DEEPB(1)=DEEPB(2)
59200 DEEPB(IMAX+1)=DEEPB(IMAX)
59300 RETURN
59400 END
59500 C*****
59600 SUBROUTINE BREAK(IMAX,JMAX)
59700 C*ROUTINE WILL DETERMINE HB AND DEEPB ON THE GRID LINES RATHER
59800 C* THAN BETWEEN THEM. REQ'D FOR COFF BEYOND SURF ZONE.
59900 COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
60000 COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
60100 COMMON/MP/ RKB(60),HBI(60),DEEPBI(60)
60200 CAPPA=0.78
60300 DO 1 I=2,IMAX
60400 DO 2 JJ=1,JMAX
60500 J=JMAX-JJ+1
60600 IF(H(I,J).LT.HB(I,J)) GO TO 2
60700 DEEPBI(I)={(H(I,J+1)*DEEP(I,J+1)**0.25)/CAPPA)**0.8
60800 HBI(I)=CAPPA*DEEPBI(I)
60900 C***ONCE THE HEIGHT & DEPTH AT BREAKING ARE FOUND, GO TO NEXT GRID-LINE.
61000 GO TO 1
61100 2 CONTINUE
61200 1 CONTINUE
61300 DO 20 I=1,IMAX
61400 IF(DEEPBI(I).GT.O.O) GO TO 20
61500 DEEPBI(I)=(H(I,1)*DEEP(I,1)**0.25/CAPPA)**0.8
61600 HBI(I)=CAPPA*DEEPBI(I)
61700 20 CONTINUE
61800 DEEPBI(1)=DEEPBI(2)
61900 DEEPBI(IMAX+1)=DEEPBI(IMAX)
62000 HBI(1)=HBI(2)
62100 HBI(IMAX+1)=HBI(IMAX)
62200 RETURN
62300 END
62400 C*****
62500 SUBROUTINE REFRAC(JBEGIN,JEND,NPTS,IBEGIN,IEND,ISTART,M)
62600 COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
62700 COMMON/AA/YZERO(60)
62800 COMMON/B/ THETA(60,20),QXTOT(60),OLDANG(60,20),DY(60,20)
62900 COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
63000 COMMON/N USED/JUSE,T,CD,CGEN,CGGEN,ANGGEN,DX,BERM,THETA0(10),MMAX
63100 COMMON/D/SIGMA,G,ELD,JMAX,IMAX,PI,TWOPI,PIO2,HGEN,IJET(10),SJETTY
63200 COMMON/G/IBREAK(60),HNONBR(20)
63300 COMMON/ZZZ/NTIME
63400 DIMENSION JBEGIN(60),JEND(60)
63500 C***** THIS SUBROUTINE WILL DETERMINE H AND
63600 C***** THETA AT THE MID PT OF Y VALUES.
63700 C**TAU IS THE FACTOR WHICH RECOUPLES THE REFRACTION EQS. SEE ABBOTT
63800 TAU=0.25
63900 C*MUST PRESCRIBE THE WAVE ANGLE AT THE OUTERMOST CONTOUR BOX
64000 C*SNELL'S LAW WILL BE USED TO START THINGS OFF.
64100 C*THETA(I,J) WILL BE AT AREA'S CENTER AND WILL USE Y(I,J) IN NEG Y-DIR
64200 C*WILL INITIALIZE ALL THETA'S USING SNELL'S LAW.
64300 DO 206 I=IBEGIN,IEND
64400 C*INITIALIZE TWO J-VALUES BEYOND JMAX,IF IN REGION 1.
64500 IF(JEND(I).EQ.JMAX) JINIT=2
64600 IF(JEND(I).NE.JMAX) JINIT=0
64700 DO 206 J=JBEGIN(I),JEND(I)+JINIT
64800 C*MUST CORRECT FOR THE CONTOUR ORIENTATION, ALPHAS.
64900 IF(I.NE.IBEGIN) GO TO 960
65000 ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0.5*(Y(I,J)
65100 * +Y(I,J+1)))/DX)
65200 GO TO 962

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65300      960 IF(I.NE.IEND) GO TO 961
65400      ALPHAS(I,J)=ATAN((0.5*(Y(I,J)+Y(I,J+1))-0.5*(Y(I-1,J)
65500      * +Y(I-1,J+1)))/DX)
65600      GO TO 962
65700      961 ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0.5*
65800      * (Y(I-1,J)+Y(I-1,J+1)))/(2.*DX))
65900      962 DALPHA=ANGGEN-ALPHAS(I,J)
66000      THETA(I,J)=ARSIN((C(I,J)/CGEN)*SIN(DALPHA))
66100      C*MUST GET THETA WRT THE X-AXIS.
66200      THETA(I,J)=THETA(I,J)+ALPHAS(I,J)
66300      206 CONTINUE
66400      C*NOW, WE MUST COMP THE BOUN WAVE HTS SO THE HTS CAN BE COMPUTED.
66500      C*WILL USE THE EQ. ***** DEL DOT (E*CG)=0.0
66600      C*NOW WE WILL CORRECT THE HT FOR SHOALING AND REFRACTION TO THE B.C.
66700      C*WILL ALSO INITIALIZE H'S WITH THESE EQUATIONS FOR ENTIRE ARRAY.
66800      DO 500 I=IBEGIN,IEND
66900      C*INITIALIZE TWO J-VALUES BEYOND JMAX IF IN REGION 1.
67000      IF(JEND(I).EQ.JMAX) JINIT=2
67100      IF(JEND(I).NE.JMAX) JINIT=0
67200      DO 500 J=JBEGIN(I),JEND(I)+JINIT
67300      H(I,J)=HGEN*SQRT(CGGEN/CG(I,J))*SQRT(COS(ANGGEN)/COS(THETA(I,
67400      * J)))
67500      IF(HB(I,J).LT.H(I,J)) H(I,J)=HB(I,J)
67600      500 CONTINUE
67700      C*-----
67800      C*****
67900      C*LET'S FILL THE DY ARRAY.
68000      C*DY WILL BE INDEXED AS THE THETA TO WHICH WE ARE GOING.
68100      DO 209 I=IBEGIN,IEND
68200      DO 209 J=JBEGIN(I)+1,JEND(I)
68300      DY(I,J-1)=0.5*(Y(I,J-1)+Y(I,J))-0.5*(Y(I,J)+Y(I,J+1))
68400      209 CONTINUE
68500      NITERS=100
68600      DO 100 NITER=1,NITERS
68700      SUMANG=0.0
68800      C*DO "60 LOOP" GOES FROM 2 TO IMAX IF ISTART =IBEGIN
68900      C*DO "60 LOOP" GOES FROM IMAX-1 TO 1 IF ISTART=IEND
69000      DO 60 II=IBEGIN,IEND
69100      C*MUST HAVE IT SET UP SO THAT THE KNOWN BOUNDARIES ANGLES AREN'T RECOMP
69200      IF(ISTART.EQ.IBEGIN) I=II
69300      IF(ISTART.EQ.IBEGIN .AND. I.EQ.IBEGIN) GO TO 60
69400      IF(ISTART.EQ.IEND) I=IEND-II+IBEGIN
69500      IF(ISTART.EQ.IEND .AND. I.EQ.IEND) GO TO 60
69600      C*ADX EQUALS ACTUAL DELTA X ACROSS SPACE STEP.
69700      C*ONLY ON BOUNDARIES WHERE FORWARD OR BACKWARD DIFFERENCING.
69800      IF(I.NE.IBEGIN) GO TO 6
69900      ADX=DX
70000      IP=I+1
70100      IM=I
70200      GO TO 12
70300      6 IF(I.NE.IEND) GO TO 10
70400      ADX=DX
70500      IP=I
70600      IM=I-1
70700      GO TO 12
70800      10 ADX=2.0*DX
70900      IP=I+1
71000      IM=I-1
71100      12 CONTINUE
71200      DO 40 J=JBEGIN(I),JEND(I)-1
71300      C*WILL GO FROM (JMAX-1) TO 1 BECAUSE THAT'S THE DIR WAVE COMES IN FROM.
71400      JJ=JEND(I)-1-J+JBEGIN(I)
71500      OLDANG(I,JJ)=THETA(I,JJ)
71600      C*LOCATE MIDPOINT BETWEEN TWO ADJACENT BLOCK CENTERS
71700      C*BECAUSE THETA'S JJ-VALUE IS THE SAME AS THE FIRST SHOREWARD Y VALUE
71800      C*MUST USE JJ, JJ+1, AND JJ+2 TO COMPUTE YBAR.
71900      YBAR=0.25*(Y(I,JJ)+2.0*Y(I,JJ+1)+Y(I,JJ+2))
72000      C*LOCATE APPROPRIATE INDICES ON IP AND IM GRID LINES.
72100      IMINUS=-1
72200      IPLUS=+1
72300      CALL LOC(IM,JJ,JOIM,USIM,YBAR,IMINUS)
72400      CALL LOC(IP,JJ,JOIP,USIP,YBAR,IPLUS)
72500      C*NOW USE THE CONSERVATION OF WAVES EQUATION.....

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72600      PART1C=RK(I,JJ+1)*SIN(THETA(I,JJ+1))
72700      PART2=-DY(I,JJ)/ADX
72800      C*WILL LINEARLY INTERPOLATE TO DETERMINE RK*COS(THETA) AT I+1 AND I-1.
72900      C*IF NO ADJ SHOREWARD PT EXISTS, PUT IN ZERO FOR TERMS IN GOV. EQ.
73000      IF(JSIM.NE.O) GO TO 301
73100      PART3B=O.O
73200      GO TO 302
73300      301 TOPIM=RK(IM,JOIM-1)*COS(THETA(IM,JOIM-1))
73400      BOTIM=RK(IM,JSIM)*COS(THETA(IM,JSIM))
73500      TOTALB=O.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-O.5*(Y(IM,JSIM)+Y(IM,JSIM))
73600      DUMB=O.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-YBAR
73700      PART3B=((TOTALB-DUMB)*(TOPIM-BOTIM)/TOTALB)+BOTIM
73800      302 IF(JSIP.NE.O) GO TO 303
73900      PART3A=O.O
74000      GO TO 304
74100      303 TOPIP=RK(IP,JOIP-1)*COS(THETA(IP,JOIP-1))
74200      BOTIP=RK(IP,JSIP)*COS(THETA(IP,JSIP))
74300      TOTALA=O.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-O.5*(Y(IP,JSIP)+Y(IP,JSIP))
74400      DUMA=O.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-YBAR
74500      PART3A=((TOTALA-DUMA)*(TOPIP-BOTIP)/TOTALA)+BOTIP
74600      304 PART3=PART3A-PART3B
74700      C*NOW MUST FIND RK*SIN(THETA) FOR I+1 AND I-1 AT J+1
74800      YBARP=O.25*(Y(I,JJ+1)+2.*Y(I,JJ+2)+Y(I,JJ+3))
74900      CALL LOC(IM,JJ+1,JPOIM,JPSIM,YBARP,IMINUS)
75000      CALL LOC(IP,JJ+1,JPOIP,JPSIP,YBARP,IPLUS)
75100      IF(JPSIM.NE.O) GO TO 305
75200      PART1B=O.O
75300      GO TO 306
75400      305 TOPM=RK(IM,JPOIM-1)*SIN(THETA(IM,JPOIM-1))
75500      BOTM=RK(IM,JPSIM)*SIN(THETA(IM,JPSIM))
75600      TOTB=O.5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))-O.5*(Y(IM,JPSIM)+Y
75700      * Y(IM,JPSIM))
75800      DUMPB=O.5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))-YBARP
75900      PART1B=((TOTB-DUMPB)*(TOPM-BOTM)/TOTB)+BOTM
76000      306 IF(JPSIP.NE.O) GO TO 307
76100      PART1A=O.O
76200      GO TO 308
76300      307 TOPP=RK(IP,JPOIP-1)*SIN(THETA(IP,JPOIP-1))
76400      BOTP=RK(IP,JPSIP)*SIN(THETA(IP,JPSIP))
76500      TOTA=O.5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))-O.5*(Y(IP,JPSIP)+Y(IP,JPSIP
76600      * ))
76700      DUMPA=O.5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))-YBARP
76800      PART1A=((TOTA-DUMPA)*(TOPP-BOTP)/TOTA)+BOTP
76900      308 PART1=TAU*PART1B+(1.-2.*TAU)*PART1C+TAU*PART1A
77000      IF(JPSIM.EQ.O)PART1=(1.-TAU)*PART1C+TAU*PART1A
77100      IF(JPSIP.EQ.O)PART1=TAU*PART1B+(1.-TAU)*PART1C
77200      ARG=((PART1+PART2*PART3)/RK(I,JJ))
77300      C*IF THE ROUTINE IS TO BLOWUP,USE SNELLS LAW.
77400      IF(ABS(ARG).LE.1.O) GO TO 41
77500      ARG=(C(I,JJ)/C(I,JJ+1))*SIN(THETA(I,JJ+1))
77600      IF(ARG.GT.1.O) ARG=1.O
77700      THETA(I,JJ)=ARSIN(ARG)
77800      GO TO 42
77900      41 THETA(I,JJ)=ARSIN(ARG)
78000      42 THETA(I,JJ)=O.5*(THETA(I,JJ)+OLDANG(I,JJ))
78100      SUMANG=SUMANG+(ABS(THETA(I,JJ)-OLDANG(I,JJ)))
78200      40 CONTINUE
78300      60 CONTINUE
78400      C*MUST EJECT IF WE HAVE REACHED AN ACCEPTABLE ITERATION ERROR
78500      C*IF THE SUM OF THE ABSOLUTE VALUE OF ANGLE CHANGES DURING AN ITERATION
78600      C* AVERAGES LESS THAN O.02 DEGREES PER GRID ITS CLOSE ENOUGH.
78700      IF(SUMANG.LT.(NPTS*O.O035)) GO TO 215
78800      IF(NITER.GE.50) GO TO 215
78900      100 CONTINUE
79000      WRITE(6,803)
79100      215 CONTINUE
79200      C*ITERATION LOOP FOR THE WAVE HEIGHT.
79300      DO 501 NITER=1,NITERS
79400      SUMH=O.O
79500      DO 510 II=IBEGIN,IEND
79600      C*MUST HAVE IT SET UP SO THAT THE KNOWN BOUNDARIES HTS. AREN'T RECOMP
79700      IF(ISTART.EQ.IBEGIN) I=II
79800      IF(ISTART.EQ.IBEGIN .AND. I.EQ.IBEGIN) GO TO 510

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79900          IF(ISTART.EQ.IEND) I=IEND-II+IBEGIN
80000          IF(ISTART.EQ.IEND .AND. I.EQ.IEND) GO TO 510
80100 C*ADX EQUALS ACTUAL DELTA X ACROSS SPACE STEP.
80200 C*ONLY ON BOUNDARIES WHERE FORWARD OR BACKWARD DIFFERENCING.
80300          IF(I.NE.IBEGIN) GO TO 503
80400          ADX=DX
80500          IP=I+1
80600          IM=I
80700          GO TO 505
80800 503      IF(I.NE.IEND) GO TO 504
80900          ADX=DX
81000          IP=I
81100          IM=I-1
81200          GO TO 505
81300 504      ADX=2.0*DX
81400          IP=I+1
81500          IM=I-1
81600 505      CONTINUE
81700          DO 502 J=JBEGIN(I),JEND(I)-1
81800          JJ=JEND(I)-1-J+JBEGIN(I)
81900          HOLD(I,JJ)=H(I,JJ)
82000          YBAR=0.25*(Y(I,JJ)+2.0*Y(I,JJ+1)+Y(I,JJ+2))
82100          CALL LOC(IM,JJ,JOIM,JSIM,YBAR,IMINUS)
82200          CALL LOC(IP,JJ,JOIP,JSIP,YBAR,IPLUS)
82300          PART13=(H(I,JJ+1)**2.)*CG(I,JJ+1)*COS(THETA(I,JJ+1))
82400          PART2=DY(I,JJ)/ADX
82500          IF(JSIM.NE.O) GO TO 311
82600          PART4B=0.0
82700          GO TO 312
82800 311      TOPIMH=(H(IM,JOIM-1)**2.)*CG(IM,JOIM-1)*(SIN(THETA(IM,JOIM-1)))
82900          BOTIMH=(H(IM,JSIM)**2.)*CG(IM,JSIM)*SIN(THETA(IM,JSIM))
83000          TOTALB=0.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-0.5*(Y(IM,JSIM+1)+Y(IM,JSIM))
83100          DUMB=0.5*(Y(IM,JOIM)+Y(IM,JOIM-1))-YBAR
83200          PART4B=((TOTALB-DUMB)*(TOPIMH-BOTIMH)/TOTALB)+BOTIMH
83300 312      IF(JSIP.NE.O) GO TO 313
83400          PART4A=0.0
83500          GO TO 314
83600 313      TOPIPH=(H(IP,JOIP-1)**2.)*CG(IP,JOIP-1)*SIN(THETA(IP,JOIP-1))
83700          BOTIPH=(H(IP,JSIP)**2.)*CG(IP,JSIP)*SIN(THETA(IP,JSIP))
83800          TOTALA=0.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-0.5*(Y(IP,JSIP+1)+Y(IP,JSIP))
83900          DUMA=0.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-YBAR
84000          PART4A=((TOTALA-DUMA)*(TOIPH-BOTIPH)/TOTALA)+BOTIPH
84100 314      PART4=PART4A-PART4B
84200          YBARP=0.25*(Y(I,JJ+1)+2.*Y(I,JJ+2)+Y(I,JJ+3))
84300          CALL LOC(IM,JJ+1,JPOIM,JPSIM,YBARP,IMINUS)
84400          CALL LOC(IP,JJ+1,JPOIP,JPSIP,YBARP,IPLUS)
84500          IF(JPSIM.NE.O) GO TO 315
84600          PART12=0.0
84700          GO TO 316
84800 315      TOPMH=(H(IM,JPOIM-1)**2)*CG(IM,JPOIM-1)*COS(THETA(IM,JPOIM-1))
84900          BOTMH=(H(IM,JPSIM)**2)*CG(IM,JPSIM)*COS(THETA(IM,JPSIM))
85000          TOTB=.5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))-.5*(Y(IM,JPSIM+1)+Y(IM,JPSIM))
85100          DUMPB=0.5*(Y(IM,JPOIM)+Y(IM,JPOIM-1))-YBARP
85200          PART12=((TOTB-DUMPB)*(TOPMH-BOTMH)/TOTB)+BOTMH
85300 316      IF(JPSIP.NE.O) GO TO 317
85400          PART11=0.0
85500          GO TO 318
85600 317      TOPPH=(H(IP,JPOIP-1)**2)*CG(IP,JPOIP-1)*COS(THETA(IP,JPOIP-1))
85700          BOTPH=(H(IP,JPSIP)**2)*CG(IP,JPSIP)*COS(THETA(IP,JPSIP))
85800          TOTA=.5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))-0.5*(Y(IP,JPSIP+1)+Y(IP,JPSIP))
85900          DUMPA=0.5*(Y(IP,JPOIP)+Y(IP,JPOIP-1))-YBARP
86000          PART11=((TOTA-DUMPA)*(TOPPH-BOTPH)/TOTA)+BOTPH
86100 318      PART1H=TAU*PART12+(1.-2.*TAU)*PART13+TAU*PART11
86200          IF(JPSIM.EQ.O)PART1H=(1.-TAU)*PART13+TAU*PART11
86300          IF(JSIP.EQ.O)PART1H=TAU*PART12+(1.-TAU)*PART13
86400          ARG=((PART1H+PART2*PART4)/(CG(I,JJ)*COS(THETA(I,JJ))))
86500 C*IF THERE IS TO BE AN INVALID SQRT,USE LINEAR SHOALING.
86600          IF(ARG.GE.O) GO TO 44
86700          ARG=(CG(I,JJ+1)*COS(THETA(I,JJ+1)))/(CG(I,JJ)*COS(THETA(I,JJ)))
86800          IF(ARG.LT.O.O) ARG=O.O
86900          H(I,JJ)=H(I,JJ+1)*SQRT(ARG)
87000          GO TO 45

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87100      44 H(I, JJ)=SQRT(ARG)
87200      45 H(I, JJ)=0.5*(H(I, JJ)+HOLD(I, JJ))
87300      HNONBR(JJ)=H(I, JJ)
87400 C*IBREAK(I)=JJ, THEREFORE JJ WILL BE LEEWARD SIDE OF GRID AT INIT BREAK
87500      IF(HB(I, JJ) .LT. H(I, JJ) .AND. HB(I, JJ+1).GE.HNONBR(JJ+1))
87600      * IBREAK(I)=JJ
87700      IF(HB(I, JJ) .LT.H(I, JJ)) H(I, JJ)=HB(I, JJ)
87800      SUMH=SUMH+ABS(H(I, JJ)-HOLD(I, JJ))
87900      502 CONTINUE
88000      510 CONTINUE
88100      IBREAK(IEND)=IBREAK(IEND-1)
88200      IBREAK(IBEGIN)=IBREAK(IBEGIN+1)
88300      IF(SUMH.LT.(NPTS*0.01)) GO TO 507
88400      IF(NITER.GE.50) GO TO 507
88500      501 CONTINUE
88600      WRITE(6,803)
88700      507 CONTINUE
88800      802 FORMAT(2X,4(F15.5),////)
88900      803 FORMAT(2X,"AFTER NITERS ITERATIONS, CONVERGENCE WAS NOT REACHED")
89000      804 FORMAT(2X,"THE WAVE HT. ROUTINE CONVERGED IN, NITER= ",I5,/)
89100      805 FORMAT(2X,"THIS IS MY CHECKING WRITE STATEMENT")
89200      806 FORMAT(2X,"THE WAVE ANGLE ROUTINE CONVERGED IN, NITER= ",I5,/)
89300      RETURN
89400      END
89500 C*****
89600      SUBROUTINE DIFF(RHOND, THETA0, ANGLE, AMP)
89700 C****DIFFRACTION ABOUT SEMI INFINITE BREAKWATER (PENNEY-PRICE)
89800      PI=3.14159265
89900      ABSS=SIN(0.5*(ANGLE-THETA0))
90000      ABSP=SIN(0.5*(ANGLE+THETA0))
90100      ABC=COS(ANGLE-THETA0)
90200      ABC1=COS(ANGLE+THETA0)
90300      XX=RHOND*ABC
90400      XXC=COS(XX)
90500      XXS=SIN(XX)
90600      XX1=RHOND*ABC1
90700      XXC1=COS(XX1)
90800      XXS1=SIN(XX1)
90900      AL=SQRT(RHOND/PI)
91000      SIG=2.0*AL*ABSS
91100      SIGP=-2.0*AL*ABSP
91200      CALL FRES(SIG, C, S, FR, FI)
91300      CALL FRES(SIGP, CP, SP, FRP, FIP)
91400      SUM1=XXC*FR+XXS*FI+XXC1*FRP+XXS1*FIP
91500      SUM2=XXC*FI-XXS*FR+XXC1*FIP-XXS1*FRP
91600      AMP=SQRT(SUM1**2+SUM2**2)
91700      RETURN
91800      END
91900 C*****
92000      SUBROUTINE FRES(A, C, S, FR, FI)
92100 C*FRESNEL INTEGRAL SUBROUTINE****AFTER ABROMOWITZ AND STEGUN.
92200      Z=ABS(A)
92300      PO2=1.5707963
92400      FZ=(1.0+0.926*Z)/(2.0+1.792*Z+3.104*Z*Z)
92500      GZ=1.0/(2.0+4.142*Z+3.492*Z*Z+6.670*Z*Z*Z)
92600      XX=PO2*Z*Z
92700      CZ=COS(XX)
92800      SZ=SIN(XX)
92900      C=0.5-GZ*CZ+FZ*SZ
93000      S=0.5-FZ*CZ-GZ*SZ
93100      IF(A.GT.0.0) GO TO 50
93200      C=-C
93300      S=-S
93400      50 FR=0.5*(1.0+C+S)
93500      FI=-0.5*(S-C)
93600      RETURN
93700      END
93800 C*****
93900      SUBROUTINE PREDIF
94000      COMMON/ A/ C(60,20), RK(60,20), Y(60,20), DEEP(60,20), ALPHAS(60,20)
94100      COMMON/ AA/ YZERO(60)
94200      COMMON/ B/ THETA(60,20), QXTOT(60), OLDANG(60,20), DY(60,20)
94300      COMMON/ C/ H(60,20), CG(60,20), HOLD(60,20), HB(60,20), YB(60)

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94400 COMMON/N USED/JUSE,T,CO,CGEN,CGGEN,ANGGEN,DX',BERM,THETAO(10),MMAX
94500 COMMON/D/SIGMA,G,ELO,UMAX,IMAX,PI,TWOPI,PI02,HGEN,IJET(10),SJETTY
94600 COMMON/G/IBREAK(60),HNONBR(20)
94700 DIMENSION J1(60),J2(60),J1REF(60),J3REF(60)
94800 C*THIS SUB CALCS WHERE DIFFRACTION GOVERNS AND WHERE REFRACT GOVERNS.
94900 C*IT WILL CALL REFRAC FOR OFFSHORE AREA(OFF TIP OF STRUCTURE).
95000 C*THEN IT WILL DO THE SHADOW ZONE USING DIFF(IF THETAO .NE.O.O)
95100 C* IT WILL THEN FINISH THE OTHERS USING REFRAC AGAIN.
95200 C*LET'S ZERO-OUT THE DIMENSIONED ARRAYS.
95300 DO 1000 I=1,IMAX+2
95400 J1(I)=0.0
95500 J2(I)=0.0
95600 J1REF(I)=0.0
95700 1000 J3REF(I)=0.0
95800 C*NOW, LETS FIND C,CG,RK,HB, AND WVNUM.
95900 DO 202 I=1,IMAX
96000 DO 202 J=1,JMAX+2
96100 DEPTH=DEEP(I,J)
96200 CALL WVNUM(DEPTH,T,DUMK)
96300 RK(I,J)=DUMK
96400 C(I,J)=CD*TANH(RK(I,J)*DEEP(I,J))
96500 EN=0.5*(1.0+((2.*RK(I,J)*DEEP(I,J))/SINH(2.*RK(I,J)*DEEP(I,J))))
96600 CG(I,J)=EN*C(I,J)
96700 HB(I,J)=0.78*DEEP(I,J)
96800 202 CONTINUE
96900 C*WILL ATTRIB AN EQUAL REACH TO EACH SIDE OF EACH M-GROIN.
97000 DO 200 M=1,MMAX
97100 IDUML=1
97200 IF(M.NE.1) IDUML=(IJET(M)+IJET(M-1))/2
97300 IDUMR=IMAX
97400 IF(M.NE.MMAX) IDUMR=(IJET(M)+IJET(M+1))/2
97500 NPTS=0
97600 DO 1 I=IDUML,IDUMR
97700 DO 2 J=1,JMAX
97800 IF(Y(I,J).LT.SJETTY) GO TO 14
97900 J1(I)=J
98000 J2(I)=JMAX
98100 GO TO 15
98200 14 CONTINUE
98300 2 CONTINUE
98400 15 CONTINUE
98500 C*IF NO STRUCT IS PRESENT(SJETTY=0.0), DO REFRAC THRUOUT GRID SYSTEM
98600 IF(SJETTY.EQ.0.0) J1(I)=1
98700 1 CONTINUE
98800 DO 16 I=IDUML,IDUMR
98900 C* 'REFRAC' STARTS ON THE NEXT TO LAST J-CONTOUR,NOT THE LAST!
99000 DO 16 J=J1(I),J2(I)-1
99100 16 NPTS=NPTS+1
99200 C*WILL NOW DO THE REFRACT FOR THE REGION 1 AREA.
99300 C*ISTART REPRESENTS THE DIRECTION THE SWEEPS WILL BEGIN FROM.
99400 C*WILL USE DUMMY IMAX,IJET,IJET+1 IN CALL STTS SO IBEGIN,IEND, AND
99500 C***ISTART WON'T CHANGE THEM.MUST RESET AFTER EACH CALL REFRAC.
99600 IMAXT=IDUMR
99700 IJETT=IJET(M)
99800 IJETP1=IJET(M)+1
99900 IDUMLL=IDUML
100000 IF(ANGGEN.GE.O.O) CALL REFRAC(J1,J2,NPTS,IDUMLL,IMAXT,IDUMLL,M)
100100 IF(ANGGEN.LT.O.O) CALL REFRAC(J1,J2,NPTS,IDUMLL,IMAXT,IMAXT,M)
100200 IMAXT=IDUMR
100300 IJETT=IJET(M)
100400 IJETP1=IJET(M)+1
100500 IDUMLL=IDUML
100600 JDUMN=J1(IJET(M))
100700 JDUMS=J1(IJET(M)+1)
100800 XDISTN=(IJET(M)-1.0)*DX+DX/2.
100900 ELTIP=T*0.5*(C(IJET(M),JDUMN)+C(IJET(M)+1,JDUMS))
101000 C*NOW MUST CHECK THE ANGLE AT THE STRUCTURE'S TIP TO SEE WHERE SHAD ZONE
101100 C*IF NO STRUCT PRESENT(SJETTY=0.0), FURTHER REFRAC/DIFF UNNECESSARY.
101200 IF(SJETTY.EQ.O.O) GO TO 13
101300 THETAO(M)=0.5*(THETA(IJET(M),JDUMN)+THETA(IJET(M)+1,JDUMS))
101400 HINC=0.5*(H(IJET(M),JDUMN)+H(IJET(M)+1,JDUMS))
101500 IF(THETAO(M))10,11,12
101600 C*THIS SECTION HANDLES REFRAC/DIFF IF THETAO<0.0.

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101700      10 CONTINUE
101800      C*FIRST ALL OF REGION 2 WILL GET REFRACTED.
101900          NPTS=0
102000          DO 100 I=IJET(M)+1, IDUMR
102100             J2(I)=J1(I)
102200          100 J1(I)=1
102300          DO 101 I=IJET(M)+1, IDUMR
102400             DO 101 J=J1(I), J2(I)-1
102500          101 NPTS=NPTS+1
102600             IMAXT=IDUMR
102700             IDUMLL=IDUML
102800             IJETT=IJET(M)
102900             IJETP1=IJET(M)+1
103000             CALL REFRAC(J1, J2, NPTS, IJETP1, IMAXT, IMAXT, M)
103100             IMAXT=IDUMR
103200             IJETT=IJET(M)
103300             IJETP1=IJET(M)+1
103400             IDUMLL=IDUML
103500      C*NOW MUST DO REGION 3 OF NEG THETA0 CASE-SHADOW ZONE.
103600          DO 102 I=IDUML, IJET(M)
103700             J2(I)=J1(I)
103800          102 J1(I)=1
103900          DO 103 I=IDUML, IJET(M)
104000             J1REF(I)=1
104100             DO 104 J=J1(I), J2(I)+1
104200                XCOORD=(I-1.0)*DX
104300                YCOORD=0.5*(Y(I, J)+Y(I, J+1))
104400                ANGLE=ATAN((XDISTN-XCOORD)/(SJETT-YCOORD))
104500                IF(YCOORD.GT.SJETT) ANGLE=PI+ANGLE
104600      C*IF MOST SHOREWARD PT OUT OF SHAD ZONE, SO ARE THE OTHERS FOR THAT I.
104700             IF(ABS(ANGLE).GT.ABS(THETA0(M))) GO TO 105
104800             RAD=SQRT((XDISTN-XCOORD)**2+(SJETT-YCOORD)**2)
104900             RHOND=RAD*TWOPI/ELTIP
105000      C*DIFFRACTION TREATS THE POS THETA0 CASE.
105100             THE=ABS(THETA0(M))
105200             CALL DIFF(RHOND, THE, ANGLE, AMP)
105300             H(I, J)=AMP*HINC
105400             ANGRAD=-ANGLE
105500      C*WILL NOW REFRACT DIFF WAVES IN THE SHAD ZONE USING SNELL'S.
105600             CTIP=ELTIP/T
105700             ALPHAS(I, J)=ATAN((0.5*(Y(I+1, J)+Y(I+1, J+1))-0.5*
105800              * (Y(I-1, J)+Y(I-1, J+1)))/(2.*DX))
105900             IF(I.EQ.IJET(M))ALPHAS(I, J)=ATAN((0.5*(Y(I, J)+Y(I, J+1))-0.5*(Y(I-1
106000              * ,J)+Y(I-1, J+1)))/DX)
106100             DALPHA=ANGRAD-ALPHAS(I, J)
106200             THETA(I, J)=ARSIN((C(I, J)/CTIP)*SIN(DALPHA))
106300             THETA(I, J)=THETA(I, J)+ALPHAS(I, J)
106400      C*MUST CHECK TO SEE IF WAVE WOULD HAVE BROKEN.
106500             IF(HB(I, J).LE.H(I, J).AND.HB(I, J+1).GT.H(I, J+1))IBREAK(I)=J
106600             IF(HB(I, J).LT.H(I, J)) H(I, J)=HB(I, J)
106700          104 CONTINUE
106800             GO TO 103
106900          105 J1REF(I)=J
107000          103 CONTINUE
107100      C*NOW MUST DO REFRACTION FOR REGION 4.
107200          NPTS=0
107300          DO 106 I=IDUML, IJET(M)
107400             DO 106 J=J1REF(I), J2(I)-1
107500          106 NPTS=NPTS+1
107600             IDUMLL=IDUML
107700             IMAXT=IDUMR
107800             IJETT=IJET(M)
107900             IJETP1=IJET(M)+1
108000             CALL REFRAC(J1REF, J2, NPTS, IDUMLL, IJETT, IDUMLL, M)
108100             IDUMLL=IDUML
108200             IMAXT=IDUMR
108300             IJETT=IJET(M)
108400             IJETP1=IJET(M)+1
108500             GO TO 13
108600      C*THIS HANDLES REFRAC/DIFF IF THETA0 IS 0.0.
108700      C*FOR THIS CASE, ONLY THREE REGIONS EXIST.
108800          11 CONTINUE
108900          NPTS=0

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109000      DO 120 I=IDUML,IJET(M)
109100          J2(I)=J1(I)
109200      120 J1(I)=1
109300          DO 121 I=IDUML,IJET(M)
109400              DO 121 J=J1(I),J2(I)-1
109500      121 NPTS=NPTS+1
109600          IMAXT=IDUMR
109700          IDUMLL=IDUML
109800          IJETT=IJET(M)
109900          IJETP1=IJET(M)+1
110000          CALL REFRAC(J1,J2,NPTS, IDUMLL, IJETT, IDUMLL, M)
110100          IMAXT=IDUMR
110200          IJETT=IJET(M)
110300          IJETP1=IJET(M)+1
110400          IDUMLL=IDUML
110500          DO 122 I=IJET(M)+1, IDUMR
110600              J2(I)=J1(I)
110700      122 J1(I)=1
110800          NPTS=0
110900          DO 123 I=IJET(M)+1, IDUMR
111000              DO 123 J=J1(I),J2(I)-1
111100      123 NPTS=NPTS+1
111200          IMAXT=IDUMR
111300          IDUMLL=IDUML
111400          IJETT=IJET(M)
111500          IJETP1=IJET(M)+1
111600          CALL REFRAC(J1,J2,NPTS, IJETP1, IMAXT, IMAXT, M)
111700          IMAXT=IDUMR
111800          IJETT=IJET(M)
111900          IJETP1=IJET(M)+1
112000          IDUMLL=IDUML
112100          GO TO 13
112200      C*THIS SECTION HANDLES REFRACT/DIFF IF THETAO>0.0
112300          12 CONTINUE
112400      C*FIRST, REGION 2- ALL REFRACTION.
112500          NPTS=0
112600          DO 110 I=IDUML, IJET(M)
112700              J2(I)=J1(I)
112800      110 J1(I)=1
112900          DO 111 I=IDUML, IJET(M)
113000              DO 111 J=J1(I), J2(I)-1
113100      111 NPTS=NPTS+1
113200          IMAXT=IDUMR
113300          IDUMLL=IDUML
113400          IJETT=IJET(M)
113500          IJETP1=IJET(M)+1
113600          CALL REFRAC(J1,J2,NPTS, IDUMLL, IJETT, IDUMLL, M)
113700          IMAXT=IDUMR
113800          IJETT=IJET(M)
113900          IJETP1=IJET(M)+1
114000          IDUMLL=IDUML
114100      C*NOW WILL DO REGION 3 OF THE POS THETAO CASE.
114200          DO 112 I=IJET(M)+1, IDUMR
114300              J2(I)=J1(I)
114400      112 J1(I)=1
114500          DO 113 I=IJET(M)+1, IDUMR
114600              J1REF(I)=1
114700      C*WILL GO ONE PT. BEYOND J2(I) TO MAKE SURE OUTOF DIFF ZONE.
114800          DO 114 J=J1(I), J2(I)+1
114900              XCOORD=(I-1.0)*DX
115000              YCOORD=0.5*(Y(I,J)+Y(I,J+1))
115100              ANGLE=ATAN((XCOORD-XDISTN)/(SJETT-YCOORD))
115200              IF(YCOORD.GT.SJETT) ANGLE=PI+ANGLE
115300      C*IF LEAST J-VALUE IS OUT OF SHAD ZONE, SO ARE OTHER J'S. (FOR EACH I)
115400              IF(ANGLE.GT.ABS(THETAO(M))) GO TO 115
115500              RAD=SQRT((XCOORD-XDISTN)**2+(SJETT-YCOORD)**2)
115600              RHOND=RAD*TWOP/ELTIP
115700              THE=THETAO(M)
115800              CALL DIFF(RHOND,THE,ANGLE,AMP)
115900              ANGRAD=ANGLE
116000      C*WILL NOW REFRACT DIFFRACTED WAVES IN SHAD ZONE USING SNELL'S.
116100          CTIP=ELTIP/T
116200          ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0.5*

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116300      * (Y(I-1,J)+Y(I-1,J+1))/(2.*DX))
116400      IF(I.EQ.IJET(M)+1)ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0.5*
116500      * (Y(I,J)+Y(I,J+1)))/DX)
116600      DALPHA=ANGRAD-ALPHAS(I,J)
116700      THETA(I,J)=ARSIN((C(I,J)/CTIP)*SIN(DALPHA))
116800      THETA(I,J)=THETA(I,J)+ALPHAS(I,J)
116900      H(I,J)=HINC*AMP
117000  C*MUST CHECK TO SEE IF WAVE WOULD HAVE BROKEN.
117100      IF(HB(I,J).LE.H(I,J).AND.HB(I,J+1).GT.H(I,J+1))IBREAK(I)=J
117200      IF(HB(I,J).LT.H(I,J)) H(I,J)=HB(I,J)
117300      114 CONTINUE
117400      GO TO 113
117500      115 J1REF(I)=J
117600      113 CONTINUE
117700  C*NOW MUST DO REFRAC FOR REGION 4.
117800      NPTS=0
117900      DO 116 I=IJET(M)+1, IDUMR
118000      DO 116 J=J1REF(I), J2(I)-1
118100      116 NPTS=NPTS+1
118200      IMAXT=IDUMR
118300      IDUMLL=IDUML
118400      IJETT=IJET(M)
118500      IJETP1=IJET(M)+1
118600      CALL REFRAC(J1REF, J2, NPTS, IJETP1, IMAXT, IMAXT, M)
118700      IMAXT=IDUMR
118800      IJETT=IJET(M)
118900      IJETP1=IJET(M)+1
119000      IDUMLL=IDUML
119100      13 CONTINUE
119200      200 CONTINUE
119300      RETURN
119400      END
119500  C*****
119600      SUBROUTINE LOC(IM, JJ, JOIM, JSIM, YBAR, IDUM)
119700      COMMON/A/ C(60,20), RK(60,20), Y(60,20), DEEP(60,20), ALPHAS(60,20)
119800      COMMON/AA/ YZERO(60)
119900      COMMON/B/ THETA(60,20), QXTDT(60), OLDANG(60,20), DY(60,20)
120000      COMMON/C/ H(60,20), CG(60,20), HOLD(60,20), HB(60,20), YB(60)
120100      COMMON/N USED/JUSE, T, CO, CGEN, CGEN, ANGEN, DX, BERM, THETA0(10), MMAX
120200      COMMON/D/SIGMA, G, ELO, JMAX, IMAX, PI, TWOPI, PIO2, HGEN, IJET(10), SJUETTY
120300  C*SUBROUTINE LOC FINDS J-VALUES WHICH ARE GREATER AND LESS THAN YBAR.
120400      JOIM=2
120500      2 AA=0.5*(Y(IM, JOIM)+Y(IM, JOIM-1))
120600      IF(AA.GT.YBAR) GO TO 4
120700      JOIM=JOIM+1
120800  C*THE FOLLOWING IS REQ'D SO THAT DY/DX>0.5
120900  C*WILL DTERMINE K SIN THETA ON IM-LINE AT A DIST YBAR.
121000  C*WILL CALL THIS POINT JUSE+1
121100      IF(JOIM.LE.JUSE) GO TO 2
121200      JOIM=JUSE+1
121300      Y(IM, JOIM)=YBAR
121400  C* DEPTH AT THIS POINT WILL BE COMP ASSUMING CONST BEACH SLOPE ON I=IM
121500      DEL=.5*(Y(IM, JOIM-1)+Y(IM, JOIM-2))-.5*(Y(IM, JOIM-2)+Y(IM, JOIM-3))
121600      BSLOPE=(DEEP(IM, JOIM-2)-DEEP(IM, JOIM-3))/DEL
121700      DEEP(IM, JOIM-1)=DEEP(IM, JOIM-2)+BSLOPE*(Y(IM, JOIM)-Y(IM, JOIM-1))
121800      DEPTH=DEEP(IM, JOIM-1)
121900      CALL WVNUM(DEPTH, T, DUMK)
122000      RK(IM, JOIM-1)=DUMK
122100      C(IM, JOIM-1)=CO*TANH(RK(IM, JOIM-1)*DEEP(IM, JOIM-1))
122200      EN=0.5*(1.0+(2.0*RK(IM, JOIM-1)*DEEP(IM, JOIM-1))/SINH(
122300      * 2.*RK(IM, JOIM-1)*DEEP(IM, JOIM-1)))
122400      CG(IM, JOIM-1)=C(IM, JOIM-1)*EN
122500  C*WILL USE SNELL'S LAW TO DETERMINE THE WAVE ANGLE HERE
122600  C*ANGLE OF CONTOUR WILL BE ASSUME TO BE THE SAME AS THE JMAX+1 CONTOUR
122700      IF(IDUM.EQ.1)ALPH=ATAN((Y(IM, JOIM-1)-Y(IM-1, JOIM-1))/DX)
122800      IF(IDUM.EQ.-1)ALPH=ATAN((Y(IM+1, JOIM-1)-Y(IM, JOIM-1))/DX)
122900      DALPHA=ANGGEN-ALPH
123000      THETA(IM, JOIM-1)=ARSIN((C(IM, JOIM-1)/CGEN)*SIN(DALPHA))
123100      THETA(IM, JOIM-1)=THETA(IM, JOIM-1)+ALPH
123200      4 JSIM=JMAX-1
123300      6 AA=0.5*(Y(IM, JSIM)+(Y(IM, JSIM+1)))
123400      IF(AA.LT.YBAR) GO TO 8
123500      JSIM=JSIM-1

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123600 C*IF JSIM=0, THERE IS NO ADJ PT, SUB REFRAC CAN HANDLE IT.
123700 IF(JSIM.EQ.0) GO TO 8
123800 GO TO 6
123900 8 RETURN
124000 END
124100
124200 C*****
124300 SUBROUTINE WVNUM(DEPTH,T,RK)
124400 G=32.17
124500 EPS=0.001
124600 TWOPI=6.283185307
124700 SIGMA=TWOPI/T
124800 RK=TWOPI/(T*SQRT(G*DEPTH))
124900 DD 100 IT=1,20
125000 ARG=RK*DEPTH
125100 EK=(G*RK*TANH(ARG))-(SIGMA**2)
125200 EKPR=G*(ARG*((SECH(ARG))**2)+TANH(ARG))
125300 RKNEW=RK-EK/EKPR
125400 IF(ABS(RKNEW-RK).LE.ABS(EPS*RKNEW)) GO TO 120
125500 RK=RKNEW
125600 100 CONTINUE
125700 WRITE(6,1000) IT,DEPTH,RK
125800 1000 FORMAT(///,10X,"ITERATION FOR K FAILED TO CONVERGE AFTER"
125900 * ,3X,13,"ITERATION",/, "OUTPUT: DEPTH, RK",3X,2F13.5)
126000 CALL EXIT
126100 120 RK=RKNEW
126200 IF(RK.GT.0.0) GO TO 140
126300 WRITE(6,1020) DEPTH,RK
126400 1020 FORMAT(///,10X," RK IS NEG",/, " OUTPUT DEPTH,RK",3X,2F13.5)
126500 CALL EXIT
126600 140 RETURN
126700 END
126800 C*****
126900 SUBROUTINE SMOOTH(THETA,IMAX,JMAX,IJET,SJETTY,MMAX,Y)
127000 C*THIS WILL SMOOTH THE WAVE ANGLE FIELD TO ACCT FOR DIFF(ARTIFICIALLY)
127100 DIMENSION TEMP(60,20),Y(60,20),THETA(60,20),IJET(10)
127200 C*(MMAX+1) IS REQ'D BECAUSE M-GROINS HAVE M+1 REACHES OF SHORELINE.
127300 DO 10 M=1,MMAX+1
127400 IF(M.NE.1) GO TO 3
127500 ILEFT=2
127600 IRIGHT=IJET(1)
127700 GO TO 5
127800 3 IF(M.NE.MMAX+1) GO TO 4
127900 ILEFT=IJET(MMAX)+1
128000 IRIGHT=IMAX-1
128100 GO TO 5
128200 4 ILEFT=IJET(M-1)+1
128300 IRIGHT=IJET(M)
128400 5 CONTINUE
128500 DO 1 J=1,JMAX-1
128600 DO 1 I=ILEFT,IRIGHT
128700 IF(I.NE.ILEFT.AND.I.NE.IRIGHT) GO TO 15
128800 C*TO GET HERE, MUST BE ON BOUN OR ADJ TO A STRUCTURE.
128900 IF(I.EQ.2.DR.I.EQ.IMAX-1) GO TO 15
129000 C*TO GET HERE,ADJ TO A STRUCT AND CAN BE ILEFT OR IRIGHT.
129100 IF(Y(I,J).GE.SJETTY) GO TO 15
129200 C*IF HERE, WITHIN JETTY AND ADJ TO EITHER SIDE.
129300 IF(I.EQ.ILEFT)TEMP(I,J)=0.5*(THETA(I,J)+THETA(I+1,J))
129400 IF(I.EQ.IRIGHT)TEMP(I,J)=0.5*(THETA(I,J)+THETA(I-1,J))
129500 GO TO 1
129600 15 TEMP(I,J)=0.25*THETA(I-1,J)+0.50*THETA(I,J)+0.25*THETA(I+1,J)
129700 1 CONTINUE
129800 10 CONTINUE
129900 DO 2 J=1,JMAX-1
130000 DO 2 I=2,IMAX-1
130100 2 THETA(I,J)=TEMP(I,J)
130200 RETURN
130300 END
130400 C*****
130500 FUNCTION SECH(A)
130600 SECH=1.0/COSH(A)
130700 RETURN
130800 END
130900 C****HERE IS WHERE THE IMSL ROUTINES MUST GO!

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## APPENDIX C

### CONTOURS AND SCHEMATIC ILLUSTRATIONS

This appendix presents tables of the original contours at Oregon Inlet and the final contours for the eight numerical simulations (Tables C-1 to C-9). Also included are schematic illustrations of sediment volumes transported from the nourished region (Figs. C-1 to C-8).

Table C-1. Initial bathymetry for all simulations (prior to any sediment addition).

Increasing I →	200,000	200,000	200,000	220,000	210,000	200,000	220,000	200,000	200,000	200,000	170,000	190,000
1	180,000	180,000	160,000	160,000	190,000	190,000	180,000	180,000	190,000	210,000	220,000	230,000
2	220,000	200,000	160,000	160,000	170,000	170,000	170,000	180,000	180,000	210,000	220,000	220,000
3	230,000	250,000	200,000	200,000	200,000	200,000	200,000	200,000	210,000	200,000	200,000	200,000
4	251,623	231,623	231,623	251,623	241,623	231,623	251,623	231,623	231,623	231,623	201,623	221,623
5	211,623	211,623	191,623	191,623	221,623	221,623	211,623	211,623	211,623	241,623	241,623	261,623
6	251,623	231,623	191,623	191,623	201,623	201,623	201,623	211,623	211,623	241,623	241,623	251,623
7	261,623	281,623	231,623	231,623	23,623	231,623	231,623	231,623	241,623	241,623	231,623	231,623
8	308,443	288,443	268,443	288,443	308,443	288,443	288,443	308,443	288,443	288,443	288,443	279,443
9	268,443	268,443	248,443	248,443	278,443	278,443	268,443	268,443	268,443	298,443	298,443	308,443
10	308,443	288,443	248,443	248,443	249,443	249,443	249,443	259,443	259,443	268,443	268,443	308,443
11	319,443	339,443	309,443	288,443	288,443	288,443	288,443	288,443	288,443	288,443	288,443	308,443
12	442,028	422,028	422,028	442,028	412,028	412,028	422,028	422,028	422,028	422,028	422,028	412,028
13	402,028	402,028	382,028	382,028	382,028	382,028	382,028	382,028	382,028	432,028	432,028	452,028
14	442,028	422,028	382,028	382,028	382,028	382,028	382,028	382,028	382,028	402,028	402,028	442,028
15	452,028	472,028	442,028	422,028	422,028	422,028	422,028	422,028	422,028	422,028	422,028	422,028
16	684,758	684,758	684,758	684,758	684,758	684,758	684,758	684,758	684,758	684,758	684,758	684,758
17	644,758	644,758	624,758	624,758	654,758	654,758	644,758	644,758	644,758	674,758	674,758	684,758
18	684,758	684,758	624,758	624,758	634,758	634,758	634,758	634,758	634,758	674,758	674,758	684,758
19	684,758	714,758	684,758	684,758	664,758	664,758	664,758	664,758	664,758	664,758	664,758	684,758
20	980,726	960,726	960,726	980,726	970,726	960,726	980,726	960,726	960,726	960,726	930,726	950,726
21	940,726	940,726	920,726	920,726	950,726	950,726	940,726	940,726	940,726	970,726	970,726	980,726
22	980,726	960,726	920,726	920,726	920,726	920,726	930,726	930,726	930,726	940,726	940,726	960,726
23	980,726	1010,726	960,726	960,726	960,726	960,726	960,726	960,726	960,726	970,726	970,726	960,726
24	1270,414	1250,414	1230,414	1250,414	1270,414	1270,414	1250,414	1250,414	1250,414	1250,414	1250,414	1240,414
25	1230,414	1230,414	1210,414	1210,414	1240,414	1240,414	1240,414	1240,414	1240,414	1260,414	1260,414	1270,414
26	1270,414	1250,414	1210,414	1210,414	1210,414	1220,414	1220,414	1220,414	1230,414	1260,414	1260,414	1270,414
27	1280,414	1300,414	1270,414	1250,414	1250,414	1250,414	1250,414	1250,414	1250,414	1250,414	1250,414	1250,414
28	1702,228	1682,228	1682,228	1702,228	1692,228	1682,228	1682,228	1682,228	1682,228	1682,228	1682,228	1672,228
29	1662,228	1662,228	1642,228	1642,228	1672,228	1672,228	1662,228	1662,228	1662,228	1692,228	1692,228	1712,228
30	1702,228	1682,228	1642,228	1642,228	1642,228	1652,228	1652,228	1652,228	1652,228	1662,228	1662,228	1702,228
31	1715,228	1732,228	1682,228	1682,228	1682,228	1682,228	1682,228	1682,228	1682,228	1682,228	1682,228	1682,228

Table C-2. Final contours, case 2.a.

THE NEW CONTOUR VALUES, Y, FOLLOW															
220.000	219.021	218.843	218.266	217.691	217.119	216.550	215.985	215.425	214.871	214.322	213.779	213.240	207.969	207.551	207.144
212.718	212.157	211.687	210.694	210.094	209.744	209.265	208.836	208.356	207.927	207.548	207.219	206.840	203.348	203.060	202.779
206.748	206.332	205.987	205.621	205.266	204.922	204.588	204.264	203.950	203.645	203.348	203.060	202.779	200.000	200.000	200.000
202.506	202.239	201.971	201.721	201.468	201.218	200.972	200.727	200.484	200.241	200.000	200.000	200.000	200.000	200.000	200.000
231.623	251.018	250.439	249.873	249.297	248.719	248.161	247.616	247.058	246.491	245.948	245.400	244.937	239.561	239.230	238.871
238.468	238.053	237.664	237.308	236.968	236.619	236.253	235.884	235.535	235.209	234.908	234.651	234.431	234.908	234.651	234.431
234.201	233.932	233.643	233.364	233.098	232.837	232.584	232.344	232.109	231.868	231.623	231.378	231.133	231.868	231.623	231.378
309.443	308.834	308.267	307.716	307.144	306.569	306.023	305.469	304.931	304.362	303.825	303.332	302.838	297.504	297.175	296.610
302.300	301.732	301.197	300.731	300.295	299.811	299.261	298.708	298.259	297.838	297.504	297.175	296.610	292.788	292.546	292.340
296.400	295.978	295.589	295.240	294.904	294.542	294.147	293.753	293.398	293.079	292.788	292.546	292.340	289.703	289.443	289.230
292.114	291.835	291.534	291.249	290.977	290.707	290.447	290.201	289.956	289.703	289.443	289.230	289.017	289.703	289.443	289.230
442.028	441.461	440.894	440.328	439.765	439.204	438.648	438.095	437.549	437.008	436.473	435.945	435.424	430.231	429.810	429.404
434.911	434.407	433.912	433.427	432.950	432.482	432.020	431.564	431.112	430.667	430.231	429.810	429.404	425.819	425.562	425.259
429.014	428.640	428.276	427.920	427.569	427.223	426.879	426.540	426.206	425.879	425.562	425.259	424.970	422.028	421.777	421.528
424.696	424.433	424.178	423.925	423.669	423.406	423.136	422.864	422.587	422.307	422.028	419.301	419.017	418.733	418.450	418.167
684.758	684.191	683.625	683.064	682.509	681.961	681.420	680.885	680.354	679.827	679.301	678.777	678.254	668.658	668.347	668.057
677.735	677.220	676.713	676.215	675.730	675.259	674.803	674.361	673.933	673.518	673.116	672.725	672.340	668.658	668.347	668.057
667.700	667.283	666.870	666.462	666.062	665.669	665.284	664.906	664.534	664.168	663.807	663.450	663.097	663.743	663.390	663.037
984.726	984.133	983.548	982.962	982.376	981.790	981.214	980.648	980.092	979.546	979.000	978.464	977.938	968.665	968.347	968.029
973.574	973.043	972.516	971.997	971.489	970.977	970.475	969.982	969.496	969.016	968.541	968.070	967.603	963.743	963.390	963.037
967.779	967.417	967.047	966.667	966.278	965.887	965.500	965.125	964.769	964.438	964.135	963.859	963.606	963.743	963.390	963.037
953.379	953.142	952.905	952.668	952.431	952.194	951.957	951.720	951.483	951.246	951.009	949.726	949.489	949.252	949.015	948.778
1270.614	1269.604	1268.594	1267.584	1266.574	1265.564	1264.554	1263.544	1262.534	1261.524	1260.514	1259.504	1258.494	1257.484	1256.474	1255.464
1262.470	1262.284	1262.100	1261.916	1261.732	1261.548	1261.364	1261.180	1260.996	1260.812	1260.628	1260.444	1260.260	1257.995	1257.585	1257.175
1256.402	1256.427	1256.063	1255.703	1255.343	1254.983	1254.623	1254.263	1253.903	1253.543	1253.183	1252.823	1252.463	1253.519	1253.250	1252.990
1252.739	1252.495	1252.256	1252.020	1251.784	1251.548	1251.312	1251.076	1250.840	1250.604	1250.368	1250.132	1249.896	1253.519	1253.250	1252.990
1702.228	1701.993	1701.758	1701.523	1701.288	1701.053	1700.818	1700.583	1700.348	1700.113	1699.878	1699.643	1699.408	1696.647	1696.577	1696.504
1694.342	1693.792	1693.253	1692.720	1692.212	1691.711	1691.225	1690.748	1690.281	1689.840	1689.407	1688.988	1688.564	1689.407	1689.168	1688.930
1686.479	1687.616	1687.434	1687.104	1686.768	1686.446	1686.130	1685.834	1685.552	1685.277	1685.014	1684.760	1684.515	1689.407	1689.168	1688.930
1684.279	1684.952	1683.831	1683.617	1683.408	1683.204	1683.004	1682.804	1682.604	1682.404	1682.204	1682.004	1681.804	1684.760	1684.515	1684.270



Table C-3. Final contours, case 2.b.

THE NEW CONTOUR VALUES, Y, FOLLOW														
200.000	219.439	218.860	218.321	217.765	217.210	216.659	216.112	215.568	215.029	214.495	213.967	213.446	212.930	212.430
212.931	212.424	211.925	211.434	210.952	210.479	210.016	209.561	209.115	208.680	208.254	207.837	207.430	207.036	206.656
207.032	206.643	206.263	205.893	205.533	205.182	204.840	204.508	204.184	203.868	203.561	203.260	202.966	202.686	202.416
202.637	202.394	202.116	201.842	201.571	201.304	201.040	200.778	200.518	200.259	200.000	199.744	199.492	199.244	199.000
251.623	251.065	250.508	249.954	249.401	248.850	248.302	247.757	247.216	246.679	246.148	245.621	245.101	244.586	244.076
244.588	244.082	243.584	243.095	242.615	242.144	241.683	241.231	240.789	240.355	239.930	239.514	239.107	238.708	238.317
238.708	238.317	237.936	237.563	237.200	236.847	236.504	236.170	235.846	235.530	235.222	234.921	234.626	234.336	234.050
234.337	234.052	233.771	233.494	233.219	232.948	232.679	232.413	232.149	231.885	231.623	231.364	231.109	230.858	230.610
309.443	308.891	308.341	307.793	307.246	306.702	306.160	305.620	305.084	304.551	304.022	303.498	302.980	302.466	301.956
296.628	296.234	295.848	295.470	295.102	294.745	294.399	294.063	293.738	293.421	293.114	292.813	292.518	292.228	291.942
292.228	291.938	291.653	291.369	291.087	290.807	290.531	290.257	289.985	289.713	289.443	289.177	288.915	288.656	288.400
432.028	431.450	430.874	430.301	429.728	429.156	428.586	428.019	427.456	426.894	426.334	425.776	425.220	424.666	424.114
432.163	431.604	431.044	430.484	429.924	429.364	428.804	428.244	427.684	427.124	426.564	426.004	425.444	424.884	424.324
429.398	428.997	428.601	428.213	427.835	427.469	427.117	426.779	426.453	426.139	425.834	425.535	425.240	424.948	424.658
424.947	424.653	424.359	424.064	423.768	423.474	423.181	422.890	422.601	422.314	422.028	421.744	421.462	421.182	420.904
684.758	684.237	683.717	683.196	682.676	682.156	681.635	681.114	680.591	680.069	679.548	679.029	678.516	678.006	677.496
678.011	677.515	677.032	676.561	676.104	675.660	675.228	674.806	674.392	673.982	673.574	673.166	672.756	672.346	671.936
672.344	671.933	671.524	671.124	670.735	670.361	670.004	669.665	669.343	669.034	668.735	668.441	668.148	667.856	667.564
667.852	667.488	667.138	666.804	666.485	666.181	665.891	665.615	665.353	665.104	664.866	664.638	664.420	664.202	663.984
960.871	960.191	959.511	958.831	958.151	957.471	956.791	956.111	955.431	954.751	954.071	953.391	952.711	952.031	951.351
973.795	972.292	972.503	972.328	972.158	971.988	971.822	971.661	971.504	971.352	971.204	971.061	970.922	970.788	970.654
968.087	967.678	967.275	966.882	966.502	966.140	965.795	965.468	965.156	964.859	964.571	964.287	964.003	963.720	963.438
963.718	963.428	963.133	962.835	962.533	962.230	961.927	961.624	961.324	961.024	960.726	960.430	960.136	959.844	959.552
1270.414	1269.827	1269.239	1268.653	1268.069	1267.487	1266.907	1266.332	1265.760	1265.194	1264.634	1264.081	1263.536	1262.992	1262.448
1263.000	1262.474	1261.959	1261.456	1260.964	1260.485	1260.018	1259.562	1259.117	1258.683	1258.259	1257.844	1257.440	1257.036	1256.632
1257.045	1256.661	1256.288	1255.927	1255.578	1255.241	1254.914	1254.605	1254.304	1254.013	1253.731	1253.455	1253.186	1252.922	1252.660
1252.921	1252.660	1252.401	1252.146	1251.893	1251.642	1251.393	1251.147	1250.901	1250.658	1250.414	1250.172	1249.932	1249.694	1249.458
1702.228	1701.600	1701.973	1700.348	1699.726	1699.108	1698.494	1697.886	1697.284	1696.689	1696.103	1695.525	1694.957	1694.390	1693.822
1694.399	1693.851	1693.315	1692.791	1692.279	1691.780	1691.293	1690.820	1690.361	1689.915	1689.483	1689.065	1688.660	1688.266	1687.882
1686.270	1685.893	1685.530	1685.180	1684.844	1684.520	1684.209	1683.910	1683.623	1683.346	1683.080	1682.823	1682.575	1682.328	1682.084
1682.336	1682.104	1681.876	1681.653	1681.445	1681.246	1681.056	1680.874	1680.700	1680.534	1680.376	1680.224	1680.076	1679.932	1679.792

Table C-4. Final contours, case 2.ci.

LINE	AREA	CONTOUR	VALUES	%	FOLLOW							
226.690	282.832	225.655	228.459	231.234	233.970	236.655	239.278	241.628	244.294	246.665	248.929	251.075
253.090	254.964	256.685	258.237	259.618	260.810	261.005	262.594	263.160	263.520	263.643	263.533	263.189
262.640	261.791	260.740	259.459	257.953	256.229	254.995	252.160	249.834	247.327	244.517	241.817	238.637
235.725	232.492	229.151	226.714	222.193	218.602	214.951	211.253	207.519	203.764	200.000		
251.623	254.652	257.687	260.718	263.712	266.652	269.545	272.366	275.145	277.797	280.346	282.804	285.152
267.349	269.369	271.215	272.907	274.439	275.772	276.662	277.065	278.308	278.968	279.868	279.818	279.515
297.935	297.079	295.672	294.634	293.068	291.265	289.216	286.935	284.449	281.778	278.928	275.925	272.776
267.535	266.119	262.565	258.909	255.172	251.353	247.456	243.493	239.492	235.520	231.623		
309.443	313.519	317.595	321.665	325.688	329.646	333.542	337.363	341.075	344.657	348.113	351.445	354.628
357.618	360.330	362.951	365.314	367.461	369.345	370.917	372.171	373.126	373.798	374.180	374.269	373.972
373.330	372.334	371.011	369.385	367.455	365.207	362.637	359.769	356.641	353.273	349.677	345.862	341.915
337.760	333.404	328.673	324.214	319.450	314.581	309.623	304.600	299.541	294.463	289.343		
402.028	407.543	413.038	418.955	425.219	431.849	438.790	446.033	453.573	461.408	469.539	477.960	486.665
506.862	510.658	514.163	517.414	520.328	522.901	525.111	526.937	528.362	529.371	529.958	530.118	529.849
529.169	528.019	526.450	524.470	522.061	519.242	516.025	512.428	508.470	504.176	499.571	494.685	489.543
484.171	478.590	472.617	466.268	460.760	454.511	448.146	441.690	435.170	428.608	422.028		
664.757	693.500	702.203	710.828	719.341	727.712	735.913	743.920	751.708	759.253	766.528	773.507	780.161
786.463	792.381	797.887	802.950	807.539	811.626	815.180	818.172	820.578	822.373	823.541	824.065	823.934
823.139	821.676	819.544	816.751	813.310	809.242	804.571	799.327	793.544	787.256	780.500	773.310	765.723
757.770	749.480	740.882	732.003	722.872	713.521	703.986	694.304	684.514	674.654	664.758		
960.726	967.348	1014.001	1030.517	1046.668	1063.067	1079.094	1094.107	1109.953	1124.857	1139.303	1153.231	1166.576
1179.271	1191.249	1202.442	1212.781	1222.600	1230.635	1236.024	1240.309	1249.436	1253.359	1256.035	1257.430	1257.518
1256.265	1253.726	1249.649	1244.675	1238.238	1230.584	1221.770	1211.859	1200.921	1189.030	1176.260	1162.684	1148.372
1133.523	1117.812	1101.693	1085.097	1068.088	1050.725	1033.071	1015.185	997.127	978.954	960.726		
1270.414	1275.696	1280.964	1286.207	1291.410	1296.559	1301.640	1306.637	1311.533	1316.308	1320.943	1325.417	1329.706
1333.786	1337.633	1341.221	1344.522	1347.511	1350.162	1352.451	1354.354	1355.950	1356.922	1357.533	1357.733	1357.454
1356.712	1355.509	1353.852	1351.750	1349.218	1346.273	1342.938	1339.236	1335.192	1330.532	1326.184	1321.275	1316.130
1310.775	1305.234	1299.529	1293.683	1287.717	1281.649	1275.468	1269.183	1262.825	1256.226	1250.144		
1702.228	1701.697	1701.166	1700.636	1700.109	1699.584	1699.062	1698.544	1698.030	1697.521	1697.017	1696.519	1696.026
1695.521	1695.061	1694.589	1694.123	1693.664	1693.213	1692.764	1692.316	1691.871	1691.432	1690.996	1690.562	1690.250
1689.654	1689.404	1689.062	1688.705	1688.335	1687.972	1687.614	1687.263	1686.917	1686.577	1686.244	1685.913	1685.589
1685.268	1684.952	1684.640	1684.331	1684.025	1683.722	1683.420	1683.121	1682.822	1682.525	1682.228		

Table C-5. Final contours, case 2.C.2.

THE NEW CONTOUR VALUES, Y, FOLLOV												
220.000	232.574	225.142	227.698	230.232	232.735	235.198	237.610	239.962	242.243	244.403	246.550	248.554
250.442	252.202	253.622	255.220	256.593	257.720	258.660	259.402	259.937	260.256	260.355	260.227	259.869
259.280	258.461	257.414	256.185	254.659	252.965	251.073	248.994	246.739	244.321	241.751	239.043	236.209
233.260	230.209	227.068	223.848	220.560	217.215	213.824	210.398	206.946	203.477	200.000		
251.623	254.387	257.181	259.990	262.787	265.552	268.275	270.949	273.563	276.104	278.562	280.926	283.187
285.327	287.332	289.187	290.877	292.368	293.708	294.821	295.716	296.392	296.811	296.995	296.924	296.569
295.985	295.117	293.992	292.618	291.000	289.148	287.075	284.796	282.337	279.682	276.875	273.917	270.824
267.614	264.301	260.896	257.407	253.846	250.224	246.555	242.849	239.119	235.374	231.623		
309.843	312.369	315.475	318.666	321.824	324.931	327.987	330.992	333.933	336.779	339.523	342.195	344.810
347.324	349.679	351.847	353.825	355.606	357.172	358.504	359.591	360.427	361.022	361.390	361.498	361.247
360.580	359.556	358.265	356.739	354.956	352.905	350.596	348.053	345.302	342.360	339.231	335.913	332.433
328.855	325.224	321.524	317.726	313.833	309.864	305.835	301.762	297.660	293.549	289.443		
482.028	485.538	489.186	492.859	496.485	499.991	503.368	506.619	509.652	512.467	515.056	517.419	519.556
486.358	489.263	491.944	494.342	496.458	498.222	500.102	501.506	502.600	503.403	504.010	504.467	504.530
503.870	502.357	500.893	499.043	496.935	494.569	491.946	489.038	485.882	482.495	478.884	475.030	470.940
486.773	462.654	458.548	454.299	449.861	445.303	440.687	436.037	431.362	426.686	422.028		
684.758	693.580	702.347	711.058	719.730	728.360	736.919	745.379	753.715	761.903	769.943	778.035	786.035
813.218	830.484	847.336	863.718	879.584	894.889	909.591	923.639	936.984	949.588	961.332	972.431	977.454
971.427	959.366	946.416	932.695	918.235	903.074	887.251	870.809	853.708	836.240	818.822	799.793	781.024
764.526	752.893	743.635	734.202	724.578	714.804	704.920	694.953	684.921	674.849	664.758		
980.726	996.141	1011.526	1026.850	1042.081	1057.184	1072.120	1086.846	1101.319	1115.484	1129.283	1146.126	1169.417
1195.11	1221.161	1245.940	1270.014	1293.157	1315.340	1329.771	1340.535	1350.556	1359.797	1368.228	1375.828	1379.114
1374.609	1365.793	1356.149	1345.701	1334.479	1322.518	1305.427	1281.833	1257.273	1231.821	1205.551	1178.548	1150.682
1126.303	1107.752	1092.429	1076.727	1060.706	1044.422	1027.926	1011.265	994.484	977.624	960.726		
1270.414	1273.892	1277.367	1280.834	1284.289	1287.728	1291.146	1294.535	1297.888	1301.196	1304.405	1307.622	1310.710
1313.688	1316.535	1319.224	1321.730	1324.052	1326.073	1327.834	1329.336	1330.587	1331.584	1332.329	1332.829	1333.115
1379.410	1370.594	1360.950	1350.502	1339.280	1327.319	1314.694	1301.671	1288.180	1274.269	1259.937	1245.264	1230.244
1293.650	1289.694	1285.465	1281.117	1276.684	1272.178	1267.628	1263.062	1258.485	1253.841	1249.144		
1702.228	1701.680	1701.140	1700.596	1700.058	1699.513	1699.974	1699.436	1698.897	1698.377	1697.854	1696.336	1695.825
1695.321	1694.828	1694.338	1693.869	1693.365	1692.823	1692.469	1692.023	1691.586	1691.156	1690.734	1690.319	1689.912
1689.313	1688.122	1686.738	1685.160	1683.491	1681.687	1679.791	1686.950	1686.617	1686.292	1685.974	1685.662	1685.356
1685.055	1684.759	1684.467	1684.178	1683.893	1683.611	1683.331	1683.053	1682.777	1682.502	1682.228		

Table C-6. Final contours, case 2.c.3.

THE NEW CONTOUR VALUES, Y, FOLLOW												
220.000	221.845	223.681	225.509	227.313	229.089	230.828	232.526	234.167	235.753	237.272	238.716	240.077
241.348	242.519	243.583	244.530	245.353	246.044	246.599	247.120	247.599	248.026	248.407	248.740	249.024
246.101	245.388	244.519	243.498	242.326	241.012	239.554	237.957	236.257	234.461	232.569	230.588	228.524
225.855	223.507	221.089	218.609	216.071	213.480	210.843	208.168	205.462	202.736	200.000		
251.623	253.498	255.392	257.293	259.177	261.030	262.846	264.621	266.350	268.025	269.639	271.186	272.660
274.050	275.345	276.535	277.605	278.550	279.355	280.008	280.498	280.816	280.956	280.915	280.693	280.287
279.700	278.935	278.004	276.914	275.671	274.278	272.735	271.046	269.215	267.249	265.161	262.964	260.672
258.303	255.866	253.369	250.814	248.203	245.537	242.819	240.057	237.263	234.447	231.623		
309.443	311.420	313.526	315.697	317.843	319.940	321.993	324.009	325.987	327.907	329.763	331.568	333.333
335.036	336.646	338.135	339.505	340.744	341.834	342.746	343.458	343.962	344.255	344.343	344.224	343.815
442.228	445.418	448.680	452.348	455.794	459.206	462.618	466.027	469.418	472.725	475.932	479.175	482.583
486.080	489.479	492.681	495.692	498.535	501.184	503.567	505.609	507.274	508.581	509.611	510.362	510.567
509.876	508.291	506.130	503.646	500.898	497.879	494.560	491.005	487.164	483.176	479.013	474.675	470.194
465.732	461.411	457.144	452.802	448.382	443.943	439.518	435.114	430.730	426.368	422.028		
664.758	656.120	706.490	716.309	726.334	736.809	747.665	758.868	770.505	782.655	796.988	813.373	831.732
852.453	874.768	897.220	919.475	941.503	962.353	982.069	1001.785	1019.385	1035.244	1048.852	1058.086	1061.185
1057.956	1046.151	1033.429	1016.170	997.242	977.029	955.720	933.448	910.379	886.753	862.903	839.272	816.819
796.596	779.055	764.002	750.342	737.126	724.257	711.804	699.726	687.912	676.278	664.758		
946.726	946.702	1015.781	1032.198	1048.818	1066.111	1083.912	1101.890	1120.103	1139.021	1159.881	1183.592	1210.260
1239.961	1271.244	1302.237	1329.025	1346.090	1362.660	1378.627	1393.615	1407.198	1419.100	1429.286	1436.598	1430.352
1436.553	1428.600	1417.146	1403.576	1388.502	1372.372	1355.413	1337.697	1319.233	1280.330	1256.251	1223.058	1190.661
1161.109	1136.334	1115.348	1095.497	1075.419	1055.263	1035.100	1016.277	997.673	979.099	960.726		
1270.414	1273.743	1276.935	1279.784	1282.576	1285.649	1288.068	1290.438	1292.774	1295.074	1299.326	1303.099	1306.958
1315.456	1320.326	1325.048	1333.859	1350.891	1367.461	1383.426	1398.116	1411.989	1423.941	1434.087	1441.399	1444.153
1441.354	1435.401	1421.491	1407.377	1393.303	1377.170	1360.214	1342.498	1324.014	1315.513	1309.511	1303.673	1298.513
1293.516	1288.477	1284.093	1279.828	1275.396	1270.916	1266.612	1262.487	1258.424	1254.393	1250.514		
1702.228	1701.647	1701.066	1700.481	1699.896	1699.317	1698.746	1698.179	1697.615	1697.057	1696.506	1695.961	1695.423
1694.694	1694.377	1693.969	1693.366	1692.875	1692.393	1691.923	1691.467	1691.019	1690.579	1690.149	1689.733	1689.329
1686.934	1688.549	1688.173	1687.806	1687.449	1687.104	1686.769	1686.446	1686.131	1685.825	1685.527	1685.238	1684.936
1684.684	1684.418	1684.161	1683.910	1683.660	1683.413	1683.170	1682.932	1682.696	1682.461	1682.228		

Table C-7. Final contours, case 2.c.4.

THE NEW CONTOUR VALUES, Y, FOLLOW												
220.000	221.649	223.694	225.532	227.357	229.164	230.947	232.699	234.414	236.083	237.699	239.252	240.734
242.133	243.440	244.642	245.748	246.688	247.511	248.166	248.704	249.057	249.234	249.244	249.067	248.768
246.163	247.436	248.522	249.433	249.170	249.740	249.153	239.418	231.545	233.430	231.211	228.899	
226.504	224.034	221.504	218.910	216.286	213.617	210.920	208.203	205.473	202.737	200.000		
251.623	253.892	255.355	257.210	259.064	260.901	262.716	264.502	266.251	267.956	269.609	271.205	272.731
274.176	275.526	276.771	277.898	278.896	279.753	280.459	281.004	281.391	281.583	281.605	281.437	281.075
280.520	279.777	278.647	277.734	276.443	274.982	273.359	271.585	269.671	267.629	265.471	263.208	260.853
258.420	255.916	253.349	250.728	248.061	245.356	242.522	239.464	236.096	232.344	231.623		
309.443	311.824	314.207	316.594	318.982	321.367	323.741	326.099	328.431	330.730	332.886	335.188	337.320
339.366	341.307	343.125	344.802	346.317	347.652	348.789	349.712	350.405	350.856	351.058	350.994	350.662
350.063	349.197	348.071	346.688	345.061	343.202	341.126	338.853	336.401	333.790	331.038	328.166	325.192
322.133	319.003	315.814	312.579	309.309	306.014	302.702	299.360	296.058	292.744	289.443		
482.028	485.709	489.391	493.072	496.753	499.429	499.408	467.751	471.380	474.973	478.514	481.986	485.366
488.632	491.756	494.710	497.464	499.986	502.286	504.214	505.862	507.163	508.095	508.641	508.786	508.522
507.847	506.762	505.276	503.402	501.157	498.584	495.646	492.432	488.951	485.234	481.309	477.208	473.956
468.585	464.11	459.566	454.960	450.309	445.628	440.926	436.211	431.487	426.758	422.011		
684.758	689.616	714.513	729.483	744.557	759.753	775.078	790.525	806.069	821.667	837.259	852.853	878.494
903.927	928.912	953.321	976.995	999.774	1021.998	1042.910	1061.184	1076.824	1094.873	1109.216	1121.782	1127.320
1128.907	1106.868	1081.351	1071.105	1055.249	1034.889	1013.156	990.193	966.154	941.196	915.473	889.135	862.324
837.470	818.190	801.075	783.899	766.720	749.579	732.498	715.486	699.536	681.634	664.758		
980.726	1000.366	1020.022	1039.705	1059.422	1079.168	1099.927	1118.668	1138.343	1157.890	1177.226	1199.724	1220.739
1260.672	1291.908	1322.298	1351.684	1373.324	1389.434	1404.547	1418.545	1431.322	1442.782	1452.850	1461.468	1465.130
1460.350	1450.611	1439.418	1426.823	1412.903	1397.747	1381.461	1364.160	1339.492	1308.613	1276.690	1243.878	1210.323
1179.637	1155.419	1134.309	1112.934	1091.375	1069.696	1047.945	1026.156	1004.350	982.538	960.726		
1270.914	1275.657	1280.936	1286.285	1291.736	1297.314	1303.040	1308.927	1314.976	1321.182	1327.523	1333.970	1340.476
1346.987	1353.432	1359.733	1365.881	1371.825	1378.235	1400.348	1423.346	1445.123	1447.583	1457.651	1466.269	1469.931
1485.151	1455.412	1444.219	1431.684	1417.704	1402.948	1386.262	1368.761	1351.242	1335.198	1342.912	1335.469	1327.947
1320.413	1312.922	1305.514	1299.220	1291.055	1284.025	1277.123	1270.336	1263.641	1257.011	1250.414		
1702.228	1701.648	1701.068	1700.491	1699.917	1699.347	1698.782	1698.223	1697.671	1697.120	1696.569	1696.063	1695.545
1695.036	1694.536	1694.047	1693.567	1693.096	1692.636	1692.185	1691.743	1691.311	1690.886	1690.471	1690.064	1689.665
1689.275	1688.892	1688.517	1688.151	1687.792	1687.441	1687.097	1686.762	1686.433	1686.113	1685.800	1685.494	1685.195
1684.902	1684.616	1684.335	1684.060	1683.793	1683.523	1683.260	1682.999	1682.741	1682.484	1682.228		

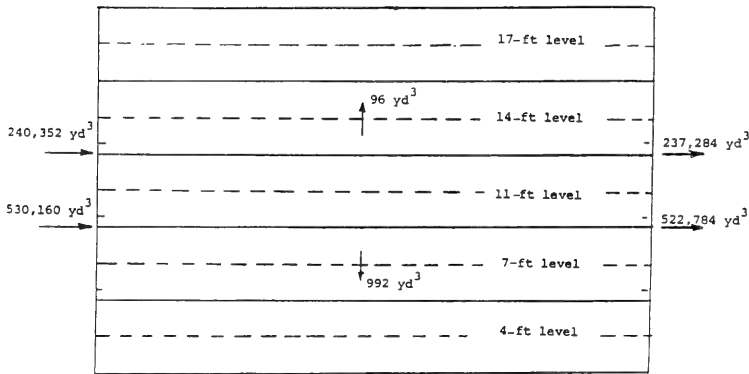
Table C-8. Final contours, case 3 (17 weeks plus sediment addition).

220.000	219.071	218.148	217.236	216.342	215.470	214.625	213.812	213.033	212.291	211.589	210.926	210.303
209.719	209.172	208.660	208.160	207.729	207.355	206.903	206.522	206.158	205.809	205.473	205.147	204.829
208.516	208.047	207.601	207.176	206.772	206.395	206.052	205.740	205.450	205.181	204.932	204.694	204.466
200.950	200.773	200.616	200.480	200.365	200.265	200.185	200.121	200.071	200.033	200.000		
251.623	250.708	249.802	248.909	248.035	247.187	246.370	245.589	244.848	244.150	243.495	242.884	242.317
241.792	241.307	240.857	240.440	240.049	239.682	239.333	238.998	238.673	238.355	238.039	237.724	237.408
231.089	231.67	231.317	231.011	230.758	230.541	230.366	230.232	230.144	230.086	230.051	230.033	230.025
232.909	233.676	232.467	232.282	232.119	231.978	231.860	231.768	231.696	231.651	231.623		
309.443	308.558	307.680	306.817	305.980	305.175	304.411	303.694	303.027	302.414	301.855	301.349	300.896
300.462	300.131	299.808	299.517	299.249	298.999	298.757	298.516	298.288	298.067	297.850	297.634	297.418
296.781	296.423	296.042	295.640	295.220	294.784	294.336	293.883	293.429	292.979	292.541	292.120	291.723
291.353	291.013	290.703	290.422	290.167	289.936	289.735	289.578	289.478	289.440	289.443		
442.028	441.318	440.621	439.951	439.321	438.745	438.232	437.789	437.421	437.129	436.913	436.770	436.696
436.603	436.722	436.798	436.699	437.013	437.127	437.225	437.289	437.302	437.252	437.136	436.952	436.699
436.373	435.968	435.482	434.916	434.278	433.576	432.822	432.026	431.198	430.354	429.508	428.679	427.882
427.158	426.422	425.764	425.148	424.568	424.020	423.508	423.043	422.643	422.312	422.028		
684.758	684.608	684.472	684.364	684.297	684.263	684.331	684.408	684.639	684.907	685.250	685.665	686.145
686.652	687.269	687.876	688.502	689.122	689.717	690.266	690.747	691.140	691.424	691.581	691.597	691.459
691.160	690.696	690.068	689.284	688.352	687.289	686.110	684.837	683.490	682.091	680.661	679.221	677.788
676.378	675.004	673.675	672.398	671.175	670.006	668.887	667.813	666.774	665.760	664.758		
980.726	991.845	1002.983	1014.160	1025.389	1036.678	1048.028	1059.430	1070.864	1082.300	1093.693	1108.458	1129.498
1159.760	1179.183	1203.166	1226.603	1249.386	1271.402	1292.545	1312.709	1331.801	1349.757	1366.447	1381.880	1394.956
1381.020	1364.718	1347.118	1328.266	1308.222	1287.065	1264.885	1241.782	1217.863	1193.239	1168.017	1142.310	1116.214
1091.233	1071.103	1054.242	1031.598	1008.515	985.527	962.356	939.412	916.497	893.605	870.726		
1270.414	1262.593	1249.812	1231.106	1215.506	1202.036	1184.706	1173.516	1170.450	1184.476	1196.543	1213.058	1236.406
1463.017	1449.303	1435.137	1420.383	1404.997	1388.935	1371.155	1352.624	1332.624	1312.616	1291.623	1268.044	1242.517
1689.958	1681.451	1668.760	1648.974	1627.783	1605.291	1581.617	1556.892	1531.254	1504.845	1477.803	1450.263	1424.348
1397.634	1379.718	1365.183	1350.630	1336.109	1321.650	1307.270	1292.970	1278.740	1264.563	1250.414		
1702.228	1701.147	1700.070	1699.001	1697.943	1696.900	1695.876	1694.874	1693.897	1692.948	1692.029	1691.143	1690.292
1689.478	1686.702	1687.966	1687.269	1686.613	1685.998	1685.424	1684.891	1684.399	1683.946	1683.530	1683.154	1682.817
1690.821	1688.600	1688.010	1687.007	1685.535	1684.491	1683.776	1683.287	1682.916	1682.633	1682.433	1682.301	1682.228
1681.226	1681.260	1681.349	1681.451	1681.523	1681.626	1681.753	1681.894	1682.048	1682.216	1682.397	1682.591	1682.798
2160.943	2179.761	2176.582	2171.412	2176.254	2175.111	2173.988	2172.888	2171.815	2170.771	2169.760	2168.784	2167.840
2160.949	2169.949	2165.282	2156.516	2163.797	2163.125	2162.500	2161.925	2161.501	2161.200	2160.919	2160.647	2160.383
2159.468	2159.217	2159.008	2158.840	2159.710	2158.617	2158.559	2158.533	2158.539	2158.573	2158.634	2158.719	2158.828
2158.956	2159.103	2159.267	2159.445	2159.636	2159.838	2160.048	2160.264	2160.480	2160.715	2160.943		

Table C-9. Final contours, case 4.

THE NEW CONTOUR VALUES, Y, FOLLOW

220.000	221.328	223.967	225.270	226.555	227.817	229.050	230.248	231.406	232.517	233.575	234.573
235.500	236.361	237.136	237.823	238.415	239.008	239.584	239.693	239.711	239.601	239.358	239.982
230.471	237.826	237.489	236.183	235.110	233.957	233.688	231.309	229.827	228.249	226.582	224.033
221.121	217.172	217.169	215.120	213.032	210.910	208.760	206.588	204.401	202.203	200.000	
218.041	209.584	201.081	192.592	184.709	176.736	169.036	162.587	157.463	152.663	148.216	144.231
306.068	307.041	308.046	308.693	309.634	310.260	310.144	311.134	311.368	311.456	311.395	311.181
301.287	309.806	308.771	307.786	306.654	305.588	303.988	302.444	300.825	299.079	297.235	295.301
291.200	289.056	286.853	284.601	282.304	279.980	277.623	275.242	272.844	270.400	268.041	
402.028	404.072	406.915	409.354	411.787	414.207	416.608	418.984	421.324	423.622	425.865	428.045
472.161	474.070	475.857	477.506	478.999	480.317	481.462	482.356	483.045	483.493	483.688	483.621
482.685	481.815	480.684	479.299	477.678	475.822	473.760	471.505	469.075	466.490	463.766	460.922
486.938	481.825	480.650	479.221	477.440	475.241	472.661	470.744	468.544	466.128	463.552	460.857
571.553	577.760	581.968	586.160	590.395	594.611	598.826	603.032	607.222	611.386	615.512	619.581
607.053	613.210	618.781	624.843	631.285	638.113	645.265	652.679	660.315	668.159	676.282	684.683
651.550	658.258	666.560	675.285	684.417	693.901	703.653	713.694	724.053	734.750	745.819	757.287
695.307	698.248	699.126	699.971	698.790	697.595	696.391	695.182	693.972	692.763	691.553	690.344
800.571	805.276	810.010	814.779	819.583	824.422	829.294	834.200	839.140	844.114	849.122	854.164
736.443	763.001	773.528	781.319	788.666	795.628	802.160	807.555	812.674	817.529	822.130	826.519
817.756	815.288	811.550	809.713	807.933	806.199	804.569	802.974	801.425	799.921	798.459	797.036
721.847	711.788	701.903	692.231	682.837	673.671	664.784	656.129	647.745	639.571	631.657	624.043
728.021	737.477	750.945	764.400	777.975	791.564	805.222	818.958	832.772	846.656	860.576	874.511
902.091	915.504	928.618	941.148	952.669	963.766	973.865	982.619	989.511	994.657	999.053	1002.653
1001.281	995.034	983.025	966.251	947.940	928.665	907.084	882.619	857.405	831.405	811.917	798.821
857.866	842.330	826.762	811.527	795.710	769.314	742.936	718.634	696.469	676.509	658.802	643.397
803.662	819.058	832.453	845.888	859.370	872.914	886.531	900.226	913.994	927.815	941.689	955.634
908.474	995.402	1007.821	1019.720	1030.586	1040.217	1049.517	1057.462	1065.052	1072.282	1079.160	1085.680
1071.178	1066.270	1053.621	1037.400	1019.600	1000.242	979.346	957.044	933.382	908.422	882.116	864.551
937.092	921.841	906.525	891.263	875.934	860.735	845.698	830.853	816.253	801.957	787.926	774.116
886.720	886.961	893.174	898.355	905.475	911.517	917.462	923.272	928.988	934.533	939.910	945.105
1050.890	1059.450	1063.766	1067.916	1071.574	1075.002	1078.004	1080.702	1083.166	1085.446	1087.500	1089.340
1069.650	1063.310	1061.189	1058.911	1056.147	1052.478	1047.815	1042.752	1036.752	1029.351	1020.116	1009.740
1028.724	1023.423	1018.933	1014.276	1009.372	994.501	969.500	942.863	917.173	891.773	867.730	845.166
1270.414	1270.105	1269.976	1269.846	1269.716	1269.666	1269.556	1269.445	1269.333	1269.220	1269.106	1268.990
1266.353	1266.031	1265.716	1265.376	1265.043	1264.708	1264.358	1264.004	1263.524	1262.894	1262.150	1261.200
1261.695	1261.275	1260.685	1260.047	1259.260	1258.350	1257.305	1256.156	1254.852	1253.342	1251.574	1250.500
1255.640	1255.132	1254.620	1254.103	1253.583	1253.059	1252.533	1252.005	1251.476	1250.945	1250.414	



Case 2.a.

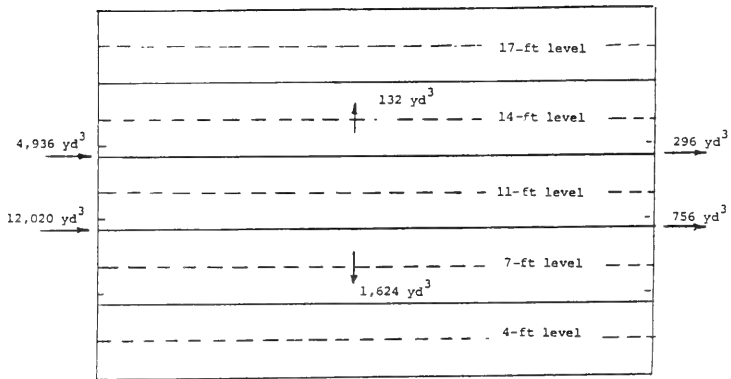
Period Considered: Twelve months, January through December, using 1975 WIS wave hindcasts

Sediment Budget Summary:

Amount of sediment added:	None
Amount of sediment transported shoreward from nourished region:	992 yd <sup>3</sup>
Amount of sediment transported seaward from nourished region:	96 yd <sup>3</sup>
Net amount of sediment transported alongshore from nourished region:	10,444 yd <sup>3</sup>
Total amount of sediment transported from nourished region:	=9,356 yd <sup>3</sup>

Figure C-1. Schematic illustration of sediment volumes transported from region, case 2.a.





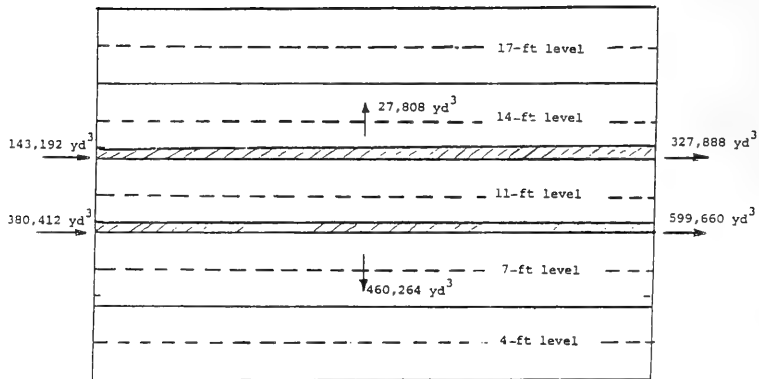
Case No. 2b.

Period considered: Twelve months, January through December, using 1975  
WIS wave hindcasts, but wave angle always set equal  
to 0°.

Sediment Budget Summary:

Amount of sediment added:	None
Amount of sediment transported shoreward from nourished region:	1,624 yd <sup>3</sup>
Amount of sediment transported seaward from nourished region:	132 yd <sup>3</sup>
Net amount of sediment transported alongshore from nourished region:	-15,904 yd <sup>3</sup>
Total amount of sediment transported from nourished region:	-14,148 yd <sup>3</sup>

Figure C-2. Schematic illustration of sediment volumes transported from region, case 2.b.



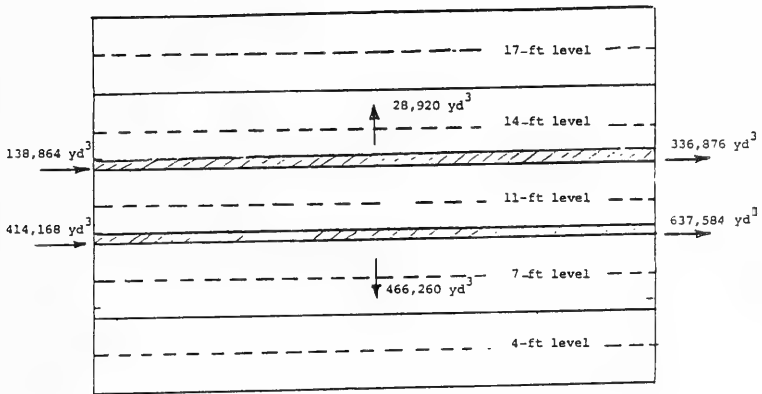
Case 2.c1.

Period considered: Twelve months, January through December, using 1975  
WIS wave hindcasts.

Sediment Budget Summary:

Amount of sediment added:	1,452,000 yd <sup>3</sup> (on 7- and 11-ft contours)
Amount of sediment transported shoreward from nourished region:	460,264 yd <sup>3</sup> (31.7pct)
Amount of sediment transported seaward from nourished region:	27,808 yd <sup>3</sup> (1.9pct)
Net amount of sediment transported alongshore from nourished region:	403,944 yd <sup>3</sup> (27.8pct)
Total amount of sediment transported from nourished region:	892,016 yd <sup>3</sup> (61.4pct)

Figure C-3. Schematic illustration of sediment volumes transported from nourished region, case 2.c1.



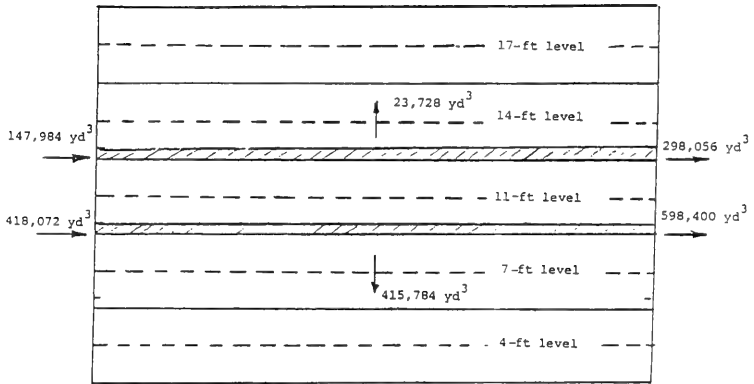
Case 2.c2.

Period considered: Twelve months, April through March, using 1975  
WIS wave hindcasts.

Sediment Budget Summary:

Amount of sediment added:	1,452,000 yd <sup>3</sup>	(on 7- and 11-ft contours)
Amount of sediment transported shoreward from nourished region:	466,260 yd <sup>3</sup>	(32.1pct)
Amount of sediment transported seaward from nourished region:	28,920 yd <sup>3</sup>	(2.0 pct)
Net amount of sediment transported alongshore from nourished region:	421,428 yd <sup>3</sup>	(29.0pct)
Total amount of sediment transported from nourished region:	916,608 yd <sup>3</sup>	(63.1pct)

Figure C-4. Schematic illustration of sediment volumes transported from nourished region, case 2.c2.



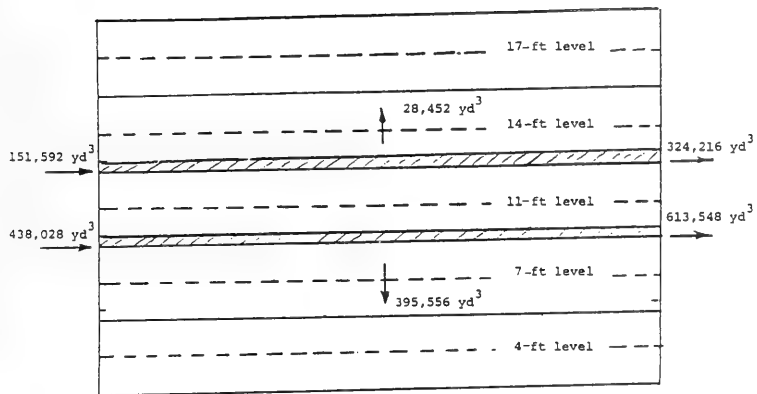
Case 2.c3.

Period considered: Twelve months, July through June, using 1975  
WIS wave hindcasts.

Sediment Budget Summary:

Amount of sediment added:	1,452,000 yd <sup>3</sup> (on 7- and 11-ft contour)	
Amount of sediment transported shoreward from nourished region:	415,784 yd <sup>3</sup> (28.6 pct)	
Amount of sediment transported seaward from nourished region:	23,728 yd <sup>3</sup> (1.6 pct)	
Net amount of sediment transported alongshore from nourished region:	330,400 yd <sup>3</sup> (22.8pct)	
Total amount of sediment transported from nourished region:	769,912 yd <sup>3</sup> (53.0pct)	

Figure C-5. Schematic illustration of sediment volumes transported from nourished region, case 2.c3.



Case 2.c4.

Period considered: Twelve months, October through September, using 1975  
WIS wave hindcasts.

Sediment Budget Summary:

Amount of sediment added: 1,452,000 yd<sup>3</sup> (on 7- and 11-ft contours).

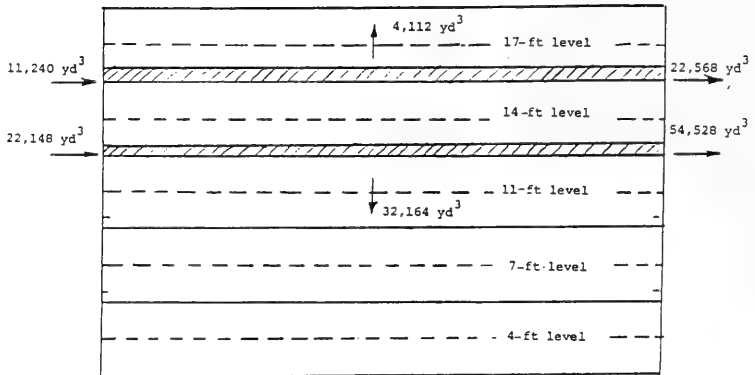
Amount of sediment transported shoreward from nourished region: 395,556 yd<sup>3</sup> (27.2 pct)

Amount of sediment transported seaward from nourished region: 28,452 yd<sup>3</sup> (2.0 pct)

Net amount of sediment transported alongshore from nourished region: 348,144 yd<sup>3</sup> (24.0 pct)

Total amount of sediment transported from nourished region: 772,152 yd<sup>3</sup> (53.2 pct)

Figure C-6. Schematic illustration of sediment volumes transported from nourished region, case 2.c4.



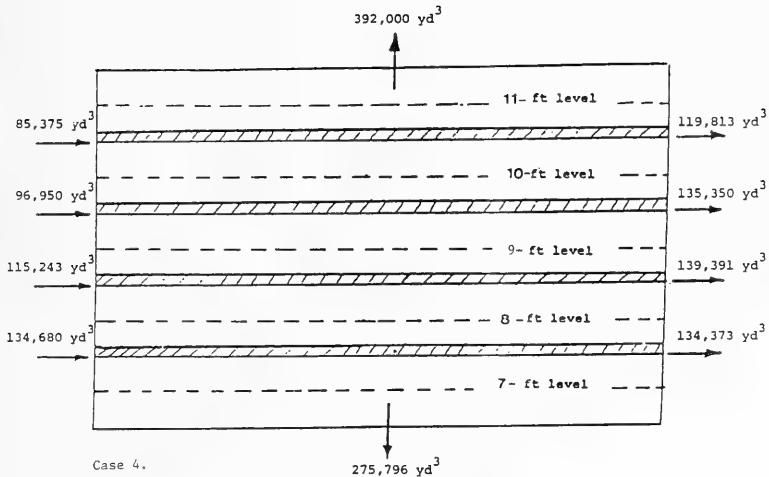
Case 3.

Period considered: Four months, January through April, using 1975 WIS wave hindcasts.

Sediment Budget Summary:

Amount of sediment added	363,000 yd <sup>3</sup> (on 11- and 14-ft contours).
Amount of sediment transported shoreward from nourished region:	32,164 yd <sup>3</sup> (8.9pct)
Amount of sediment transported seaward from nourished region:	4,112 yd <sup>3</sup> (1.1pct)
Net amount of sediment transported alongshore from nourished region:	43,708 yd <sup>3</sup> (12.0pct)
Total amount of sediment transported from nourished region:	79,984 yd <sup>3</sup> (22.0pct)

Figure C-7. Schematic illustration of sediment volumes transported from nourished region, case 3.



Period considered: Twelve months, January through December, using 1975  
WIS wave hindcasts.

**Sediment Budget Summary:**

Amount of sediment added: 1,452,000 yd<sup>3</sup> (on 7-, 8-, 9-, and 10-ft contours).

Amount of sediment transported shoreward from nourished region: 275,796 yd<sup>3</sup> (19.0pct)

Amount of sediment transported seaward from nourished region: 392,000 yd<sup>3</sup> (27.0pct)

Net amount of sediment transported alongshore from nourished region: 96,679 yd<sup>3</sup> (6.7pct)

Total amount of sediment transported from nourished region: 764,475 yd<sup>3</sup> (52.6pct)

Figure C-8. Schematic illustration of sediment volumes transported from nourished region, case 4.

APPENDIX D

METHODOLOGY AND PROGRAM LISTING OF COMPUTER PROGRAM WHICH  
 CONVERTS BATHYMETRIC DATA INTO MONOTONICALLY DECREASING DEPTH CONTOURS

In order to simulate prototype shorelines (and in this case to help verify the numerical model via Channel Islands Harbor data), the (x, y, z) data points must be transformed into a form suitable for use in the model (i.e., bars can not be present). First, the bathymetric data have to be put into a form with fixed longshore and offshore spacings (i.e.,  $\Delta x$  and  $\Delta y$  equal constants). This can be accomplished using one of the many available canned programs which do the interpolation. The problem is then one of finding the most suitable value of the constant, A, in the equation  $h = Ay^{2/3}$ . However, as is usually the case, the exact location of the shoreline ( $h = 0$ ) is unknown. In addition, one requires the added constraint is required that the volumes of sediment (or conversely, the water above the profiles) balance. The problem is solved using LaGrange Multipliers and the Newton Raphson technique for non linear equations.

The equation to be minimized is

$$F(A, ydel_1, ydel_2, \dots, ydel_{IMAX}) = \sum_{i=1}^{IMAX} \sum_{j=1}^{IMAX} (h_{meas_{i,j}} - h_{pred_{i,j}})^2 \quad (D-1)$$

where A is the scale parameter in the equilibrium beach profile,  $ydel_i$  are the locations of the shoreline for the IMAX profiles,  $h_{meas}$  is the interpolated depth from the survey, and  $h_{pred}$  is the depth predicted by the equation

$$h_{pred_{i,j}} = A(y_{i,j} - ydel_i)^{2/3} \quad (D-2)$$

The constraint equation is as follows

$$g(A, ydel_1, \dots, ydel_{IMAX}) = V_{pred} = \sum_{i=1}^{IMAX} \Delta x \left\{ \int_{ydel_i}^y f A(y - ydel_i)^{2/3} dy \right\}$$

$$= \sum_{i=1}^{IMAX} \frac{3}{5} \Delta x A(y_f - ydel_i)^{5/3} = V_{meas} \quad (D-3)$$

where  $V_{pred}$  is the predicted volume of water above the profile to the reference datum,  $V_{meas}$  is the measured volume computed from the survey,  $\Delta x$  is the longshore distance between onshore-offshore profiles, and  $y_f$  is the distance offshore to the last point on each of the measured profiles (it was a constant after the interpolation routine was used).



LaGrange Multipliers procedure says to form the quantify  $F^*$  as

$$F^* = F - \lambda g \quad (D-4)$$

take the total differential of equation (D-4)

$$dF^* = dF - \lambda dg = \left( \frac{dF}{dA} dA + \frac{dF}{d(yde1_1)} d(yde1_1) + \dots + \frac{dF}{d(yde1_{IMAX})} d(yde1_{IMAX}) \right) - \lambda \left( \frac{dg}{dA} dA + \frac{dg}{d(yde1_1)} d(yde1_1) + \dots + \frac{dg}{d(yde1_{IMAX})} d(yde1_{IMAX}) \right) \quad (D-5)$$

Rearranging

$$0 = dF^* = \left( \frac{dF}{dA} - \lambda \frac{dg}{dA} \right) dA + \left( \frac{dF}{d(yde1_1)} - \lambda \frac{dg}{d(yde1_1)} \right) d(yde1_1) + \dots \quad (D-6)$$

It is clear that the terms in brackets in equation (D-6) must individually equal zero, however this leaves  $(IMAX + 2)$  unknown ( $ude1_i =$  to  $IMAX, A,$  and  $\lambda$ ) and only  $(IMAX = 1)$  Equations. The  $(IMAX + 2)$ th equation is taken as equation (D-3). The following system of equation then results:

$$0 = \frac{dF}{dA} - \lambda \frac{dg}{dA} = \sum_{i=1}^{IMAX} \sum_{j=1}^{JMAX} [-2(h_{meas_{i,j}} - A(y_{i,j} - yde1_i)^{2/3})(y_{i,j} - yde1_i)^{2/3}] - \lambda \sum_{i=1}^{IMAX} \frac{3}{5} \Delta x (y_f - yde1_i)^{5/3} \quad (D-7-1)$$

$$0 = \frac{dF}{d(y_{del1})} - \lambda \frac{dg}{d(y_{del1})} = \sum_{j=1}^{JMAX} [2(h_{meas1,j} - A(y_{1,j} - y_{del1}))^{2/3} \\ * (2/3 A(y_{1,j} - y_{del1}))^{-1/3} + \lambda \Delta x A (y_f - y_{del1})^{2/3} \\ \vdots \\ \vdots \\ \vdots] \quad (D-7-2)$$

$$0 = \frac{dF}{d(y_{delIMAX})} - \lambda \frac{dg}{d(y_{delIMAX})} = \sum_{j=1}^{JMAX} [2(h_{measIMAX,j} - A(y_{IMAX,j} - y_{delIMAX}))^{2/3} \\ * (2/3 A(y_{IMAX,j} - y_{delIMAX}))^{-1/3}] + \lambda \Delta x A (y_f - y_{delIMAX})^{2/3} \\ (D-7-(IMAX+1))$$

$$V_{meas} = \sum_{i=1}^{IMAX} (3/5 \Delta x A (y_f - y_{delI})^{5/3}) \\ (D-7-(IMAX+2))$$

Because Equations (D-7) is a system of nonlinear equations, it can not be written in matrix form as a  $[D] [x] = [E]$  system of equations (the brackets denote matrices). To solve the equations, a Newton-Raphson Iteration technique for nonlinear equations was used. This is done by differentiating each of the  $(IMAX + 2)$  equations with respect to each of the unknowns, the resulting equations are then linear in terms of  $\Delta a$ ,  $\Delta y_{del1}$ , . . .  $\Delta y_{delIMAX}$ ,  $\Delta \lambda$ . The resulting matrix is inverted to obtain the  $\Delta$ (unknown) and the quantities are added to the original estimates to produce a better estimate. This iterative procedure is continued until the changes become acceptably small. The solution converged rapidly. Generally, the first row of the matrix to be inverted is ( $a_{11}$  represents the  $k^{th}$  row and the  $l^{th}$  column of the matrix).

$$a_{11} = \sum_{j=1}^{IMAX} \sum_{i=1}^{JMAX} 2(y_{i,j} - y_{del_i})^{4/3}$$

$$a_{1,2} = \sum_{j=1}^{JMAX} \frac{4}{3} (y_{1,j} - y_{del1})^{-1/3} (h_{meas1,j} - 2A(y_{1,j} - y_{del1}))^{2/3}$$

$$a_{1,IMAX+1} = \sum_{j=1}^{JMAX} \left[ \frac{4}{3} (y_{IMAX,j} - y_{del_{IMAX}})^{-1/3} (h_{meas_{IMAX,j}} - 2A(y_{IMAX,j} - y_{del_{IMAX}})^{2/3}) \right]$$

$$a_{1,IMAX+2} = \sum_{i=1}^{IMAX} \left[ \frac{3}{5} \Delta x (y_f - y_{del_1})^{5/3} \right] \quad (D-8)$$

The second row of the matrix is as follows:

$$a_{2,1} = \sum_{j=1}^{JMAX} \left[ \frac{4}{3} h_{meas_{1,j}} (y_{1,j} - y_{del_1})^{-1/3} - \frac{8}{3} A (y_{1,j} - y_{del_1})^{1/3} \right] + \lambda \Delta x (y_f - y_{del_1})^{2/3}$$

$$a_{2,2} = \sum_{j=1}^{JMAX} \left[ \frac{4}{9} A h_{meas_{i,j}} (y_{1,j} - y_{del_1})^{-4/3} + \frac{4}{9} A^2 (y_{1,j} - y_{del_1})^{-2/3} \right] - \lambda (2/3) \Delta x A (y_f - y_{del_1})^{-1/3}$$

$$a_{2,3} = 0$$

⋮

$$a_{2,IMAX+1} = 0$$

$$a_{2,IMAX+2} = \Delta x A (y_f - y_{del_1})^{2/3} \quad (D-9)$$

The third row is simply these elements repeated except that the ones on the right-hand side of the first and last elements are changed to twos, and the  $a_{3,3}$  element is similar to the  $a_{2,2}$  except the ones on the right hand side become twos. The remaining column elements (i.e., those when the  $k = 1$ ) are zeroes. This process is continued to fill the array, except for the last row.

The  $(IMAX+2)^{th}$  row is as follows:

$$a_{IMAX+2,1} = \sum_{i=1}^{IMAX} \frac{3}{5} \Delta x (y_f - y_{del1_i})^{5/3}$$

$$a_{IMAX+2,2} = -\Delta x A (y_f - y_{del1_1})^{2/3}$$

$$\vdots$$

$$a_{IMAX+2, IMAX+1} = -\Delta x A (y_f - y_{del1_{IMAX}})^{2/3}$$

$$a_{IMAX+2, IMAX+2} = 0 \quad (D-10)$$

The E matrix in the [D] [x] = [E] system of equations is

$$E_1 = - \left[ \sum_{i=1}^{IMAX} \sum_{j=1}^{JMAX} 2(h_{meas_{i,j}} - A(y_{i,j} - y_{del1_i})^{2/3})(y_{i,j} - y_{del1_i})^{2/3} \right. \\ \left. - \lambda \sum_{i=1}^{IMAX} \left(\frac{3}{5}\right) \Delta x (y_f - y_{del1_i})^{5/3} \right]$$

$$E_2 = - \left[ \sum_{j=1}^{JMAX} 2(h_{meas_{1,j}} - A(y_{1,j} - y_{del1_1})^{2/3}) \left(\frac{2}{3}\right) A (y_{1,j} - y_{del1_1})^{-1/3} \right. \\ \left. + \lambda (\Delta x A (y_f - y_{del1_1})^{2/3}) \right]$$

$$E_{IMAX+1} = - \left[ \sum_{j=1}^{JMAX} 2(h_{meas_{IMAX,j}} - A(y_{IMAX,j} - y_{del1_{IMAX}})^{2/3}) \right. \\ \left. * \left(\frac{2}{3}\right) A (y_{1,j} - y_{del1_1})^{-1/3} + \lambda (\Delta x A (y_f - y_{del1_1})^{2/3}) \right]$$

$$E_{IMAX+2} = - \left[ \sum_{i=1}^{IMAX} \left(\frac{3}{5}\right) \Delta x A (y_f - y_{del1_i})^{5/3} - V_{meas} \right] \quad (D-11)$$

The  $[D] [x] = [E]$  system of equations was then solved, as explained previously, by solving the  $x$  column vector (which represents the changes in the unknowns,  $\Delta A, \Delta y_{del1} \dots \Delta y_{del_{MAX}}, \Delta \lambda$ ), adding these changes to the respective variables and iterating until a final solution is obtained.

The computer program which did these calculations for the Channel Island Harbor simulation follows. A user-supplied matrix inversion routine is required (Line 37,200).

```

100  $RESET FREE
200  C*****PROGRAM CIH/BVALUE1
300  FILE 5(KIND=PACK,TITLE="CIH42076A",FILETYPE=7)
400  FILE 6(KIND=REMOTE)
500  C*THIS PROGRAM USES THE INTERPOLATED PROFILES OF CIH.
600  C*IT FINDS THE LOCATION OF THE SHORELINE, YDEL AND THE BEST
700  C*FIT LEAST SQUARES "B" VALUE FOR H=BY**2/3
800  C*USES LAGRANGE MULTIPLIERS TO CONSTRAIN THE VOLUMES(SO THEY ARE EQUAL)
900  C*THEN IT USES NEWTON-RAPHSON ITER FOR NON-LIN EQS
1000 DIMENSION X(40)
1100 DIMENSION WKAREA(600),AMATRX(23,23),BMATRX(23,1)
1200 DIMENSION Y(40,20),Z(40,20),YDEL(40),JBEGIN(40),YDELI(40)
1300 DIMENSION DYTWO(40,20),DYONE(40,20),DYMTWO(40,20),DYMONE(40,20)
1400 DIMENSION DYMFOR(40,20),DYFOR(40,20),YDONE(40,20),YDMTWO(40,20)
1500 DIMENSION YDMONE(40,20),YETWO(40),YEDONE(40),YEMONE(40)
1600 DIMENSION YEMTWO(40),YEMFOR(40),YEFIVE(40)
1700 EXPON=2./3.
1800 THIRD=0.3333333333333333
1900 C*FIRST READ IN THE PROFILES FROM DISKPACK.
2000 DO 1 I=1,34
2100 DO 1 J=1,15
2200 1 READ(5,100) X(I),Y(I,J),Z(I,J)
2300 100 FORMAT(14X,F6.0,F5.0,F5.0)
2400 C*NOW WE MUST GET A FIRST APPROX FOR YDEL
2500 C*WE WILL USE LINEAR INTERPOLATION TO DETERMINE IT.
2600 IBEGIN=1
2700 IMAX=21
2800 JMAX=15
2900 C*CHANGE PROFILE TO SPAN 1 TO IMAX(IF ALREADY DONE,WON'T HARM THINGS)
3000 ITEMP1=1
3100 ITEMP2=IMAX-IBEGIN+1
3200 K=-1
3300 DO 777 I=1,ITEMP2
3400 K=K+1
3500 DO 777 J=1,JMAX
3600 Y(I,J)=Y(IBEGIN+K,J)
3700 777 Z(I,J)=Z(IBEGIN+K,J)
3800 IMAX=ITEMP2
3900 DX=100.00
4000 DO 2 I=1,IMAX
4100 DO 3 J=1,JMAX
4200 IF(Z(I,J).GE.0.0) GO TO 3
4300 C*FIRST NEG POINT ON THE PROFILE IS SEAWARD OF Z=0.0
4400 C* WE MUST ALSO REMEMBER THIS LOCATION.
4500 C*IF Z(I,1)<0.,CHOOSE ARBITRARY PT, ROUTINE ITERATES TO SOLN.
4600 ZDUM=1.0
4700 IF(J.NE.1) ZDUM=Z(I,J-1)
4800 YDUM=Y(I,J)-50.0
4900 IF(J.NE.1) YDUM=Y(I,J-1)
5000 DELY=ZDUM/((ZDUM-Z(I,J))/(Y(I,J)-YDUM))
5100 YDEL(I)=YDUM+DELY
5200 JBEGIN(I)=J
5300 GO TO 2
5400 3 CONTINUE
5500 2 CONTINUE
5600 C*THE VALUES FOR Z ARE NEG ON FILE, MUST NOW MAKE POS.
5700 C*THE Z VALUES ARE ALSO *10.
5800 DO 35 I=1,IMAX
5900 DO 35 J=JBEGIN(I),JMAX
6000 35 Z(I,J)=-Z(I,J)/10.0
6100 C*MUST INITIALIZE "B" SO WILL MAKE A FIRST GUESS.
6200 C*MUST ALSO GUESS LAMBDA (XLAMB)
6300 B=0.30
6400 XLAMB=-2.0
6500 DO 10 ITER=1,100
6600 C*LET'S CALCULATE THE VOL OF WATER ABOVE THE PROFILE,VMEAS.
6700 C*ITS OUR CONSTRAINT,BUT SINCE YDEL IS NOT KNOWN,A PRIORI,IT WILL CHANGE
6800 VMEAS=0.0
6900 DO 200 I=1,IMAX
7000 DO 200 J=JBEGIN(I),JMAX
7100 IF(J.NE.JBEGIN(I)) GO TO 201

```

```

7200      VMEAS=VMEAS+DX*Z(I,J)*(0.5*(Y(I,J)+Y(I,J+1))-YDEL(I))
7300      GO TO 200
7400  201 IF(J.EQ.JMAX)   GO TO 202
7500      VMEAS=VMEAS+DX*0.5*(Y(I,J+1)-Y(I,J-1))*Z(I,J)
7600      GO TO 200
7700  202 VMEAS=VMEAS+DX*Z(I,J)*(Y(I,J)-0.5*(Y(I,J)+Y(I,J+1)))
7800      200 CONTINUE
7900  C*PRIOR TO EQS, COMPUTE AND STORE SEVERAL VALUES WE NEED OVER AND OVER
8000  C*BECAUSE COMPUTER CAN'T RAISE A NEG VALUE TO AN EXPONENT
8100  C*MUST PRESERVE THE SIGN.
8200      DO 400 II=1,IMAX
8300          DO 401 JJ=JBEGIN(II),JMAX
8400              ARG1=Y(II,JJ)-YDEL(II)
8500              DYSIGN=SIGN(1.,ARG1)
8600              DY=ABS(Y(II,JJ)-YDEL(II))
8700              DYTWO(II,JJ)=DY**EXPON
8800                  DYONE(II,JJ)=DYSIGN*DY**THIRD
8900                  DYMTWO(II,JJ)=DY**(-EXPON)
9000                  DYMONE(II,JJ)=DYSIGN*DY**(-THIRD)
9100                  DYMFOR(II,JJ)=DY**(-2.*EXPON)
9200                  DYFOR(II,JJ)=DY**(2.*EXPON)
9300  401 CONTINUE
9400      ARG2=1400.-YDEL(II)
9500      DSIGN=SIGN(1.,ARG2)
9600      DYE=ABS(ARG2)
9700      YETWO(II)=DYE**EXPON
9800      YEONE(II)=DSIGN*DYE**THIRD
9900      YEMONE(II)=DSIGN*DYE**(-THIRD)
10000     YEMTWO(II)=DYE**(-EXPON)
10100     YEMFOR(II)=DYE**(-2.*EXPON)
10200     YEFIVE(II)=DSIGN*DYE**(5.*THIRD)
10300     400 CONTINUE
10400  C*LET'S INPUT THE FIRST ROW OF THE MATRIX. A
10500     SUM1B=0.0
10600     DO 300 II=1,IMAX
10700         DO 300 JJ=JBEGIN(II),JMAX
10800     300 SUM1B=SUM1B+2.*DYFOR(II,JJ)
10900         AMATRX(1,1)=SUM1B
11000         SUMLAM=0.0
11100         DO 305 K=1,IMAX
11200             SUM1K=0.0
11300             DO 306 JJ=JBEGIN(K),JMAX
11400     306 SUM1K=SUM1K+2.*EXPON*DYMONE(K,JJ)*(Z(K,JJ)-2.*B*
11500             *DYTWO(K,JJ))
11600             SUMLAM=SUMLAM-0.6*DX*YEFIVE(K)
11700     305 AMATRX(1,K+1)=SUM1K
11800             AMATRX(1,IMAX+2)=SUMLAM
11900  C*NOW THE MIDDLE ROWS OF THE AMATRX.
12000     DO 410 LROW=2,IMAX+1
12100         SUM2B=0.0
12200         II=LROW-1
12300         DO 415 JJ=JBEGIN(II),JMAX
12400     415 SUM2B=SUM2B+2.*EXPON*Z(II,JJ)*DYMONE(II,JJ)-4.*EXPON*
12500         *B*DYONE(II,JJ)
12600         AMATRX(LROW,1)=SUM2B+XLAMB*DX*YETWO(II)
12700         DO 430 II=1,IMAX
12800             SUM2Y=0.0
12900             DO 425 JJ=JBEGIN(II),JMAX
13000     425 SUM2Y=SUM2Y+2.*EXPON*THIRD*B*Z(II,JJ)*DYMFOR(II,JJ)+THIRD*EXPON
13100             *2.*B*B*DYMTWO(II,JJ)
13200             IF((II+1).EQ.LROW) GO TO 431
13300             AMATRX(LROW,II+1)=0.0
13400             GO TO 430
13500     431 AMATRX(LROW,II+1)=SUM2Y-XLAMB*EXPON*DX*B*YEMONE(II)
13600     430 CONTINUE
13700     410 AMATRX(LROW,IMAX+2)=DX*B*YETWO(LROW-1)
13800  C*NOW THE LAST ROW OF THE MATRIX A
13900     SUMFB=0.0
14000     DO 450 II=1,IMAX
14100     450 SUMFB=SUMFB+0.6*DX*YEFIVE(II)
14200     AMATRX(IMAX+2,1)=SUMFB

```

```

14300      DO 453      II=1,IMAX
14400      453  AMATRX(IMAX+2,II+1)=-DX*B*YETWO(II)
14500      AMATRX(IMAX+2,IMAX+2)=O.O
14600  C*NOW MUST INPUT THE BMATRX.
14700      SUMF1A=O.O
14800      SUMF1B=O.O
14900      DO 455      II=1,IMAX
15000      SUMF1B=SUMF1B+XLAMB*O.6*DX*YEFIVE(II)
15100      DO 455      JJ=JBEGIN(II),JMAX
15200      455  SUMF1A=SUMF1A-2.*(Z(II,JJ)-B*DYTWO(II,JJ))*DYTWO(II,JJ)
15300      BMATRX(1,1)=- (SUMF1A-SUMF1B)
15400      DO 460      II=1,IMAX
15500      SUMFII=O.O
15600      DO 462      JJ=JBEGIN(II),JMAX
15700      462  SUMFII=SUMFII+2.*(Z(II,JJ)-B*DYTWO(II,JJ))*EXPON*B*DYMONE(II,JJ)
15800      SUMFII=SUMFII+XLAMB*DX*B*YETWO(II)
15900      460  BMATRX(II+1,1)=-SUMFII
16000      SUMV=O.O
16100      DO 465      II=1,IMAX
16200      465  SUMV=SUMV+O.6*DX*B*YEFIVE(II)
16300      BMATRX(IMAX+2,1)=- (SUMV-VMEAS)
16400  C*NEXT LET'S CALL THE MATRIX INVERSION ROUTINE VIA IMSL
16500      CALL LEQT2F(AMATRX,1,IMAX+2,23,BMATRX,3,WKAREA,IER)
16600  C*THE SOLN IS RETURNED IN THE VECTOR BMATRX
16700  C*FINALLY, WE MUST UPDATE THE X VECTOR IN AX=B.
16800      B=B+BMATRX(1,1)
16900      XLAMB=XLAMB+BMATRX(IMAX+2,1)
17000      DO 470      II=1,IMAX
17100      470  YDEL(II)=YDEL(II)+BMATRX(II+1,1)
17200  C*CHECK THE CRITERION FOR COMPLETION
17300      SUMVEC=O.O
17400      DO 475      II=1,IMAX
17500      475  SUMVEC=SUMVEC+ABS(BMATRX(II,1))
17600      IF(SUMVEC.LT.(O.1*(IMAX+2))) GO TO 11
17700      WRITE(6,*) B,ITER,(I,YDEL(I),I=1,IMAX),XLAMB
17800      10  CONTINUE
17900      11  CONTINUE
18000  C*LET'S WRITE IT ALL OUT.
18100      WRITE(6,*) ITER,B,(I,YDEL(I),I=1,IMAX)
18200      STOP
18300      END

```



## APPENDIX E

### USER DOCUMENTATION AND INPUT AND OUTPUT FOR PROGRAM VERIFICATION

The computer program presented in Appendix B was run on a Burroughs B-7700 computer. The B7000/B6000 series FORTRAN language was designed so several existing programs written in FORTRAN would be compatible with minimal changes. It was designed to be compatible with Fortram IV, H level and to contain ANSI X3.9-1966 Standard FORTRAN as a subset.

Line 37,200 of the coding (see App. B) requires a subroutine from the IMSL subroutine package, LEQT1B and its associated subroutines. If the user's computing center has access to this package of subroutine programs they need only bind them to the program (note: copyright laws prohibited the inclusion of the IMSL coding). If not, a substitute subroutine must be user supplied. It must facilitate the solution of a banded storage mode matrix.

The program input will be described here using a card deck set-up, however, the use of diskpack or magnetic tape input follows directly. Lines 3100, 4100, 5500, 5900, 6800, 7500, and 12,900 are read statements. The cards used for the simulation presented in this appendix are shown in Figure E-1. The first card contains the value of WDEPTH, the depth of water (in meters) to which the input wave conditions are to be transformed (a partial list of variables used in the program is presented beginning on page A-8 of Appendix A). The format statements are obviously in the program coding.

The second data input card is read by line 4100 where the variables SJTETY, BERM, SFACE, and DIAM are required (length of the structure, berm height, shore face slope, and sediment diameter, respectively).

Lines 5500 reads MMAX, the number of structures to be simulated (as set-up here, a maximum of 10 structures can be modeled, however, appropriate changes in array dimensions would allow additions (structures). Line 5900, which is in a "DO" loop reads the lesser I grid value adjacent to where the structure is desired. The number of structures, MMAX, determines the number of data cards required here; 3 structures require 3 cards with the 3 I grid locations (note, the present configuration of the refraction and diffraction subroutines requires evenly spaced structures, however this can be altered if necessary).

The parameter ADEAN, which represents the value of A in the equilibrium profile used is the next value input (line 6800). As mentioned previously, whenever possible a site-specific value should be used. The space-step and time-step (DX and DELT in the coding) are input next (line 7500).

The last input values are the wave data, HS, T, ALPWIS read by line 12,900. This statement is in a loop made by the unconditional GO TO statement (line 16,400) and the read statement. There is an action specifier included in the read statement to transfer the program to statement 1000, thereby stopping execution of the program once all the wave climate data have been used. The number of data cards required for this read statement is dictated by the length of the simulation and the time-step used.

The input file and output for program verification follow.



INPUT: FILE\_DUM

100	10.000			
200	5.000			
300		300.000	0.0500	0.220
400		1		
500		25		
600		0.1500		
700		100.00		
800	21600.00			
900	5.0	8.0	3.0	
1000	5.0	8.0	3.0	
1100	5.0	8.0	3.0	
1200	5.0	8.0	3.0	
1300	5.0	8.0	3.0	
1400	5.0	8.0	3.0	
1500	5.0	8.0	3.0	
1600	5.0	8.0	3.0	
1700	5.0	8.0	3.0	
1800	5.0	8.0	3.0	
1900	5.0	8.0	3.0	
2000	5.0	8.0	3.0	
2100	5.0	8.0	3.0	
2200	5.0	8.0	3.0	
2300	5.0	8.0	3.0	
2400	5.0	8.0	3.0	
2500	5.0	8.0	3.0	
2600	5.0	8.0	3.0	
2700	5.0	8.0	3.0	
2800	5.0	8.0	3.0	
2900	5.0	8.0	3.0	
3000	5.0	8.0	3.0	
3100	5.0	8.0	3.0	
3200	5.0	8.0	3.0	
3300	5.0	8.0	3.0	
3400	5.0	8.0	3.0	
3500	5.0	8.0	3.0	
3600	5.0	8.0	3.0	

```

.....
TO WHAT DEPTH ARE THE WAVES TO BE TRANSFORMED.....
THE DEPTH (IN FT.) WAVES TRANSFORMED TO, WDEPTH= 32.808
.....
ITS TIME FOR SURVEY, BEAM, SPACE, AND DIAM
.....
THE LENGTH OF THE STRUCTURE, SURJET= 300.000
THE HEIGHT OF THE BERM, BERH= 5.000
THE SLOPE OF THE BEACH FACE, SFAC= 0.0500
.....
THE SEDIMENT DIAMETER, DIAM= 0.220
.....
THE NUMBER 1 GROUND IS LOCATED AT (X)10.75
.....
NOW ENTER THE VALUE OF ADEAN
THE VALUE OF ADEAN= 0.1500 IN THE EQ H=AY**2/3
READ IN THE SPACE STEP, TIME STEP
.....
THE VALUE OF THE LONGSHORE SPACE STEP, D% 100.000
THE TIME STEP IN SECONDS, DELT= 21600.000
.....
THE BOUNDARY Y-VALUES, I=1, IMAX ARE AS FOLLOWS
.....
0.00 31.62 68.01 137.71 252.98 464.76 760.73 1050.41 1656.50 2674.85
.....
THE DEPTHS BETWEEN CONTOURS ARE AS FOLLOWS
.....
1.00 2.00 3.00 5.00 7.00 11.00 14.00 17.00 25.00 32.81
.....
NUNIV=1,
NUNIV=2,
NUNIV=3,
NUNIV=4,
NUNIV=5,
NUNIV=6,
NUNIV=7,
NUNIV=8,
NUNIV=9,
NUNIV=10,
THE TOTAL ELAPSED NUMBER OF TIME STEPS, NUNIV= 10

THE LONGSHORE TRANSPTS, QX, FOLLOW
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000

```





THE NEW CONTOUR VALUES, Y, FOLLOW		0.000	0.001	0.002	0.003	0.004	0.006	0.008	0.011	0.015	0.021	0.029
0.040	0.086	0.132	0.178	0.224	0.270	0.316	0.362	0.408	0.454	0.500	0.546	0.592
-0.015	-0.011	-0.008	-0.005	-0.002	-0.001	0.000	0.001	0.002	0.003	0.004	0.005	0.006
31.623	31.626	31.631	31.636	31.643	31.650	31.661	31.674	31.692	31.714	31.744	31.784	31.835
28.051	28.751	29.351	29.849	30.248	30.563	30.809	31.000	31.145	31.258	31.345	31.412	31.463
68.011	68.058	68.106	68.156	68.206	68.256	68.306	68.356	68.406	68.456	68.506	68.556	68.606
60.927	61.920	63.006	64.024	64.809	65.449	65.963	66.390	66.729	67.002	67.221	67.395	67.535
67.645	67.733	67.803	67.858	67.902	67.936	67.964	67.988	68.007	68.025	68.041	68.057	68.073
137.705	137.763	137.819	137.878	137.945	138.022	138.114	138.223	138.350	138.496	138.661	138.847	139.054
128.968	129.973	140.477	141.032	141.714	142.521	143.453	144.520	145.723	147.062	148.537	150.150	151.899
126.171	127.997	129.952	132.027	134.211	136.494	138.876	141.357	143.936	146.614	149.391	152.264	155.233
136.109	136.983	137.857	138.731	139.605	140.479	141.353	142.227	143.101	143.975	144.849	145.723	146.597
254.359	254.067	253.150	253.234	253.321	253.411	253.507	253.608	253.716	253.831	253.952	254.081	254.217
250.559	250.535	250.569	250.643	250.747	250.872	251.011	251.158	251.308	251.458	251.605	251.747	251.883
252.012	252.134	252.249	252.357	252.458	252.554	252.645	252.732	252.816	252.896	252.973	253.047	253.118
464.758	464.759	464.760	464.761	464.762	464.763	464.764	464.765	464.766	464.767	464.768	464.769	464.770
464.748	464.748	464.748	464.748	464.748	464.748	464.748	464.748	464.748	464.748	464.748	464.748	464.748
464.746	464.748	464.749	464.750	464.752	464.753	464.754	464.755	464.756	464.757	464.758	464.759	464.760
760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726
760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726
760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726
1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414
1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414
1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414

MINIV-21.  
 MINIV-22.  
 MINIV-23.  
 MINIV-24.  
 MINIV-25.  
 MINIV-26.  
 MINIV-27.  
 MINIV-28.  
 MINIV-29.  
 MINIV-30.

THE TOTAL ELAPSED NUMBER OF TIME-STEPS, MINIV= 30

THE LONGSHORE TRANSPORTS OF, FOLLOW  
 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000  
 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000  
 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000  
 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000



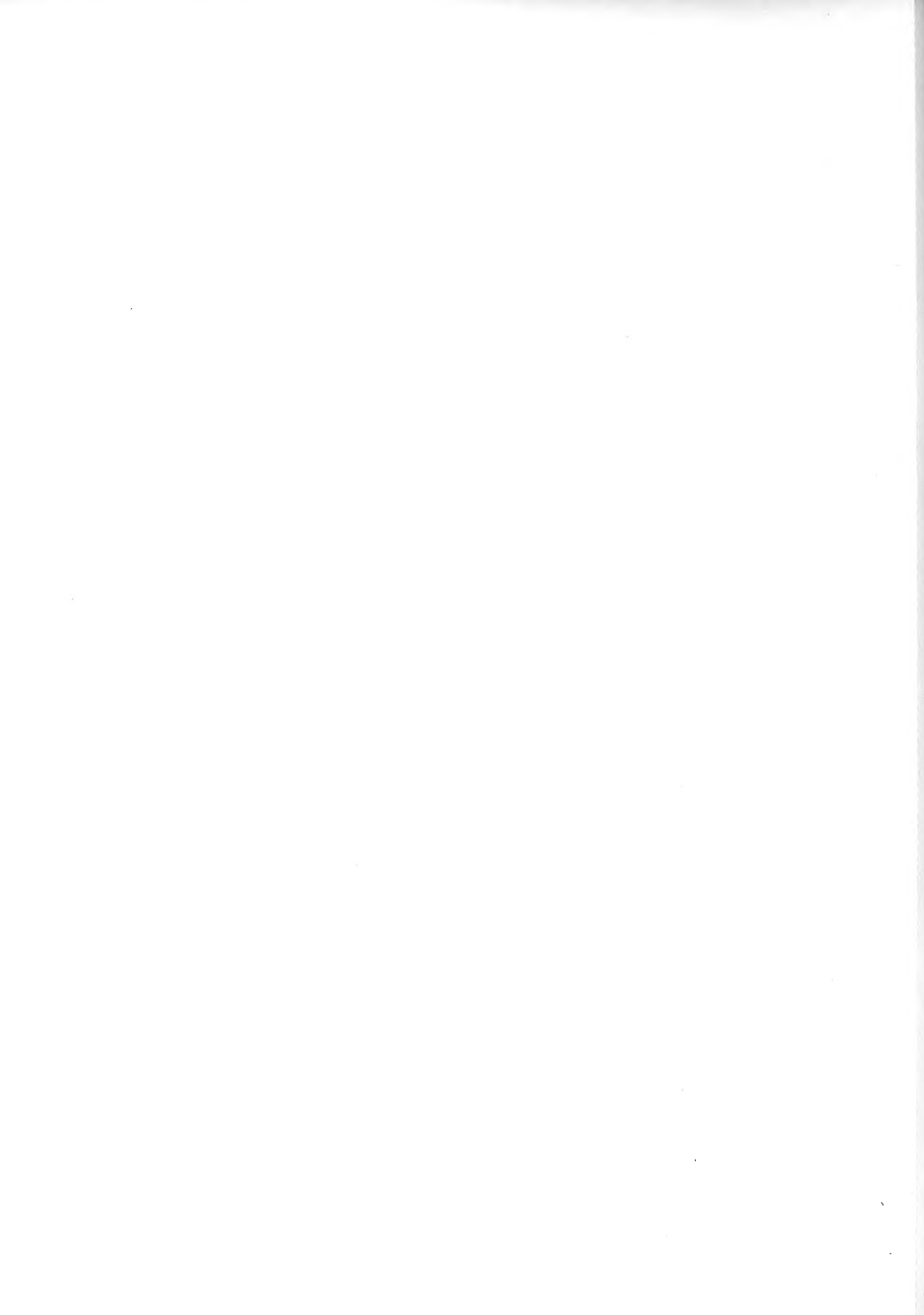


THE NEW CONTOUR VALUES, Y, FOLLOW:

	0.0000	0.0003	0.0007	0.0011	0.0016	0.0022	0.0029	0.0038	0.0050	0.0064	0.0083	0.0107	0.137
0.177	0.227	0.293	0.377	0.484	0.618	0.783	0.977	1.211	1.496	1.821	2.187	2.595	3.046
-1.624	-1.422	-1.196	-0.978	-0.618	-0.283	-0.484	-0.484	-0.316	-0.002	0.303	0.000	-0.137	-0.106
-0.083	-0.064	-0.050	-0.038	-0.029	-0.016	0.000	0.019	0.031	0.037	0.033	0.022	0.007	0.000
31.623	31.642	31.662	31.685	31.708	31.738	31.771	31.811	31.860	31.918	31.986	32.077	32.184	
32.114	32.147	32.186	32.230	32.279	32.333	32.392	32.456	32.525	32.599	32.678	32.762	32.851	
71.214	71.247	71.286	71.330	71.379	71.433	71.492	71.556	71.625	71.699	71.778	71.862	71.951	
31.257	31.328	31.387	31.435	31.475	31.508	31.537	31.561	31.584	31.604	31.623	31.643	31.663	31.670
68.041	68.095	68.150	68.208	68.270	68.340	68.421	68.512	68.616	68.732	68.860	69.000	69.151	69.318
69.580	69.892	70.264	70.706	71.211	71.854	72.592	73.475	74.453	75.476	76.595	77.829	79.157	80.571
58.945	60.376	61.580	62.614	63.523	64.354	65.157	65.982	66.821	67.685	68.592	69.550	70.567	71.641
67.172	67.372	67.578	67.794	68.024	68.267	68.524	68.794	69.077	69.374	69.685	69.999	70.317	70.639
140.342	140.828	141.394	142.034	142.741	143.518	144.368	145.284	146.259	147.297	148.399	149.568	150.806	152.115
140.342	140.920	141.473	142.114	142.856	143.716	144.710	145.860	147.192	148.718	150.342	152.146	154.123	156.254
124.860	126.687	128.213	129.547	130.699	131.693	132.554	133.298	133.939	134.493	134.971	135.384	135.740	
136.048	136.315	136.547	136.748	136.926	137.082	137.222	137.350	137.468	137.568	137.654	137.728	137.793	137.849
252.982	253.115	253.241	253.372	253.501	253.630	253.758	253.885	254.011	254.136	254.260	254.383	254.505	254.627
254.814	254.969	255.120	255.268	255.414	255.558	255.700	255.840	255.978	256.114	256.248	256.380	256.510	256.639
250.910	251.066	251.219	251.369	251.517	251.663	251.807	251.949	252.089	252.227	252.363	252.497	252.629	252.760
2.164	2.516	2.516	2.519	2.522	2.525	2.527	2.529	2.531	2.533	2.535	2.537	2.539	2.541
164.759	164.761	164.763	164.765	164.768	164.770	164.772	164.774	164.776	164.778	164.780	164.782	164.784	164.786
464.785	464.786	464.786	464.786	464.785	464.783	464.781	464.778	464.774	464.770	464.766	464.762	464.758	464.754
464.749	464.744	464.739	464.735	464.730	464.722	464.714	464.706	464.698	464.690	464.682	464.674	464.666	464.658
464.735	464.737	464.739	464.742	464.744	464.746	464.748	464.750	464.752	464.754	464.756	464.758	464.760	464.762
760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726
760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726
760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726	760.726
1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414
1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414
1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414	1050.414



<p>Perlin, Marc</p> <p>A numerical model to simulate sediment transport in the vicinity of coastal structures / by Marc Perlin and Robert G. Dean.--Fort Belvoir, Va. : U.S. Army, Corps of Engineers, Coastal Engineering Research Center, Springfield, Va. : available from NTIS, 1983.</p> <p>[119] p. : ill. ; 28 cm.--(Miscellaneous report / Coastal Engineering Research Center ; no. 83-10).</p> <p>Cover title.</p> <p>"May 1983."</p> <p>Report provides an implicit finite-difference, n-line numerical model which predicts sediment transport and the resulting bathymetry in the vicinity of coastal structures. The wave field transformation includes refraction, shoaling, and diffraction.</p> <p>1. Numerical model. 2. Shoreline evolution. 3. Sediment transport. 4. Wave transformation. 5. Littoral barrier. I. Title. II. Dean, Robert G. III. Coastal Engineering Research Center (U.S.). IV. Series: Miscellaneous report (Coastal Engineering Research Center (U.S.)).</p> <p>TC203 .U581mr no. 83-10 627</p>	<p>Perlin, Marc</p> <p>A numerical model to simulate sediment transport in the vicinity of coastal structures / by Marc Perlin and Robert G. Dean.--Fort Belvoir, Va. : U.S. Army, Corps of Engineers, Coastal Engineering Research Center, Springfield, Va. : available from NTIS, 1983.</p> <p>[117] p. : ill. ; 28 cm.--(Miscellaneous report / Coastal Engineering Research Center ; no. 83-10).</p> <p>Cover title.</p> <p>"May 1983."</p> <p>Report provides an implicit finite-difference, n-line numerical model which predicts sediment transport and the resulting bathymetry in the vicinity of coastal structures. The wave field transformation includes refraction, shoaling, and diffraction.</p> <p>1. Numerical model. 2. Shoreline evolution. 3. Sediment transport. 4. Wave transformation. 5. Littoral barrier. I. Title. II. Dean, Robert G. III. Coastal Engineering Research Center (U.S.). IV. Series: Miscellaneous report (Coastal Engineering Research Center (U.S.)).</p> <p>TC203 .U581mr no. 83-10 627</p>
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