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\section*{ANTENNA LABORATORY}

\section*{Technical Report No. 35}

\section*{A THEORETICAL STUDY OF THE EQUIANGULAR SPIRAL ANTENNA}
by
Plessa Edward Mast*
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            1 2 \text { September 1958}
            Contract AF33(616)-3220
                Project No. 6(7-4600) Task 40572
            Sponsored by
            WRIGHT AIR DEVELOPMENT CENTER
                Electrical Engineering Research Laboratory
        Engineering Experiment Station
            University of Illinois
            Urbana, Illinois
    ```
*Submitted in partial fulfillment of the requirements for the degree of Doctor
of Philosophy in Electrical Engineering at the University of Illinois, 1953.
```

    During the preparation of this work the author has had many
    interesting and helpful discussions with various staff members of
the Antenna Laboratory at the University of Illinois. It is a
pleasure to mention in particular Professor V. H. Rumsey who initially
suggested and directed this project, Dr. E. C. Jordan who was
advisor during its final stages, and Dr. P. E. Mayes who has given
continued interest and guidance.

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\section*{ABSTRACT}

In the past few years some entirely new broadband antennas have been developed. At the present time it is easy to construct practical antennas which have essentially the same pattern and impedance over a 10 to 1 , or larger, frequency range. One group of broadband antennas utilizes the useful property of the equiangular (logarithmic) spiral curve that a scale change and a rotation are equivalent.

In this paper theoretical methods for determining the electric and magnetic fields produced by an equiangular spiral structure are considered. The equiangular spiral structure consists of two thin conducting strips (arms) with edges defined by equiangular spiral curves developed on a cone. The structure is considered infinite in extent with an arbitrary rate of spiral and an arbitrary cone angle. The planar equiangular spiral is included as a special case. To make the problem amenable to analysis it is necessary in some cases to restrict the gaps between the spiral arms to be small.

Expressions for the static (DC) electric fields are derived from separated solutions of Laplace's equation. The static electric fields are shown to be a function of only two variables. The separated solutions are a product of the circular functions, and associated Legendre functions of imaginary degree and real order. An infinite summation of the separated solutions is necessary to meet the required boundary conditions. For a small gap between the spiral arms the coefficients in the summation are expressed independently in a simple mathematical form. For an
arbitrary gap the coefficients can not be determined independently, and the solutions are approximated by a finite sum. The least squares criterion is used to obtain the best values of the coefficients, and the coefficients are expressed as the simultaneous solutions of a finite set of linear algebraic equations.

For the electromagnetic problem, separated solutions of the vector Helmholtz equation are obtained in an oblique spiral coordinate system. The separated solutions are similar to those of the spherical coordinate system. They are a product of Bessel functions of complex order, associated Legendre functions of complex degree and real order, and the circular functions. A double summation is required to satisfy the boundary conditions. Expressions for the coefficients in the summation are derived in terms of the tangential electric fields in the gap between the spiral arms.

For the special case of a balanced antenna with narrow gaps between the arms, expressions are derived for the fields produced in the gaps by a source at the origin. These solutions make available a means of calculating the input impedance, the current distribution, and the pattern of an equiangular spiral antenna.

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\(2\)

\section*{LIST OF SYMBOLS}
\begin{tabular}{|c|c|c|}
\hline & & Page \\
\hline \(\beta\) & Phase shift constant & 21 \\
\hline \(\gamma_{\text {m }}\) & Defined on & 18 \\
\hline \(\Gamma\) & Gamma function & 12 \\
\hline \(\epsilon\) & Dielectric constant of the medium & 21 \\
\hline \(\eta\) & Intrinsic impedance of the medium & 29 \\
\hline \(\theta\) & Conventional spherical coordinate variable & 4 \\
\hline \(\theta_{0}\) & Antenna cone angle & 4 \\
\hline \(\hat{\hat{\theta}}\) & Unit vector normal to a constant \(\theta\) surface & 23 \\
\hline \(\mu\) & Permeability of the medium & 21 \\
\hline \(v\) & Separation constant (TE) & 27, 34 \\
\hline \(\bar{v}\) & Separation constant (TM) & 29, 33 \\
\hline \(\pi_{\kappa}^{\prime}\) & Separated solution (TE) & 26 \\
\hline \(\Pi^{\prime}\) & Scaler function (TE) & 26 \\
\hline \(\Pi \prime \prime\) & Scalar function (TM) & 29 \\
\hline T & Spiral variable & 10, 26 \\
\hline \({ }^{\top}{ }_{n}\) & Antenna parameter & 11 \\
\hline \(\phi\) & Conventional spherical coordinate variable & 4 \\
\hline \(\hat{\phi}\) & Unit vector normal to a constant \(\phi\) surface & 23 \\
\hline \(\psi\) & Potential function of ( \(r, \theta, \phi\) ) & 8 \\
\hline * & Complex conjugate & \\
\hline a & Antenna parameter - rate of spiral & 4 \\
\hline \(\mathrm{A}_{\mathrm{m}}\) & Coefficient & 11 \\
\hline \(\mathrm{A}^{\prime}{ }_{K}\) & Coefficient (TE) & 26 \\
\hline
\end{tabular}


\section*{LIST OF SYMBOLS (CONTINUED)}
\begin{tabular}{|c|c|c|}
\hline & & Page \\
\hline \[
A_{v}^{1} \mathrm{~m}
\] & Coefficient for \(\theta<\theta_{0}\) (TE) & 28 \\
\hline \[
A_{\bar{v}}^{\prime \prime}
\] & Coefficient for \(\theta<\theta_{0}\) (TM) & 29 \\
\hline \[
\mathrm{n}, \kappa
\] & Gegenbauer's polynomial & 32 \\
\hline \(\mathrm{b}_{\mathrm{p}}\) & Power series coefficient & 40 \\
\hline \(B_{m}\) & Coefficient & 14 \\
\hline \[
B_{v}^{\prime} \mathrm{m}^{\prime}
\] & Coefficient for \(\theta>\theta_{0} \quad\) (TE) & 29 \\
\hline \[
B_{v}^{\prime \prime m}
\] & Coefficient for \(\theta>\theta_{0}\) (TM) & 29 \\
\hline \(\mathrm{C}_{\mathrm{m}}\) & Coefficient & 15 \\
\hline \[
c_{n+j \frac{m}{a}}^{\prime m}
\] & Coefficient (TE) & 33 \\
\hline \[
C_{n+j \frac{m}{a}}^{\prime \prime m}
\] & Coefficient (TM) & 32 \\
\hline e & Naperian base & \\
\hline E & Electric field vector of ( \(r, \Theta, \phi, t\) ) & 21 \\
\hline E & Electric field vector of (r, \(\theta\) ( \(\phi\) ) & 21 \\
\hline f & Electric field in the gap ( r comp.) & 31 \\
\hline F & Scalar function & 39 \\
\hline \(F\) & Hypergeometric function & 12 \\
\hline g & Electric field in the gap ( \(\phi\) comp.) & 31 \\
\hline \(\stackrel{\bar{H}}{ }\) & Magnetic field vector of ( \(r, \theta, \phi, t\) ) & 21 \\
\hline \(\underline{H}\) & Magnetic field vector of (r, \(\Theta, \phi\) ) & 21 \\
\hline j & \(=\sqrt{-1}\) & \\
\hline \(J_{\nu+\frac{1}{2}}\) & Bessel function of the first kind & 28 \\
\hline \(L_{k}\) & Defined on & 19 \\
\hline \(M_{n}^{\prime}, M_{n}^{\prime \prime}\) & Defined on & 44 \\
\hline
\end{tabular}


\section*{LIST OF SYMBOLS (CONTINUED)}



\section*{1. INTRODUCTION}

Recent years have seen the development and use of a number of broadband antennas. Experimental techniques have been used to provide entirely new types of antenna structures which maintain essentially the same pattern and impedance characteristics over a 10 to 1 , or larger, frequency range. One basis for the design of broadband antennas has been the "angle method" \({ }^{1}\) whereby the boundaries of the antenna are specified primarily in terms of angles, and thus lengths are avoided which are resonant at one frequency and not at others. The biconical antenna, the disc-cone, the fin, and the equiangular spiral are all examples of practical antenna structures which are specified primarily in terms of angles.

While the angle concept specifies in general what boundaries can be used to construct an antenna which might be broadband, it does not predict what the actual pattern or impedance will be. To date almost all of the development of broadband antennas has been of an experimental nature with only a minimum amount of theoretical development. Schelkunoff \({ }^{2}\) has derived theoretical expressions for the pattern and impedance of the infinite biconical structure by showing that the TEM mode is excited by a source at the origin. Carrel \({ }^{3}\) has devised methods for analyzing theoretically an infinite biconical structure of arbitrary cross section showing that the infinite structure has characteristics which are independent of frequency. However, the finite over-all size required in a practical antenna gives rise to an "end effect" which seriously
limits the bandwidth obtainable with the biconical antennas of arbitrary cross section.

Using the "angle method", Rumsey in 1954 proposed a class of antennas based on the equiangular spiral. The balanced planar equiangular spiral has been very thoroughly investigated experimentally by Dyson \({ }^{4}\) who has shown that it is easy to construct a practical antenna having frequency independent characteristics over a 20 to 1 bandwidth. He has also shown that over a range of frequencies the input impedance and the pattern of this antenna are not affected by increasing the length of the antenna arms. Thus, the equiangular spiral structure does not have an appreciable "end effect," and after a critical size is passed the characteristics of the finite antenna are the same as for the infinite structure.

Experimentally, the balanced planar version of the equiangular spiral antenna radiates a circularly polarized, bidirectional pattern, with the two lobes of the pattern perpendicular to the plane of the antenna. Theoretically, the pattern rotates about a line perpendicular to the plane of the antenna as the frequency is changed. However, in the useful frequency range the pattern is nearly symmetrical about the axis of rotation, and, therefore this rotation has a small effect on the experimental patterns of the antenna. Recently, Dyson \({ }^{5}\) has shown that the balanced equiangular spiral developed on, a cone can be made into a practical broadband antenna with a unidirectional pattern.

This paper presents the results of a theoretical study of the electric and magnetic fields produced by an equiangular spiral structure.


As the boundaries of the equiangular spiral antenna can be specified in reasonably simple mathematical terms, it was felt worthwhile to investigate methods of obtaining exact theoretical expressions for the fields. To obtain a feeling for the problem, the static (DC) electric fields were determined first by obtaining separated solutions of Laplace's equation. The static solutions pointed the way to a set of coordinate variables which were used to obtain the electromagnetic fields as solutions of the vector Helmholtz equation. While it was desired to determine mathematical expressions for the fields under the most general conditions, several simplifying assumptions were necessary. In all cases the spiral structure is considered infinite in extent, and the spirals are assumed to continue indefinitely close to the origin. Also, in some places in the analysis the gap between the spiral arms is assumed arbitrarily small.
2. THE EQUIANGULAR SPIRAL ANTENNA

\subsection*{2.1 The Equiangular Spiral}

A general equiangular (or logarithmic) spiral curve can be defined as the intersection of the two surfaces.
\[
\mathbf{r}=s_{o} e^{a \phi}
\]
and
\[
\theta=\theta_{0}
\]
where \(s_{0}, a\), and \(\theta_{0}\) are real parameters, and \(r, \theta\), and \(\phi\) are the conventional spherical coordinates shown in Fig. 1.


The equiangular spiral curve has the useful property that a change in scale is equivalent to a rotation. If the scale of the coordinate system is changed by a factor \(c\) such that
\[
\begin{equation*}
\mathbf{r}^{\prime}=\mathrm{cr} \tag{2-2}
\end{equation*}
\]
the defining equations for the spiral can be written as
\[
\begin{align*}
& \mathbf{r}^{\prime}=\mathrm{c} s_{6} \mathrm{e}^{\mathrm{a} \phi}=s_{6} \mathrm{e}^{\mathrm{a}\left(\phi+\phi_{0}\right)}  \tag{2-3}\\
& \theta=\theta_{0}
\end{align*}
\]
where
\[
\begin{equation*}
\phi_{\mathrm{O}}=(\ln c) / \mathrm{a} . \tag{2-4}
\end{equation*}
\]

Thus a change in scale by the factor \(c\) produces the same spiral as would be obtained by rotating the original curve by an angle ( \(\ell \mathrm{n} \mathrm{c}\) )/a about the polar axis.

\subsection*{2.2 The Equiangular Spiral Antenna}

Equiangular spiral curves can be used to define the boundaries of an antenna by using four curves having the same values for the parameters a and \(\theta_{0}\), but different values \(s_{1}, s_{2}, s_{3}\), and \(s_{4}\) for the parameters \(s_{0}\). The parameters \(s_{1}, s_{2}, s_{3}\), and \(s_{4}\) must be chosen such that
\[
\begin{equation*}
s_{1}<s_{2}<s_{3}<s_{4}<s_{1} e^{2 \pi a} \tag{2-5}
\end{equation*}
\]

One arm of the antenna is formed by placing a thin conducting strip on the cone \(\theta=\theta_{0}\) such that the edges of the strip coincide with the spirals corresponding to \(s_{0}=s_{1}\) and \(s_{0}=s_{2}\). In a similar manner another strip with edges coinciding with the spirals \(s_{0}=s_{3}\) and \(s_{0}=s_{4}\) forms a second arm. Near the origin the two arms of the antenna come arbitiparily close together, and the origin is a convenient place to excite the antenna.

Examples of equiangular spiral antennas are shown in Figs. 2 and 3 .

The infinite equiangular spiral antenna defined above has the useful property that a scale change is equivalent to a rotation. This assures that the space variations of the fields produced by different excitation frequencies can be related simply by rotating the reference axis of the coordinate system. Therefore, the pattern of the infinite equiangular spiral antenna rotates as the excitation frequency is changed, and the input impedance is independent of frequency.


FIGURE 2 THE EQUIANGULAR SPIRAL STRUCTURE DEVELOPED IN THE PLANE \(\theta_{0}=\pi / 2\)


FIGURE 3. THE EQUIANGULAR SPIRAL STRUCTURE DEVELOPED ON THE CONE \(\theta_{o}=22.5^{\circ}\).

\section*{3. THE STATIC (DC) ELECTRIC FIELDS}

\subsection*{3.1 Laplace's Equation with Spiral Variables}

With one of the arms of an equiangular spiral structure at the potential \(+V_{o}\) and the other at \(-V_{o}\), the potential \(\psi(r, \theta, \phi)\) at any point in space is given by the finite solution of Laplace's equation.
\[
\begin{equation*}
\nabla^{2} \psi=0 \tag{3-1}
\end{equation*}
\]
which satisfies the boundary conditions at \(\theta=\theta_{0}\) that
\[
\begin{gather*}
\psi=+V_{o} \text { for } s_{1} e^{2 \pi \mathrm{ka}}<r e^{-\mathrm{a} \phi}<s_{2} e^{2 \pi \mathrm{ka}} \\
\psi=-\mathrm{V}_{0} \quad \text { for } s_{3} e^{2 \pi \mathrm{ka}}<r e^{-\mathrm{a} \phi}<s_{4} e^{2 \pi \mathrm{ka}} \\
k=0, \pm_{1}, \pm 2, \ldots . \tag{3-2}
\end{gather*}
\]

The potential \(\Psi\) 'and the boundary conditions are functions of all three of the coordinate variables, but the boundary conditions are expressed in terms of \(\theta\) and \(\mathrm{re}^{-\mathrm{a} \phi}\). This suggests the introduction of a new set of variables, one of which is re \(e^{-\mathrm{a} \phi}\). A set of variables which has been found convenient is
\[
\begin{align*}
\overline{\mathbf{r}} & =\mathbf{r} \\
\mathrm{s} & =\mathbf{r} \mathrm{e}^{-\mathrm{a} \phi} \\
\theta & =\theta . \tag{3-3}
\end{align*}
\]

Laplace's equation in spherical coordinates \({ }^{6}\)
\[
\begin{equation*}
\nabla^{2} \psi=\frac{1}{r^{2}} \frac{\partial}{\partial r}\left(r^{2} \frac{\partial \psi}{\partial r}\right)+\frac{1}{r^{2} \sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial \psi}{\partial \theta}\right)+\frac{1}{r^{2} \sin ^{2} \theta} \frac{\partial^{2} \psi}{\partial \phi^{2}}=0 \tag{3-4}
\end{equation*}
\]
provides a convenient starting point, and in terms of \(\bar{r}, \theta\), and \(s\) Eq. 3-4 becomes
\[
\begin{align*}
\nabla^{2} \overline{\mathrm{~V}}= & \frac{1}{\bar{r}^{2}} \frac{\partial}{\partial \overline{\mathrm{r}}}\left(\overline{\mathrm{r}}^{2} \frac{\partial \overline{\mathrm{~V}}}{\partial \overline{\mathrm{r}}}\right)+\frac{2 \mathrm{~s}}{\overline{\mathrm{r}}^{2} \frac{\partial^{2} \overline{\mathrm{~V}}}{\partial_{s} \overline{\mathrm{~T}}^{\prime}}+\frac{1}{\overline{\mathrm{r}}^{2}} \frac{\partial}{\partial_{s}}\left(s^{2} \frac{\partial \overline{\mathrm{~V}}}{\partial_{s}}\right)+\frac{\mathrm{a}^{2} \mathrm{~s}}{\overline{\mathbf{r}}^{2} \sin ^{2} \theta} \frac{\partial}{\partial_{s}}\left(\mathrm{~s} \frac{\partial \overline{\mathrm{~V}}}{\partial s}\right)} \\
& +\frac{7}{\overline{\mathbf{r}}^{2} \sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial \overline{\mathrm{~V}}}{\partial \theta}\right)=0 \tag{3-5}
\end{align*}
\]
with \(\psi(r, \theta, \phi)=\overline{\mathrm{V}}(\overline{\mathrm{r}}, \theta, \mathrm{s})\).

The boundary conditions on \(\overline{\mathrm{V}}\) are independent of \(\overline{\mathrm{r}}\). If Eq. 3-5 is independent of \(\bar{r}\) when \(\partial \overline{\mathrm{V}} / \partial \overline{\mathbf{r}}\) is assumed zero, the \(\overline{\mathrm{V}}\) which satisfies the boundary conditions is independent of \(\overline{\mathbf{r}}\). Assuming \(\partial \overline{\mathrm{v}} / \partial \overline{\bar{r}}=0\) in Eq. \(3-5\) gives
\[
\begin{equation*}
\frac{\partial}{\partial_{s}}\left(s^{2} \frac{\partial \bar{v}}{\partial s}\right)+\frac{a^{2} s}{\sin ^{2} \theta} \frac{\partial}{\partial s}\left(s \frac{\partial \bar{v}}{\partial s}\right)+\frac{1}{\sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial \bar{v}}{\partial \theta}\right)=0 \tag{3-6}
\end{equation*}
\]
which is independent of \(\overline{\mathbf{r}}\), and the assumption is justified.
Therefore, the original three dimensional problem in spherical coordinates is reduced to a two dimensional problem, and the static potential can be expressed in terms of only two variables \(s\) and \(_{i} \theta\).

\subsection*{3.2 Separated Solutions for Laplace's Equation}

A further simplification in the two dimensional Laplace's equation and the boundary conditions is obtained by use of the substitutions
\[
T=\ln s, \quad V(\theta, T)=\overline{\mathrm{V}}(\bar{r}, \Theta, s)
\]
which reduces Eq. 3-6 to
\[
\begin{equation*}
\left(1+\frac{a^{2}}{\sin ^{2} \theta}\right) \frac{\partial^{2} v}{\partial T^{2}}+\frac{\partial V}{\partial \tau}+\frac{1}{\sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial V}{\partial \theta}\right)=0 \tag{3-7}
\end{equation*}
\]

Letting \(T_{n}=\ell n s_{n}\), the boundary conditions in terms of \(\theta\) and \(T\) are
\[
\begin{gather*}
V=+V_{0} \text { for } \tau_{1}+2 \pi a k<\tau<\tau_{2}+2 \pi a k \\
V=-V_{0} \text { for } \tau_{3}+2 \pi a k<\tau<\tau_{4}+2 \pi a k \\
k=0, \pm 1, \pm 2, \pm_{3}, . . . \tag{3-8}
\end{gather*}
\]
which are periodic in \(T\) with period \(2 \pi\) a. Separated solutions of Eq. 3-7 can be obtained by assuming a solution of the form
\[
\begin{equation*}
\mathrm{V}_{\mathrm{m}}=A_{\mathrm{m}} \Theta e^{j \frac{m}{a} \tau} \tag{3-9}
\end{equation*}
\]
where
\(A_{m}\) is a complex constant dependent only on \(m\),
\(\Theta\) 파 \(\Theta(\theta)\) is independent of \(\tau\),
and
\(m\) is required to be an integer to have solutions with a periodicity in \(T\) agreeing with the boundary conditions. The use of a sum of complex functions to represent a real potential is convenient as separated solutions of the form \(\Theta(\Theta) \cos \frac{m}{a} T\) or \(\Theta(\theta) \sin \frac{m}{a} T\), individually, will not satisfy Eq. 3-7. It is shown in Appendix A that, if the potential is assumed real at \(\theta=\theta_{0}\), the solutions presently obtained give real values for the potential for all \(\theta\) and \(\tau\). It is found that \(V_{m}\) will satisfy Eq. 3-7 if \(\Theta\) satisfies
\[
\begin{equation*}
\frac{d^{2} \theta}{d \theta}+\operatorname{ctn} \theta \frac{d \Theta}{d \theta}+\left[\left(j \frac{m}{a}\right)\left(1+j \frac{m}{a}\right)-\frac{m^{2}}{\sin ^{2} \theta}\right] \Theta=0 \tag{3-10}
\end{equation*}
\]

Eq. \(3-10\) is a form of the associated Legendre equation of degree \(j \frac{m}{a}\) and
order m . Many of the references on the associated Legendre equation consider only the special case of integral order and degree. References which consider the general case of complex degree and order are Hobson, \({ }^{7}\) Snow; \({ }^{8}\) and Schelkunoff. The notation used in the following is the same as used by Hobson.

The two linearly independent solutions of Eq. 3-10 are the associated Legendre functions of the first kind \(P_{j \frac{m}{a}}^{m}(\cos \theta)\), and the second kind \(Q_{j \frac{m}{a}}^{m}(\cos \theta)\). For integral \(m\) and real \(\theta, p_{j \frac{m}{a}}^{m}(\cos \theta)\) is finite for all \(\theta\) except \(\theta=\pi\), and \(Q_{j \frac{m}{2}}^{m}(\cos \theta)\) is finite for all \(\theta\) except \(\theta=0\) or \(\pi\). As \(Q_{j \frac{m}{a}}^{m}(\cos \theta)\) becomes infinite at both \(\theta=0\) and \(\pi\), it is not useful in the representation of the desired potential function and need not be considered further. For \(\theta\) neal and \(m\) a positive integer, \(P_{j}^{m} \frac{m}{2}(\cos \theta)\) is given by
\(P_{j \frac{m}{a}}^{m}(\cos \theta)=\frac{(-)^{m}}{2 m} \times \frac{\Gamma\left(m+1+j \frac{m}{a}\right)}{\Gamma\left(-m+1+j \frac{m}{a}\right)} \times \frac{\sin ^{m} \theta}{(m)!} F\left(m-j \frac{m}{a} ; m+1+j \frac{m}{a} ; m+1 ; \sin ^{2} \frac{\theta}{2}\right)\)
and for \(m\) a negative integer by
\[
\begin{equation*}
P_{j}^{m} \frac{m}{a}(\cos \theta)=\frac{\sin ^{-m} \theta}{2^{-m}(-m)!} F\left(-m-j \frac{m}{a},-m+1+j \frac{m}{a} ;-m+1 ; \sin ^{2} \frac{\theta}{2}\right) \tag{3-1.2}
\end{equation*}
\]
where \(F_{\text {is }}\) the hypergeometric function
\[
\begin{equation*}
F(\alpha, \beta ; \gamma ; z)=1+\frac{\alpha \cdot \beta}{1 \cdot \gamma} z+\frac{\alpha(\alpha+1) \beta(\beta+1)}{1 \cdot 2 \cdot \gamma(\gamma+1)} z^{2}+ \tag{3-13}
\end{equation*}
\]
and \(\Gamma\) represents the gamma function \({ }^{10}\) The fact that there are no solutions of Eq. 3-10 which are finite
for all real values of \(\Theta\) makes it necessary to divide the space about the spiral structure into two regions with a different mathematical representation for the fields in each of the regions. The logical boundary to use is the cone \(\theta=\Theta_{0}\) as shown in Fig. 4.


FIGURE 4 BOUNDARY CONDITIONS AT \(\theta=\theta_{0}\).

In region \(I\) for \(\theta<\theta_{0}, P_{j}^{m} \frac{m}{a}(\cos \theta)\) can be used in representing the potential, and in region II for \(\theta>\theta_{0}, p_{j \frac{m}{a}}^{m}(-\cos \theta)\) is appropriate.

On the boundary surface \(\theta=\theta_{0}\) the potential from both regions must be \(+V_{0}\) or \(-y_{0}\) on the arms of the spiral; also, the expressions for the potential from the two regions and their normal derivatives must match along the gap between the arms. The forced separation of the potential expressions into two regions greatly complicates the problem as it becomes a boundary value problem with mixed boundary conditions.

The appropriate separated solutions of the two dimensional Laplace!s equation with spiral variables are
\[
V_{m}=A_{m} P_{j \frac{m}{a}}^{m}(\cos \theta) e^{j \frac{m}{a} \tau} \quad \theta \leq \theta_{0}
\]
and
\[
\begin{equation*}
V_{m}=B_{m} P_{j \frac{m}{a}}^{m}(-\cos \theta) e^{j \frac{m}{a} T} \quad \theta \geq \theta_{0} \tag{3-14}
\end{equation*}
\]

A single value of min Eqs. 3-14 is not sufficient to meet the required boundary conditions, but a summation of terms of this form over all integer values of \(m\) will be found adequate. The expressions for the potential at any point are
\[
\begin{equation*}
V(\theta, \tau)=\sum_{m=-\infty}^{\infty} A_{m} P_{j \frac{m}{a}}^{m}(\cos \theta) e^{j \frac{m}{a} T} \quad \theta \leq \theta_{0} \tag{3-15}
\end{equation*}
\]
and
\[
V(\theta, \tau)=\sum_{m=-\infty}^{\infty} B_{m} P_{j \frac{m}{a}}^{m}(-\cos \theta) e^{j \frac{m}{a} \tau} \quad \theta \geq \theta_{0}
\]

Expressions for the coefficients \(A_{m}\) and \(B_{m}\) will be derived in the succeeding sections.
3.3 The Potential in Terms of Potential at \(\theta=\theta\)

The coefficients \(A_{m}\) and \(B_{m}\) will be determined first in terms of the potential distribution \(V\left(\theta_{0}, \tau\right)\) existing on the boundary \(\theta=\theta_{0}\). The potential on the boundary is a continuous periodic function of \(\tau\),
and may be expanded in a Fourier series as
\[
\begin{equation*}
V\left(\theta_{0}, T\right)=\sum_{m=-\infty}^{\infty} C_{m} e^{j \frac{m}{2} T} \tag{3-16}
\end{equation*}
\]
with the coefficients \(C_{m}\) given by
\[
\begin{equation*}
C_{m}=\frac{1}{2 \pi a} \int_{T}^{T} \int_{1}^{T+2 \pi a} V\left(\theta_{o}, T\right) e^{-j \frac{m}{a} T} d T \tag{3-17}
\end{equation*}
\]

From Eqs. 3-15 and 3-16 the relations between \(A_{m}, B_{m}\), and \(C_{m}\) are
\[
\begin{equation*}
A_{m}=\frac{C_{m}}{P_{j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)} \tag{3-18}
\end{equation*}
\]
and
\[
B_{m}=\frac{C_{m}}{P_{j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)}
\]

Eqs. 3-17 and 3-18 express the coefficients \(A_{m}\) and \(B_{m}\) in terms of an arbitrary distribution of potential in the gap with respect to \(T\), and they assure that the potentials from regions I and II match at the gap. The potential distribution in the gap is not arbitrary, but is restricted by the requirement that the normal derivatives of the potential match at the gap.
3.4 Potential on the Boundary for a Small Gap

As the gaps between the spiral arms are made small
\[
\begin{equation*}
\tau_{2} \rightarrow \tau_{3} \text { and } \tau_{4} \longrightarrow \tau_{1}+2 \pi a \tag{3-19}
\end{equation*}
\]

For arbitrarily small gaps the potential is specified over the entire cone \(\theta=\theta_{0}\) as
\[
\begin{array}{ll}
\mathrm{V}=+\mathrm{V}_{\mathrm{o}} & \mathrm{~T}_{1}+2 \pi \mathrm{ak}<\tau<\tau_{2}+2 \pi \mathrm{ak}=\tau_{3}+2 \pi \mathrm{ak} \\
\mathrm{~V}=-\mathrm{V}_{\mathrm{o}} & \mathrm{~T}_{3}+2 \pi \mathrm{ak}<\tau<\tau_{4}+2 \pi a k=\tau_{1}+2 \pi \mathrm{a}(\mathrm{k}+1) \\
& \mathrm{k}=0, \pm 1, \pm 2, \ldots \tag{3-20}
\end{array}
\]
\(C_{m}\) is given by
\[
\begin{equation*}
C_{m}=\frac{1}{2 \pi a} \int_{T_{1}}^{\tau} v_{0} e^{-j \frac{m}{a}} d \tau-\int_{\tau_{2}}^{T} 1+2 \pi a \quad v_{0} e^{-j \frac{m}{a} \tau} d \tau \tag{3-21}
\end{equation*}
\]
and
\[
\begin{align*}
& C_{o}=v_{o}\left[\frac{\tau_{2}-\tau_{1}}{\pi a}-1\right] \\
& C_{m}=\frac{j v_{0}}{\pi m}\left[e^{-j \frac{m}{a} \tau_{2}}-e^{-j \frac{m}{a} \tau}\right] \quad m \neq 0 \tag{3-22}
\end{align*}
\]

Substitution of \(C_{m}\) from Eq. 3-22 into Eqs. 3-18 and 3-22 gives an explicit expression for the potential at any point in terms of the parameters \(a, \tau_{1}, \tau_{2}\), and \(\theta_{0}\) as
\[
\frac{v}{V_{0}}=\left[-\frac{\tau_{2}-\tau_{1}}{\pi a}-1\right]+\frac{1}{\pi} \sum_{\substack{m=-\infty \\ m \neq 0}}^{\infty} \frac{j}{m}\left[e^{-j \frac{m}{a} \tau 2}-e^{-j \frac{m}{a} \tau 1}\right]_{\substack{P^{\frac{m}{a}}} \frac{p^{m}(\operatorname{m}}{P^{m}}(\cos \theta)}^{j \frac{m}{a} \tau} e^{j \leq \theta_{0}}
\]
\[
\left.\frac{v}{v_{0}}=\left[\frac{\tau_{2}-\tau 1}{\pi a}-1\right]+\frac{1}{\pi} \sum_{\substack{m \neq-\infty \\ m \neq 0}}^{\infty} \frac{j}{m}\left[e^{-j \frac{m}{a} 2}-e^{-j \frac{m}{a} \tau}\right]\right]_{\substack{P^{m} \\ P^{m}}}^{j^{\frac{m}{a}}\left(-\cos \theta_{0}\right)} e^{j \frac{m}{a} \tau} \theta_{0}
\]

\subsection*{3.5 Potential on the Boundary for an Arbitrary Gap}

With an arbitrary gap between the arms of the spiral the problem of determining the potential distribution in the gap is complicated by the mixed boundary conditions.

Exact solutions for some two dimensional potential problems with mixed boundary conditions can be obtained by using conformal mapping techniques \({ }^{11}\). For example, an exact expression can be obtained for the potential distribution across a slit in an infinite plane sheet \({ }^{12}\). For a small gap in the equiangular spiral structure the potential in the gap might be approximated by using the distribution obtained from the plane sheet case, however, there does not appear to be a simple method of deriving an exact expression for the potential in the gap. Any method seems to depend on an iterative procedure,
the simultaneous solution of an infinite set of equations, or the equivalent. However, if the gap potential is approximated by using a finite number of terms in the Fourier expansion of Eq. 3-16, the least squares criterion \({ }^{13}\) provides a method for determining the best values for the coefficients. Approximating with \(2 M+1\) terms of the series and using the subscripts I and II to identify the approximate solutions for \(\theta<\theta_{0}\) and \(\theta>\theta_{0}\) respectively, the expressions for the potential are from Eqs. 3-15 and 3-18,

\[
\begin{equation*}
V_{\text {II }}(\theta, \tau)=\sum_{m=-M}^{M} C_{m} \frac{P^{m \frac{m}{a}}(-\cos \theta)}{P_{j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)} e^{j \frac{m}{a} \tau} \quad \theta>\theta_{0} \tag{3-24}
\end{equation*}
\]

In terms of \(C_{m}\) the potential at \(\theta=\theta_{0}\) is
\[
\begin{equation*}
V_{I}\left(\theta_{0}, \tau\right)=\sum_{m=-M}^{M} C_{m} e^{j \frac{m}{a} \tau}=V_{\text {III }}\left(\theta_{0}, \tau\right) \tag{3-25}
\end{equation*}
\]

For \(\tau_{1}<\tau<\tau_{2}\) the error in the potential due to using a finite number of terms is
\[
v_{o}-\sum_{m=-M}^{M} c_{m} e^{j \frac{m}{a} \tau}
\]
and for \(\tau_{3}<\tau<\tau_{4}\) the error is
\[
-v_{o}-\sum_{m=-M}^{M} C_{m} e^{j \frac{m}{a} \tau}
\]

For \(\theta<\theta_{0}\) the normal derivative of the potential is
\[
\begin{equation*}
\left.\frac{\partial V_{I}}{\partial \theta}\right]_{\theta=\theta_{0}}=\sum_{m=-M}^{M} A_{m} \frac{d P^{m} \frac{m}{a}\left(\cos \theta_{0}\right)}{d \theta} e^{j \frac{m}{a} T} \tag{3-26}
\end{equation*}
\]
where
\[
\left.\frac{d p_{j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}{d \theta}=\frac{d p_{j \frac{m}{a}}^{m}(\cos \theta)}{d \theta}\right] \theta=\theta_{0}
\]
and for \(\theta>\theta_{0}\)
\[
\begin{equation*}
\left.\frac{\partial V_{I I}}{\partial \theta}\right]_{\theta=\theta_{0}}=\sum_{m=-M}^{M} B_{m} \frac{d P^{m} \frac{m}{a}\left(-\cos \theta_{0}\right)}{d \theta} \tag{3-27}
\end{equation*}
\]

As the normal derivatives should be equal in the gap at \(\theta=\theta_{0}\), the error is
where
\[
\begin{align*}
& \left.\left.\frac{\partial V_{I}}{\partial \theta}\right] \theta=\theta_{0}-\frac{\partial V_{\text {II }}}{\partial \theta}\right] \theta=\theta_{0}=\sum_{m=-M}^{M} \gamma_{m} c_{m} e^{j \frac{m}{a} \tau}  \tag{3-28}\\
& \gamma_{m}=\frac{\operatorname{dP}_{j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}{B_{j-\frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}-\frac{d p_{j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)}{\sum_{j \frac{m}{m}}^{m}\left(-\cos \theta_{0}\right)} . \tag{3-29}
\end{align*}
\]

The mean square error \(\vec{M}\) over a pertod is
\[
\begin{align*}
& \vec{M}=\int_{\tau}^{\tau} 2\left[v_{0}-\sum_{m=-M}^{M} c_{m} e^{j \frac{m}{a} \tau}\right]^{2} d \tau+\int_{\tau}^{\tau}\left[\sum_{m=-M}^{M} \gamma_{m} c_{m} e^{j \frac{m}{a} \tau}\right]^{2} d \tau \\
& +\int_{\tau_{3}}^{\tau}\left[v_{0}+\sum_{m=-M}^{M} c_{m} e^{j \frac{m}{a} \tau}\right]^{2} d \tau+\int_{\tau^{\prime}}^{\tau} 1+2 \pi a\left[\sum_{m=-M}^{M} \gamma_{m} c_{m} e^{j \frac{m}{a} \tau}\right]^{2} d \tau \tag{3-30}
\end{align*}
\]

By setting the derivative of \(\bar{M}\) with respect to each \(C_{m}\) equal to zero, a system of \(2 \mathrm{M}+1\) equations and \(2 \mathrm{M}+1\) unknowns is obtained for any nôn-zero width of the spiral arms. As \(V_{0}\) is real, \(C_{-m}\) is the complex conjugate of \(C_{m}\), and the equations may be reduced to \(M+1\) equations and \(M+1\) unknowns. Using \(*\) to indicate the complex conjugate, the
-
first of these equations is
\[
\begin{gather*}
C_{0}\left[\left(T_{2}-T_{1}+T_{4}-T_{3}\right)\left(1-\gamma_{0} \gamma_{0}^{*}\right)+2 \pi a r \gamma_{0} \gamma_{0}^{*}\right]-\sum_{m=1}^{M}\left(1-\gamma_{0} \gamma_{0}^{*}\right) \\
{\left[C_{m} L_{m}+C_{m}^{*} L_{-m}\right]=V_{0}\left[T_{2}-T_{1}-T_{4}+T_{3}\right]} \tag{3-31}
\end{gather*}
\]
and the remaining \(M\) equations are obtained by using integer values of \(p\) from 1 to \(M\) in
\(C_{p}^{*}\left[\left(T_{2}-T_{1}+\tau_{4}-T_{3}\right)\left(1-\gamma_{p} \gamma_{p}^{*}\right)+2 \pi a \gamma_{p} \gamma_{p}^{*}\right]+\sum_{\substack{m=1 \\ m \neq p}}^{M} \underset{m}{C} L_{p-m}\left(1-\gamma_{p} \gamma_{m}^{*}\right)\)
\[
+\sum_{m=0}^{M} C_{m}^{L}{ }_{p+m}\left(1-\gamma_{p} \gamma_{m}=\frac{a}{j p} V_{o}\left[e^{j \frac{p}{a} T_{2}}-e^{j \frac{p}{a} T} 1-e^{j \frac{p}{a} T} 4 \quad+e^{j \frac{p}{a} T} 3\right]_{(3-32)}\right.
\]
where
\[
\begin{equation*}
L_{k}=\frac{a}{j k}\left[e^{j \frac{k}{a} \tau} 2-e^{j \frac{k}{a} T} 1+e^{j \frac{k}{a} T} 4-e^{j \frac{k}{a} T^{3}}\right] \tag{3-33}
\end{equation*}
\]

The simultaneous solution of the \(M+1\) linear algebraic equations of Eqs. 3-31 and 3-32 gives the best values for the \(C_{m}^{\prime}\) in the least squares sense for arbitrary parameters in the spiral structure, and Eq. 3-24 expresses the potential in terms of the \(C_{m}^{1} s\).

Even though Eqs. 3-31 and 3-32 may be simplified somewhat by an appropriate choice of the various parameters, the labor involved in making a numerical calculation of the potential does not seem justified. The static solutions were originally considered to obtain a feeling for problems with spiral boundaries and, also, with the faint hope that there might be a simple relation between the static and time-varying solutions. The fact that relatively simple expressions for the potential can be derived when the gap between the spiral arms is small indicates that it is worthwhile, at least for this special case, to consider the much more difficult problem of determining the electromagnetic fields produced by the equiangular spiral antenna.

\section*{3. 6 Expressions for the Electric Field Intensity}

The three spherical components of the electric field intensity
can be determined by taking the negative of the gradient of the potential,
\[
\begin{equation*}
\underline{E}=-\operatorname{grad} V \tag{3-34}
\end{equation*}
\]

The resulting expressions for the electric field intensities in terms of the \(C_{m}{ }^{\prime} s\) for \(\theta<\theta_{0}\) are
\[
\begin{align*}
E_{r} & =\frac{1}{r} \sum_{m=-\infty}^{\infty} j \frac{m}{a} C_{m} \frac{P^{m}\left(\operatorname{m} \frac{m}{a}\right.}{P_{j}^{m}(\cos \theta)} j_{j}^{a}
\end{align*} e^{j \frac{m}{a} \tau}
\]
and for \(\theta>\theta_{0}\) the expressions are the same except that \(P_{j \frac{m}{a}}^{m}(\cos \theta)\)
and \(\quad d P_{j \frac{m}{m}}^{m}(\cos \theta)\) are replaced by \(p_{j \frac{m}{m}}^{m}(-\cos \theta)\)

and \(d P_{j-\frac{m}{m}}^{m}(-\cos \theta)\) respectively. It is noted that \(E_{r}\) and \(E_{\phi}\) for any \(\frac{j \frac{m}{a}}{d \theta}\)
spiral structure and all \(\theta\) are simply related by
\[
\begin{equation*}
E_{\phi}=-\frac{a}{\sin \theta} E_{r} \tag{3-36}
\end{equation*}
\]
for the static fields.

\section*{4. THE ELECTROMAGNETIC FIELDS}

\subsection*{4.1 Introduction}

To determine exact solutions to a general antenna problem, Maxwell's equations are often used as a starting point. In differential form for a homogeneous, isotropic, sourcefree region they are
\[
\begin{align*}
& \operatorname{curl} \underline{\bar{E}}=-\mu \frac{\partial \bar{H}}{\partial \mathrm{t}} \\
& \operatorname{curl} \underline{\bar{H}}=\epsilon \frac{\partial \overline{\mathrm{E}}}{\partial \mathrm{t}} \tag{4-1}
\end{align*}
\]

The elimination of \(\bar{E}\) (or \(\overline{\underline{H}}\) ) in Eq. 4-1 results in the vector wave equation
\[
\begin{equation*}
\operatorname{curl} \operatorname{curl} \underline{\bar{E}}+\mu \epsilon \frac{\partial^{2} \bar{E}}{\partial t^{2}}=0 \tag{4-2}
\end{equation*}
\]
in \(\underline{E}\) (or \(\overline{\underline{H}}\) ). By considering monochromatic sinusoidal oscillations the time dependence may be removed. Using the complex number representation with \(e^{j \omega t}\) time convention
\[
\begin{align*}
& \underline{E}=\operatorname{Re}\left[\underline{E} e^{j \omega t}\right]  \tag{4-3}\\
& \underline{\bar{H}}=\operatorname{Re}\left[\underline{H} e^{j \omega t}\right],
\end{align*}
\]
and the vector wave equation reduces to the vector Helmholtz equation in \(\underline{E}\) (or \(\underline{H}\) )
\[
\begin{equation*}
\operatorname{curl} \operatorname{curl} \underline{E}=\beta^{2} \underline{E} \tag{4-4}
\end{equation*}
\]
with \(\beta^{2}=\omega^{2} \mu \epsilon\).
It is desired to find solutions of Eq. 4-4 which satisfy the boundary conditions of an equiangular spiral structure and meet the physical requirements of an electromagnetic field.
4.2 An Orthogonal Spiral Coordinate System

To obtain the needed solutions of the vector Helmholtz eqiation,
it is very desirable to have an orthogonal coordinate system which "fits" the boundaries of the equiangular spiral structure. When the antenna is developed in the plane \(\theta=\pi / 2\) an orthogonal coordinate system which "fits" the antenna may be developed. In terms of the usual cylindrical coordinates \(\rho, \phi\), and \(z\) let
\[
\begin{align*}
& q=\rho e^{-a \phi} \\
& \eta=\rho e^{\phi / a}  \tag{4-5}\\
& z=z
\end{align*}
\]
and \(\zeta, \eta\), and \(z\) form an orthogonal system. In the plane \(z=0\) a line of constant \(\hat{\zeta}\) coincides with an edge of the antenna, and lines of constant \(\eta\) form a set of equiangular spirals which are perpendicular to the edges of the antenna. However, this coordinate system is not one of the limited number of orthogonal systems in which the vector Helmholtz equation is separable, and no method could be found to adapt it to an exact solution of the equiangular spiral antenna problem. This system is useful in solving spiral problems in which there is no variation in the \(z\) direction, and is mentioned here as it seems to be an "obvious" system to use.

\subsection*{4.3 An Oblique Spiral Coordinate System}

The fact that the static potentials can be expressed in terms of only the two variables \(s\) and \(\theta\) suggests their use as the basis of a spiral coordinate system. The time-varying fields can not be expressed in terms of \(s\) and \(\theta\) only, and the "logical" choice for a third variable is one which will complete an orthogonal system. Letting \(p=p(r, \theta, \phi)\) represent the third coordinate variable, a unit vector \(\hat{\underline{p}}\) which is
normal to a surface of constant \(p\) is given by
\[
\begin{equation*}
\underline{\hat{p}}=\frac{\operatorname{grad} \mathrm{p}}{|\operatorname{grad} \mathrm{p}|} . \tag{4-6}
\end{equation*}
\]

To form an orthogonal system \(\hat{\hat{p}}\) must satisfy
\[
\begin{equation*}
\underline{\hat{p}}=\underline{\hat{s}} \times \underline{\hat{\theta}} \tag{4-7}
\end{equation*}
\]
where \(\underline{\hat{s}}\) and \(\underline{\hat{\theta}}\) are unit vectors normal to constant \(s\) and \(p\) surfaces respectively. The expression for \(\hat{\hat{s}}\) is
\[
\begin{equation*}
\underline{\hat{s}}=\frac{\operatorname{grad} s}{|\operatorname{grad} s|}=\frac{\sin \theta}{\sqrt{a^{2}+\sin ^{2} \theta}} \hat{\underline{r}}-\frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}} \hat{\phi} \tag{4-8}
\end{equation*}
\]

Combining Eqs. 4-6, 4-7, and 4-8 gives
\[
\begin{equation*}
\frac{\operatorname{grad} p}{|\operatorname{grad} p|}=\frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}} \underline{\hat{r}}+\frac{\sin \theta}{\sqrt{a^{2}+\sin ^{2} \theta}} \hat{\phi} \tag{4-9}
\end{equation*}
\]
which leads directly to the three separate equations
\[
\frac{\partial p}{\partial r}=|\operatorname{grad} p| \frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}}, \frac{\partial p}{\partial \theta}=0, \text { and } \frac{\partial p}{\partial \phi}=|\operatorname{grad} p| \frac{r \sin ^{2} \theta}{\sqrt{a^{2}+\sin ^{2} \theta}}
\]

From Eq: \(4-10\), \(p\) must be both independent of \(\theta\), and
\[
\frac{\partial \mathrm{p} / \partial \mathrm{r}}{\partial \mathrm{p} / \partial \phi}=\frac{\mathrm{a}}{\mathrm{r} \sin ^{2} \theta}
\]

The desired function \(p(r, \theta, \phi)\) does not exist, and it is not possible to form an orthogonal coordinate system using \(s\) and \(\theta\) as two of the variables.

For lack of a better set, the variables
\[
\begin{align*}
& u=\beta r \\
& \theta=\theta  \tag{4-11}\\
& s=r e^{-\mathrm{a} \phi}
\end{align*}
\]
are used. This oblique coordinate system has two distinct advantages. It permits separated solutions of the vector Helmholtz equation which
are similar to those obtained with the spherical coordinate system. Also, with it both the vector Helmholtz equation and the boundary conditions are independent of \(\beta\). As this system is oblique it is of ten convenient to express the various components of the field vectors in a mixed system using the spherical unit vectors \(\underline{\hat{r}}, \underline{\hat{\theta}}\), and \(\hat{\phi}\), and the spiral variables \(u, \theta\) and \(s\). At times the spiral unit vectors \(\underline{\hat{s}}\) and \(\underline{\hat{p}}\) given by
\[
\begin{align*}
& \underline{\hat{s}}=\frac{\sin \theta}{\sqrt{a^{2}+\sin ^{2} \theta}} \underline{\hat{r}}-\frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}} \underline{\hat{\phi}}  \tag{4-12}\\
& \underline{\hat{p}}=\frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}} \hat{\underline{r}}+\frac{\sin \theta}{\sqrt{a^{2}+\sin ^{2} \theta}} \hat{\phi}
\end{align*}
\]
and the field intensities in these directions will also be used.
4.4 The Vector Helmholtz Equation with Spiral Variables

The vector Helmholtz equation expanded in spherical coordinates \({ }^{14}\) is given in Eq. 4-13. For \(\beta \neq 0\) in a mixed spherical spiral system Eq. 4-13 becomes Eq. 4-14. Originally the vector Helmholtz equation is a function of four variables \(r, \theta, \phi\), and \(\beta\), but Eq. 4-14 (and the boundary conditions) are a function of only the three variables \(u\), \(s\), and \(\theta\).

\subsection*{4.5 Separated Solutions}

As Maxwell's equations include the relation div \(\underline{E}=0\), the vector solutions of Eq. 4-14 may be expressed in terms of only two scalar functions. One of the scalar functions can be chosen to generate a transverse electric (TE) field with \(\mathrm{E}_{\mathrm{r}}=0\), and the second scalar function chosen to generate a transverse magnetic (TM) field with \(H_{r}=0\). Using a prime to indicate the fields of the \(T E\) solution and double prime for the fields of the \(T M\) solution, the total electric

and magnetic fields are
\[
\begin{align*}
& \underline{\mathrm{E}}=\underline{\mathrm{E}}^{\prime}+\underline{\mathrm{E}}^{\prime \prime} \\
& \underline{\mathrm{H}}=\underline{\mathrm{H}}^{\prime}+\underline{\mathrm{H}}^{\prime \prime} \tag{4-15}
\end{align*}
\]

Considering first the TE case, a scalar function \(\Pi^{\prime}=\Pi^{\prime}(u, \theta, s)\) which gives a field with \(E_{r}^{\prime}=0\) may be derived from
\[
\begin{equation*}
\underline{E}^{\prime}=\frac{\operatorname{curl} \hat{\underline{\hat{r}}} \Pi^{\prime}}{\beta} \tag{4-16}
\end{equation*}
\]
\(\underline{E}^{\prime}\) satisfies all three of the equations contained in Eq. 4-13 if \(\Pi^{\prime}\) is a solution of
\[
\begin{align*}
& \frac{1}{\sin \theta}\left[\frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial \Pi^{\prime}}{\partial \theta}\right)\right]+\left(1+\frac{a^{2}}{\sin ^{2} \theta}\right) s \frac{\partial}{\partial s}\left(s \frac{\partial \Pi^{\prime}}{\partial s}\right)+\text { us } \frac{\partial^{2} \Pi^{\prime}}{\partial s^{\partial u}} \\
&  \tag{4-17}\\
& +u^{2} \frac{\partial}{\partial u}\left(\frac{s}{u} \frac{\partial \Pi^{\prime}}{\partial s}\right)+u^{2} \frac{\partial^{2} \Pi^{\prime}}{\partial u^{2}}+u^{2} \Pi^{\prime}=0 .
\end{align*}
\]

The solutions of Eq. 4-17 will be obtained in separated form, and as more than one of the separated solutions will be needed, let
\[
\begin{equation*}
\Pi^{\prime}=\sum_{\kappa} A_{\kappa}^{\prime} \pi_{\kappa}^{\prime} \tag{4-18}
\end{equation*}
\]
where \(A_{K}^{\prime}\) is a constant and \(\sum_{\kappa}\) indicates a summation over all appropriate values of the separation constants. Making use of the same substitution that proved useful in the static solutions,
\[
T=\ln s
\]
\(\Pi^{\prime}\) satisfies Eq. 4-17 if \(\pi_{\kappa}^{\prime}\) is a solution of
\[
\begin{align*}
\frac{1}{\sin \theta} & {\left[\frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial \pi_{\kappa}^{\prime}}{\partial \theta}\right]+\left(1+\frac{a^{2}}{\sin ^{2} \theta}\right) \frac{\partial^{2} \pi_{\kappa}^{\prime}}{\partial \tau^{2}}+u \frac{\partial^{2} \pi_{\kappa}^{\prime}}{\partial u \partial \tau}+u^{2}\left(\frac{1}{u} \frac{\partial \pi_{\kappa}^{\prime}}{\partial \tau}\right)\right.} \\
& +u^{2} \frac{\partial^{2} \pi_{\kappa}^{\prime}}{\partial u^{2}}+u^{2} \pi_{\kappa}=0 \tag{4-20}
\end{align*}
\]

Assuming a separated solution of the form
\[
\begin{equation*}
\pi_{K}^{\prime}=U(u) \Theta(\theta) e^{j \frac{m}{a} T} \tag{4-21}
\end{equation*}
\]
with \(U\) independent of \(\theta\) and \(\tau\), and \(\theta\) independent of \(u\) and \(\tau, \Pi_{K}^{\prime}\) is a solution of Eq. 4-20 if \(U\) and \(\theta\) satisfy the ordinary differential equations
\[
\begin{gather*}
\frac{d^{2} \Theta}{d \theta}+\operatorname{ctn} \theta \frac{d \Theta}{d \theta}+\left[v(v+1)-\frac{\cdots m^{2}}{\sin ^{2} \theta}\right] \Theta=0  \tag{4-22}\\
u^{2} \frac{\partial^{2} U}{\partial u^{2}}+j \frac{m}{a} 2 u \frac{\partial U}{\partial u}+\left[u^{2}-v(v+1)-j \frac{m}{a}\left(1-j \frac{m}{a}\right)\right] U:=0 \tag{4-23}
\end{gather*}
\]
and
\(v\) is a separation constant, and the appropriate values for \(v\) and \(m\) are still to be determined. : To have fields which vary periodically in \(\phi\) with a period of \(2 \pi a, m\) must be integral. It will later be shown that the required values of \(v\) are complex.

Eq. 4-22 is similar to Eq. 3-10 obtained in the static solutions and is a form of the associated Legendre equation of degree \(v\) and order m . The two linearly independent solutions of Eq. 4-22 are the associated Legendre functions of the first kind \(P_{\nu}{ }^{m}(\cos \theta)\) and the second kind \(Q_{\nu}{ }^{m}(\cos \theta)\). For \(m\) zero or a positive integer there are no solutions of Eq. 4-22 which are finite for all real values of \(\theta\) unless \(v\) is an integer greater than or equal to \(m\). Since \(v\) is not to be an integer, it is again necessary to consider solutions in two regions as illustrated in Fig. 4. For the required values of \(v\), \(Q_{\nu}{ }^{m}(\cos \theta)\) becomes infinite both at \(\theta=0\) and \(\pi\) and is not useful for representing a physical field. \(P_{\nu}{ }^{m}(\cos \theta)\) is finite for all \(\theta\) except \(\theta=\pi\), and for mero or a positive integer is given by
\[
P_{v}^{m}(\cos \theta)=\frac{(-)^{m} \Gamma(\hat{\psi}+m+1)}{2^{m} \Gamma(\nu-m+1)} \times \frac{\sin ^{m} \theta}{m!} F\left(m-v, v+m+1 ; m+1 ; \sin ^{2} \frac{\theta}{2}\right)
\]
and for \(m\) a negative integer by
\[
\begin{equation*}
P_{\nu}^{m}(\cos \theta)=\frac{\sin ^{-m} \theta}{2^{-m}(-m)!} F\left(\nu-m+1,-m-\nu ; 1-m ; \sin ^{2} \frac{\theta}{2}\right) \tag{4-25}
\end{equation*}
\]
\(P_{\nu}{ }^{m}(\cos \theta)\) may be used in representing the fields in region \(I\) for \(\theta<\theta_{0}\), and \(P_{\nu}{ }^{m}(-\cos \theta)\) used in region II for \(\theta>\theta_{0}\).

Solutions of Eq. 4-23 can be expressed in terms of the Bessel functions \({ }^{15}\) as
\[
\begin{equation*}
U(u)=u^{\frac{1}{2}} u^{-j \frac{m}{a}} z_{v+\frac{1}{2}}(u) \tag{4-26}
\end{equation*}
\]
where \(Z_{v+\frac{1}{2}}(u)\) represents a Bessel function of order \(v+\frac{1}{2}\). Watson \({ }^{16}\) has given a very detaildd account of the properties of the Bessel functions of complex order. The Bessel function of the first kind \(J_{\nu+\frac{1}{2}}(u)\) of order \(\nu+\frac{1}{2}\) is defined by \({ }^{17}\)
\[
\begin{equation*}
J_{v+\frac{1}{2}}(u)=\sum_{P=0}^{\infty} \frac{(-)^{p}\left(\frac{u}{2}\right)^{v+2 p+\frac{1}{2}}}{p!\Gamma(v+p+1)} \tag{4-27}
\end{equation*}
\]

For complex values of \(v, J_{\nu+\frac{1}{2}}(u)\) and \(J_{-v-\frac{1}{2}}(u)\) are linearly independent solutions of Bessel's equation, and, therefore the needed solutions of Eq. 4-23 can be expressed by using only Bessel functions of the first kind.

Using the subscripts \(I\) and II to indicate solutions valid for \(\theta<\theta_{0}\) and \(\theta>\theta_{0}\) respectively, the general forms for the scalar function \(\Pi^{\prime}\) which generates the TE part of the field are
\[
\begin{align*}
& \text { for region } I, \theta<\theta_{0} \\
& \qquad \Pi_{I}^{\prime}=\sum_{v m} A_{v}^{\prime m} u^{\frac{1}{2}} u^{-j \frac{m_{4}}{a}} J_{v+\frac{1}{2}}^{(u)} p_{v}^{m}(\cos \theta) e^{j \frac{m^{2}}{a}} \tag{4-28}
\end{align*}
\]
for region II, \(\theta>\theta_{0}\)
\[
\begin{equation*}
\Pi_{\text {III }}^{\prime}=\sum_{\nu m} B_{\nu}^{\prime m} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{\nu+\frac{1}{2}}^{(u)} P_{v}^{m}(-\cos \theta) e^{j \frac{m}{a} T} \tag{4-28}
\end{equation*}
\]

In a similar manner the expressions for the scalar \(\Pi^{\prime \prime}\) which generates the TM part of the field are
\[
\begin{aligned}
& \text { for region } I, \theta<\theta_{0}, \\
& \qquad \Pi_{I}^{\prime \prime}=\sum_{\bar{\nu} m} A_{\bar{\nu}}^{\prime m} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{\bar{\nu}+\frac{1}{2}}^{(u)} P_{\bar{\nu}}^{m}(\cos \theta) e^{j \frac{m}{a} T} \\
& \text { for region II, } \theta>\theta_{0} \\
& \Pi_{I I}^{\prime \prime}=\sum_{\bar{\nu} m} B_{\bar{\nu}}^{\prime \prime m} u^{\frac{1}{2} u^{-j \frac{m}{a}} J_{\bar{\nu}+\frac{1}{2}}^{(u)} P_{\bar{\nu}}^{m}(-\cos \theta) e^{j \frac{m}{a} \tau}}
\end{aligned}
\]
where \(\bar{v}\) is the separation constant.
From Eqs. 4-16, 4-28, 4-29, and Maxwell's equations, the following expressions for the electric and magnetic fields with spiral variables may now be derived.

TE Components - Region I \(\quad \theta<\theta_{0}\)
\[
\begin{align*}
& \eta=\sqrt{\frac{\mu}{\epsilon}} \\
& E_{r}^{\prime}=0 \\
& E_{\theta}^{\prime}=-\frac{a}{u \sin \theta} \sum_{m v} A_{v}^{\prime m}\left(j \frac{m}{a}\right) u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{v+\frac{1}{2}}(u) P_{\psi}{ }^{m}(\cos \theta) e^{j \frac{m}{a} \tau} \tag{4-30b}
\end{align*}
\]
\[
(4-30 a)
\]
\(E_{\phi}^{\prime}=-\frac{1}{u} \sum_{m \nu} A_{\nu}^{\prime m} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{\nu+\frac{1}{2}} \frac{d P_{\nu}{ }^{m}(\cos \theta)}{d \theta} e^{j \frac{m}{a} T}\)
\(-j \eta H_{r}^{\prime}=\frac{1}{u^{2}} \sum_{m v} v(\nu+1) A_{\nu}^{\prime m} u^{\frac{1}{2} u^{-j \frac{m}{a}}} J_{\nu+\frac{1}{2}}(u) P_{\nu}{ }^{m}(\cos \theta) e^{j \frac{m}{a} \tau}\)
\[
\begin{align*}
& -j \eta H_{\theta}^{\prime}=\frac{1}{u} \sum_{m \nu} A_{\nu}^{\prime m} u^{\frac{1}{2}} u^{-j \frac{m}{a}}\left[-\frac{\nu}{u} J_{v+\frac{1}{2}}(u)+J_{v-\frac{1}{2}}(u)\right] \frac{d P_{v}^{m}(\cos \theta)}{d \theta} e^{j \frac{m}{a} \tau}  \tag{4-30e}\\
& -j \eta H_{\phi}^{\prime}=-\frac{a}{u \sin \theta} \sum_{m \nu} A_{\nu}^{\prime m}\left(j \frac{m}{a}\right) u^{\frac{1}{2}} u^{-j \frac{m}{a}}\left[-\frac{\nu}{u} J_{v+\frac{1}{2}}(u)+J_{\nu-\frac{1}{2}}(u)\right] P_{\nu}^{m}(\cos \theta) e^{j \frac{m}{a} T}
\end{align*}
\]

TM Components - Region I \(\quad \theta<\theta_{0}\)
\[
\begin{align*}
& E_{r}^{\prime \prime}=\frac{1}{u^{2}} \sum_{m \vec{\nu}} \bar{v}(\bar{v}+1) A_{\bar{\nu}}^{\prime \prime m} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{\bar{v}+\frac{1}{2}}(u) P_{\bar{v}}^{m}(\cos \theta) e^{j \frac{m}{a} \tau} \\
& E_{\theta}^{\prime \prime}=\frac{1}{u} \sum_{m \nu} A_{\bar{v}}^{\prime \prime m} u^{\frac{1}{2}} u^{-j \frac{m}{a}}\left[-\frac{\bar{v}}{u} J_{\bar{\nu}+\frac{1}{2}}(u)+J_{\bar{v}-\frac{1}{2}}(u)\right] \frac{d P_{\bar{v}}^{m}(\cos \theta)}{d \theta} e^{j \frac{m}{a} \tau} \\
& E_{\phi}^{\prime \prime}=-\frac{a}{u \sin \theta} \sum_{m \bar{\nu}} A_{\bar{v}}^{\prime \prime m}\left(j \frac{m}{a}\right) u^{\frac{1}{2}} u^{-j \frac{m}{a}}\left[-\frac{\bar{v}^{u}}{u} J_{\bar{v}+\frac{1}{2}}(u)+J_{\bar{v}-\frac{1}{2}}(u)\right] P_{\bar{v}}^{m}(\cos \theta) e^{j \frac{m}{a} \tau} \\
& \text { (4-30i) } \\
& -j \eta H_{\mathbf{r}}^{\prime}=0 \\
& -j \eta H_{\theta}^{\prime \prime}=-\frac{a}{u \sin \theta} \sum_{m \vec{\nu}} A_{\nu} A^{m}\left(j \frac{m}{a}\right) u^{u^{\frac{1}{2}} u}{ }^{-j \frac{m}{a}} J_{\bar{\nu}+\frac{1}{2}}(u) P_{\bar{\nu}}{ }^{m}(\operatorname{oos} \theta) e^{j \frac{m}{a} \tau}  \tag{4-30k}\\
& -j \eta H_{\phi}^{\prime \prime}=-\frac{1}{u} \sum_{m \bar{\nu}} A_{\nu}{ }^{\prime \prime}{ }^{m} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{\bar{\nu}+\frac{1}{2}}(u) \frac{d P_{\bar{v}}{ }^{m}(\cos \theta)}{d \theta} e^{j \frac{m}{a} \tau} . \tag{4-301}
\end{align*}
\]

In region \(I I\) for \(\theta>\theta\) the general expressions for the fields are the same as those given in Eq. \(4-30\) with \(A_{\nu}^{\prime m}, A_{\bar{\nu}}^{1 \mathrm{~m}}, P_{\nu}{ }^{m}(\cos \theta)\),
\(\frac{d P_{\nu}{ }^{m}(\cos \theta)}{d \theta}, P_{\bar{v}}{ }^{m}(\cos \theta)\), and \(\frac{d P_{\bar{\nu}}{ }^{m}(\cos \theta)}{d \theta}\) replaced by \(B_{\nu}^{\prime m}, B_{\bar{v}}^{n m}\), \(P_{\nu}{ }^{m}(-\cos \theta), \frac{d P_{\nu}{ }^{m}(-\cos \theta)}{d \theta}, P_{\bar{\nu}}{ }^{m}(-\cos \theta)\), and \(\frac{d P_{\bar{\nu}}{ }^{m}(-\cos \theta)}{d \theta}\).

\subsection*{4.6 The Fields from Specified Conditions on the Boundary}

The values of \(\nu, m, A_{\nu}^{\prime m}, A_{\bar{v}}^{\prime \prime m}, B_{\nu}^{\prime m}\) and \(B_{\bar{v}}^{\prime \prime m}\) of Eq. \(4-30\) can be determined in terms of the tangential electric field at \(\theta=\theta_{0}\).

For an antenna developed on the cone \(\theta=\theta_{0}\) with one conducting arm between \(\tau_{1}\) and \(\tau_{2}\), and the other between \(\tau_{3}\) and \(\tau_{4}\), the fields are periodic in \(\tau\); the tangential field intensity over one period may be expressed as
\[
\begin{array}{rlrl}
\left.E_{r}\right]_{\theta=\theta_{0}} & =0 & \tau_{1}<\tau<\tau_{2}, & \tau_{3}<\tau<\tau_{4} \\
& =f(u, \tau) & \tau_{2}<\tau<\tau_{3}, &  \tag{4-31}\\
\tau_{4}<\tau<\tau_{1}+2 \pi a \\
\left.E_{\phi}\right]_{\theta=\theta_{\gamma}} & =0 & & \tau_{1}<\tau<\tau_{2}, \\
& & \tau_{3}<\tau<\tau_{4} \\
& =g(u, \tau) & \tau_{2}<\tau<\tau_{3}, & \\
\tau_{4}<\tau<\tau_{1}+2 \pi a
\end{array}
\]
\(f(u, \tau)\) and \(g(u, \tau)\) are the \(r\) and \(\varnothing\) components, respectively, of the electric field intensity in the gap and are assumed specified. As \(E_{r}^{\prime}=0,{ }^{p}{ }_{\bar{v}}{ }^{m}\) and \(B_{\bar{\nu}}{ }^{\prime \prime} m\) are determined from \(\left.E_{r}\right]_{\theta=\theta_{0}}\) only. For any constant \(u\), if \(\left.E_{r}\right] \theta=\theta_{0}\) in one period is continuous except for a finite number of finite disopntinuities and has only a finite number of maxima and minima, it may be represented by a Fourier series whose coefficients are functions of \(u\) alone.

Thus,
\[
\begin{equation*}
\left.E_{r}\right]_{\theta=\theta_{0}}=\sum_{m=-\infty}^{\infty} f_{m}(u) e^{j \frac{m}{a} T} \tag{4-32}
\end{equation*}
\]
with
\[
\begin{equation*}
f_{m}(u)=\frac{1}{2 \pi a} \int_{\tau}^{\tau} 3(u, \tau) e^{-j \frac{m}{a} \tau} d \tau+\frac{1}{2 \pi_{a}} \int_{\tau_{4}}^{\tau} f^{+2 \pi a} f(u, \tau) e^{-j \frac{m}{a}} d \tau \tag{4-33}
\end{equation*}
\]

Making use of Gegenbauer's generalization of Neumann's expansion \({ }^{18}\), \(u_{\mathrm{m}}(\mathrm{u})\) may be expanded in a series of Bessel functions. Considering \(u_{\text {, }}\) as a complex variable, if \(u f_{m}(u)\) is an entire function it may be

expanded in the series
\[
\begin{equation*}
u f_{m}(u)=\sum_{n=0}^{\infty} c_{n+j \frac{m}{a}}^{n} u^{-\frac{1}{2}} u^{-j \frac{m}{a}} J_{n+\frac{1}{2}+j \cdot j \frac{m}{a}}^{(u)^{\prime}} \tag{4-34}
\end{equation*}
\]
which converges for all \(u\). The coefficients \(C_{n+j \frac{\prime \prime}{a}}\) may be found by making use of Gegenbauer's polynomial \(\bigoplus_{\leqslant \frac{1}{2} n}^{n}(u) K\) defined by \({ }^{19}\)
\[
\begin{equation*}
F_{n, \kappa}^{(u)}=\frac{2^{n+\kappa}(n+\kappa)}{u^{n+1}} \sum_{p=0}^{\leqslant \frac{1}{2} n} \frac{\Gamma(n-p+\kappa)}{(p)!}\left(\frac{u}{2}\right)^{2 p} \tag{4-35}
\end{equation*}
\]
\(\nabla_{n, k}(u)\) and the Bessel functions of the first kind satisfy the relations
\[
\begin{align*}
& \int_{c} u^{-K} J_{n+K}^{(u)} \operatorname{F}_{k, K}^{(u)} d u=0 \quad k^{2} \neq n^{2} \\
& \int_{c} u^{-K} \underset{n+K}{(u)} F_{n, K}^{(u)} d u=2 \pi j \tag{4-36}
\end{align*}
\]
where cis a closed contour encircling the origin once in a positive direction. Using these expressions, \(C_{n+j \frac{m}{a}}^{\prime \prime m}\) can be expressed in terms of \(f_{m}(u)\) as
\[
\begin{equation*}
c_{n+j \frac{m}{a}}^{\prime \prime m}=\frac{1}{2 \pi j} \int_{c}^{\rho} u f_{m}(u) F_{n, \frac{1}{2}+j \frac{m}{a}}^{(u)} d u \tag{4-37}
\end{equation*}
\]
or in terms of \(f(u, T)\) as
\[
c_{n+j \frac{m}{a}}^{\prime \prime m}=\frac{1}{j a(2 \pi)^{2}} \int_{c}^{\rho}\left[\int_{\tau_{2}}^{\tau} u f(u, \tau) e^{-j \frac{m^{-}}{a}} d \tau+\int_{\tau_{4}}^{T_{1}+2 \pi a} u f(u, \tau) e^{-j \frac{m}{a} \tau} d \tau\right] F_{n, \frac{1}{2}+j \frac{m}{a}}^{(u)} d u
\]
\(\left.E_{r}\right]_{\Theta=\theta_{0}}\) has now been expanded in the double series
\[
\begin{equation*}
\left.E_{r}\right] \theta=\theta_{0}=\sum_{m=-\infty}^{\infty} \sum_{n=0}^{\infty} C_{n+j \frac{m}{a}}^{\prime \prime m} u^{-\frac{3}{2}} u^{-j \frac{m}{a}} J_{n+\frac{1}{2}+j \frac{m}{a}}^{(u)} e^{j \frac{m}{a} T} \tag{4-39}
\end{equation*}
\]

Comparing Eqs. 4-39 and \(4-30 \mathrm{~g}\) the characteristic values of \(\bar{v}\) are
\[
\begin{equation*}
\bar{v}=n+j \frac{m}{a} \tag{4-40}
\end{equation*}
\]
with \(n\) taking on integer values from 0 to \(+\infty\), and \(m\) integer values from \(-\infty\) to \(+\infty\). Also,
\[
\begin{gather*}
+\infty \text { Also, }  \tag{4-41}\\
A_{\bar{\nu}}^{\prime \prime m}=A_{n+j \frac{m}{a}}^{\prime \prime m}=\frac{C_{n+j \frac{m}{a}}^{\prime \prime m}}{\left(n+j \frac{m}{a}\right)\left(n+1+j \frac{m}{a}\right) P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{o}\right)} \\
B_{\bar{v}}^{\prime \prime m}=B_{n+j \frac{m}{a}}^{\prime \prime m}=\frac{C_{n+j \frac{m}{a}}^{m}}{\left(n+j \frac{m}{a}\right)\left(n+l+j \frac{m}{a}\right) P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{o}\right)}
\end{gather*}
\]
and

Therefore, Eqs. 4-38, 4-41, and 4-30 used in this order give explicit expressions for the \(T M\) components of all the electric and magnetic fields in terms of the specified tangential electric field in the gap.

After the \(T M\) components of the field are determined, the TE components may be obtained in a similar manner. Expanding \(\left.E_{\phi}\right]_{\theta=\theta_{0}}\) in a Fourier series,
\[
\begin{equation*}
\left.E_{\phi}^{\prime}\right] \theta=\theta_{0}=\sum_{m=-\infty}^{\infty} g_{m}(u) e^{j \frac{m_{T}}{a}} \tag{4-42}
\end{equation*}
\]
with
\[
\left.2 \pi a g_{m}(u)=\int_{T_{2}}^{T_{3}} g(u, T) e^{-j \frac{m^{-} T}{a}} d T+\int_{T_{4}}^{T_{1}+2 \pi a} g(u, T) e^{-j \frac{m^{T}}{a}} d T-\int_{T_{1}}^{T_{1}+2 \pi_{a}} E_{\phi}^{\prime \prime}\right]_{\theta=\theta_{0}} e^{-j \frac{m}{a} T} d T
\]

Expanding \(\mathrm{ug}_{\mathrm{m}}\) (u) in a series of Bessel functions,
\[
\begin{equation*}
\operatorname{ug}_{m}(u)=\sum_{n=-1}^{\infty} c_{n+j \frac{m}{a}}^{\prime} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{n+\frac{1}{2}+j \frac{m}{a}}^{(u)} \tag{4-44}
\end{equation*}
\]
with

These equations express \(E_{\phi} \quad \begin{aligned} & \square \\ & \phi=\theta_{0}\end{aligned}\) in a double series as
\[
\begin{equation*}
\left.E_{\phi}^{\prime}\right] \theta=\theta_{0}=\sum_{m=-\infty}^{\infty} \sum_{n=-1}^{\infty} C_{n+j \frac{m}{a}}^{\prime} u^{-\frac{1}{2}} u^{-j \frac{m}{a}} J_{n+\frac{1}{2}+j \frac{m}{a}}^{(u)} e^{j \frac{m}{a} T} \tag{4-46}
\end{equation*}
\]

Comparing Eq. 4-46 with Eq. \(4-30 \mathrm{~b}\) the characteristic values of \(v\) are
\[
\begin{equation*}
v=n+j \frac{m}{a} \tag{4-47}
\end{equation*}
\]
with \(n\) taking on integer values from -1 to \(+\infty\), and \(m\) integer values from \(-\infty\) to \(+\infty\). Also,
\[
\begin{equation*}
A_{v}^{\prime m}=A_{n+j \frac{m}{a}}^{\prime m}=\frac{-C_{n+j \frac{m}{a}}^{d P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}}{\frac{d \theta}{d i}} \tag{4-48}
\end{equation*}
\]
and
\[
B_{v}^{\prime m}=B_{n+j \frac{m}{a}}^{\prime m}=\frac{-C_{n+j \frac{m}{a}}^{\prime m}}{\frac{d P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)}{d \theta}}
\]

In terms of \(g(u, T)\). Eq. \((4-45)\) can be expressed as
\[
\begin{align*}
& +\frac{j m}{\sin \theta_{o}}\left[\frac{c_{n+1}^{\prime \prime}+j \frac{m}{a}}{\left(n+1+j \frac{m}{a}\right)\left(2 n+3+2 j \frac{m}{a}\right)}-\frac{c_{n-1+j \frac{m}{a}}}{\left(n+j \frac{m}{a}\right)\left(2 n-1+2 j \frac{m}{a}\right)}\right] \tag{4-49}
\end{align*}
\]
where \(C_{k+j \frac{m}{2}}^{m}\) is taken as zero for \(k<0\).
Eqs. 4-49, 4-48, and 4-30 used in sequence give explicit expressions
for the TE components of all the electric and magnetic fields in
terms of a specified tangential electric field in the gap.

\subsection*{4.7 The Mixed Boundary Conditions}

Having derived expressions for the electromagnetic fields at all points in terms of the tangential electric field at \(\theta=\theta_{0}\), one is faced with the more recondite problem of determining \(\underline{E}_{\tan }\) at \(\theta=\theta_{0}\) when the antenna is excited by a source at the origin. Assuming \(E_{\tan }\) in the gap, and from it calculating the performance of the antenna, is essentially the equivalent of assuming the current distribution on an antenna. Useful results are often obtained from assumed current distributions, and an assumption for \(\underline{E}_{\tan }\) in the gap based on experimental measurements could be made. However, this procedure somewhat avoids the problem, and it would be much more desirable if exact expressions could be derived. The correct \(\underline{E}_{\tan }\) in the gap will make \(\underline{H}_{\tan }\) continuous across the gap, will correspond to a finite input voltage at the origin, and will make the origin a source of energy. The complication of making \(\underline{H}_{\tan }\) continuous across the gap is due to the fact that there are no solutions of the associated Legendre equation of order \(m\) and degree \(n+j \frac{m}{a}\) which are finite for all \(\theta\). This makes the general problem one of mixed boundary conditions with \(\underline{E}_{\tan }\) specified as zero over the surface of the metal arms and \({\underset{\tan }{ }}\) specified as continuous across the gap. The solution of problems in electromagnetic theory with mixed boundary conditions normally lead to an iterative procedure where an approximate solution is assumed and from it better approximations calculated, or to the simultaneous solution of a large (infinite) set of simultaneous equations.

Regardless of the method used it seems highly desirable at
this point to consider approximations or simplifications which will reduce the complexity of the problem. Using the static solutions as a guide, the logical simplification is to consider that the gaps between the antenna arms are small. The equiangular spiral antenna with small gaps is a practical antenna having broadband characteristics. To determine \(E_{\text {tan }}\) in a wide gap one must find both \(E_{r}\) and \(E_{\phi}\), each of which is a function of two variables, \(u\) and \(\tau\). For a narrow gap, however, the electric field is always across the gap, so it is necessary to find only \(E_{s}\) which is a function of \(u\) only. Also, by making the arms of equal width the variations of \(E_{s}\) in the gap with \(u\) will be the same for both gaps. For these reasons the next section will develop a routine for determining the electric field produced in a small gap of a balanced equiangular spiral antenna by a source at the origin.

\section*{5. THE BALANCED ANTENNA WITH NARROW GAPS}
5.1 The Electric Fields at \(\theta=\theta_{0}\)

As the gaps between the arms of the equiangular spiral antenna are made narrow, \(\tau_{2} \rightarrow \tau_{3}\) and \(\tau_{4} \rightarrow \tau_{1}+2 \pi a\). If the antenna is also balanced (i.e. the arms are the same width) \(T_{3}=T_{1}+\pi\) a. Without loss of generality, the antenna can be rotated on the coordinate axis to make
\[
\begin{align*}
& \tau_{1}=0  \tag{5-1}\\
& \tau_{3}=\pi \mathrm{a}
\end{align*}
\]

When the gaps are narrow it is convenient to consider the components of the electric and magnetic fields which are in the directions of the unit vectors \(\underline{\hat{s}}\) and \(\underline{\hat{p}}\) defined by Eq. \(4-12\). Using Eq. \(4-12\) the \(s\) and \(p\) components of the electric (magnetic) fields \(E_{s}\left(H_{s}\right)\) and \(E_{p}\left(H_{p}\right)\) are
\[
E_{s}=\frac{\sin \theta}{\sqrt{a^{2}+\sin ^{2} \theta}} E_{r}-\frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}} E_{\phi}
\]
\[
\begin{equation*}
E_{p}=\frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}} E_{r}+\frac{\sin \theta}{\sqrt{a^{2}+\sin ^{2} \theta}} E_{\phi} \tag{5-2}
\end{equation*}
\]

The \(s\) component of the field is "across" the gap, and the \(p\) component is "along" the gap.

The fields in the gap are illustrated in Fig. 5. As the antenna arms are made of thin sheets of conducting material, the thickness of the arms \(\Delta \theta\) is assumed arbitrarily small, but not zero. As the gap width \(\Delta T\) approaches zero, \(E_{p}\) evaluated in the gap must approach zero. The field vectors satisfy Maxwell's equations and the well known conditions at the boundary surface between different media \({ }^{20}\). \(E_{p}\) is


FIGURE 5 ELECTRIC AND MAGNETIC FIELDS IN A NARROW GAP
zero inside the metal arms, and since the tangential components of \(\underline{E}\) are continuous across a boundary surface, \(E_{p}\) is zero just inside either edge of the gap at the points \(T=\tau_{2}^{+}\)and \(T=T_{3}{ }^{-}\). If \(E_{p}\) evaluated in the gap did not approach zero as \(\Delta \tau \longrightarrow 0, E_{p}\) would be discontinuous with respect to \(T\) between \(T=\tau_{2}{ }^{+}\)and \(T=\tau_{3}{ }^{-}\). However, this discontinuity in \(E_{p}\) is not allowable as the media is uniform between \(T=\tau_{2}{ }^{+}\) and \(T_{3}{ }^{-}\). When the gaps are made small the determination of the tangential electric fields on the cone \(\theta=\theta_{0}\) is simplified as the p component approaches zero, and only the s component need be found.

As the gaps are made small, \(E_{S}\) evaluated on the cone \(\theta=\theta_{0}\) is zero for all values of \(u\) and \(T\) except \(\tau=0, \pi\) a where it becomes infinite. The integral of \(E \cdot d 1\) across the gap represents a voltage and must be finite. Therefore, when the gaps are small an approximation for the tangential electric fields on the cone \(\theta=\theta_{0}\) is
\[
\begin{equation*}
\left.\mathrm{E}_{\mathrm{s}}\right]_{\Theta=\theta_{0}}=\mathrm{F}(\mathrm{u})[\delta(\mathrm{T}-0)-\delta(\mathrm{T}-\pi \mathrm{a})] \tag{5-3}
\end{equation*}
\]
\[
\left.\mathrm{E}_{\mathrm{p}}\right]_{\Theta=\theta_{0}}=0
\]
\(\delta\left(\tau-\tau_{0}\right)\) represents the Dirac delta "function" defined as
\[
\begin{array}{ll}
\delta\left(\tau-\tau_{0}\right)=0 & \tau \neq \tau_{0} \\
\delta\left(\tau-\tau_{0}\right)=\infty & \tau=\tau_{0}  \tag{5-4}\\
\int_{T_{0}-\epsilon}^{\tau_{0}+\epsilon} \delta\left(\tau-\tau_{0}\right) d \tau=1,
\end{array}
\]
and \(F(u)\) is an arbitrary function of \(u\) still to be determined.

The voltage \(V(u)\) across the gap is given by
\[
\begin{equation*}
V(u)=\int_{\operatorname{across} \operatorname{gap}}^{E \cdot d l} \tag{5-5}
\end{equation*}
\]

Integrating Eq. 5-5 relates \(V(u)\) and \(F(u)\) by
\[
\begin{equation*}
\beta V(u)=\frac{u F(u)}{\sqrt{a^{2}+\sin ^{2} \theta_{0}}} \tag{5-6}
\end{equation*}
\]

Since the antenna is balanced the voltage distribution \(V(u)\) will be the same for both gaps, and li.m \(V(u)\) gives the input voltage exciting \(u \rightarrow 0\) the antenna. By restricting the gap width to be very small, the problem of finding all of the fields produced by the spiral antenna has been reduced to finding the voltage along the gap.
5.2 Expressions for \(C_{n+j \frac{m}{a}}{ }^{m}\) and \(C_{n+j \frac{m}{a}}^{n}\)

To have the antenna excited at the origin by a finite voltage,
lim \(V(u)\) must be finite. Since \(V(u)\) represents the physical voltage \(u \rightarrow 0\)
obtained, it is reasonable to assume that \(V(u)\) is continuous and has continuous derivatives for all values of \(u\), and can be expanded in the power series
\[
\begin{equation*}
\beta V(u)=\sum_{p=0}^{\infty} b_{\bar{p}} u^{p} \tag{5-7}
\end{equation*}
\]

It is assumed that this series converges for all values of \(u\), and that the series derived using it also converge. The coefficients \(C_{n+j \frac{m}{a}}^{l m}\) and \(C_{n+j \frac{m}{a}}^{\prime \prime m}\) of Section 4 may be expressed in terms of the coefficients \(b_{p}\), and, therefore, all of the fields expressed in terms of a single set of unknown coefficients. The substitution of Eqs. 5-3, 5-6, and 5-7 into Eq. 4-30 gives an expression for \(C_{n+j \frac{m}{a}}^{11 m}\) as
for \(m\) even
\[
\begin{equation*}
C_{n+j \frac{m}{a}}^{\prime \prime m}=0 \tag{5-8}
\end{equation*}
\]
for \(m\) odd, \(n=0,1,2,3, \ldots\)
\[
C_{n+j \frac{m}{a}}^{\prime \prime m}=\frac{\sin \theta_{0}}{\pi a}(2)^{n+\frac{1}{2}+j \frac{m}{a}\left(n+\frac{1}{2}+j \frac{m}{a}\right)} \sum_{p=0}^{\leq \frac{1}{2} n} \frac{\Gamma\left(n-p+\frac{1}{2}+j \frac{m}{a}\right)}{p!(2)^{2 p}} b_{n-2 p}
\]

Substituting into \(4-49\) gives \(C_{n+j \frac{m}{a}}^{\prime m}\) as
for \(m\) even
\[
c_{n+j \frac{m}{a}}^{\prime m}=0
\]
for \(m\) odd, \(n=-1 \quad c^{1} m \quad-1+j \frac{m}{a}=0\)
for \(m\) odd, \(n=0,1,2,3, \ldots\)

One aspect in the derivation of the preceding equations should be considered here. If \(f_{m}(u)\) is derived from Eq. 4-33, it is
\[
\begin{equation*}
f_{m}(u)=\frac{\sin \theta_{o}}{\pi a \sqrt{a^{2}+\sin ^{2} \theta}} F(u) \quad m \text { odd } \tag{5-9}
\end{equation*}
\]
which combined with Eq. 4-12 expresses the variation in electric field intensity along the gap \(F(u)\) as
\[
\begin{equation*}
F(u)=\frac{\pi a \sqrt{a^{2}+\sin ^{2} \theta_{o}}}{\sin \theta_{0}} \sum_{n=0}^{\infty} C_{n+j \frac{m}{a}}^{\prime \prime m} u^{-\frac{3}{2}} u^{-j \frac{m}{a}} J_{n+\frac{1}{2}+j \frac{m}{a}}^{(u)} \tag{5-10}
\end{equation*}
\]
\(F(u)\) does not depend on the method used in solving the problem; that is, \(F(u)\) must be independent of \(m\) and \(n\). For any one value of \(n\), \(u^{-j \frac{m}{a}}\)
\(J{ }^{(u)}\)
\[
f_{m}(u)=0 \quad m \text { even }
\]
over many values of \(n\) to obtain a solution. If only one value of \(n\) could be used to represent a solution, the operation of the antenna could be described in terms of "modes" existing on the structure, and it would only be necessary to determine what "mode" is excited by a source at the origin. Unfortunately, the summation over \(n\) must be made, and \(F(u)\) does not seem to have a simple mathematical form.

\subsection*{5.3 The Continuity of Tangential \(\underline{H}\) from Regions I and II}

If the voltage along the gap \(V^{\prime}(u)\) is to correspond to that produced by a source at the origin, it is restricted by the condition that the components of \(\underline{H}\) tangential to the cone \(\theta=\theta_{0}\) must be continuous as the gap is crossed from Region I to Region II. Referring again to Fig. 5, the \(s\) component of \(\underline{H}\) must approach zero as the gap width is made small. In terms of the magnetic flux density \(\underline{B}\) given by \(\underline{B}=\mu \underline{H}\), any time-varying component of \(B_{S}\) is zero in the conducting arm. The normal component of \(\underline{B}\) is continuous across a surface, so \(B_{S}\) is zero just inside the gap at the points \(T=T_{2}^{+}\)and \(T=T_{3}{ }^{-}\). If \(B_{S}\) in the gap did not approach zero as \(\Delta T \longrightarrow 0, B_{s}\) would be discontinuous in a continuous media. Therefore, \(B_{S} \longrightarrow 0\) as \(\Delta T \longrightarrow 0\), and \(H_{S}\) in the gap approaches zero as the gap is made narrow. To insure continuity of the tangential components of \(\underline{H}\) in the gap the relation to be enforced is
\[
\begin{equation*}
\left.\left.\mathrm{H}_{\mathrm{pI}}\right]_{\text {gap }}=\mathrm{H}_{\mathrm{pII}}\right]_{\text {gap }} \tag{5-11}
\end{equation*}
\]
where the subscripts \(I\) and II refer to the field evaluated from \(\theta<\theta_{0}\) and \(\theta>\theta_{0}\), respectively. The magnetic fields in the two gaps are the same except for sign, so it is sufficient to enforce Eq. \(5-11\) only at the gap at \(T=0\).

In Appendix \(B\) expressions for \(H_{p}\) evaluated at the gap are derived in terms of the coefficients \(b_{p}\) of the power series expansion for \(V(u)\). It is shown there that for Eq. \(5-11\) to be satisfied for all values of \(u\) except \(u=0, u=\infty\), the \(b_{p}\) coefficients must be related as follows:
for \(p=1,2,3, \ldots\)
\(\sum_{\substack{m=-\infty \\ m \text { odd }}}^{\infty}\left\{\frac{\sin ^{2} \theta_{0}}{a^{2}} \sum_{n=0}^{p-1} \frac{(-1)^{n+1}(2)^{2 n+1}\left(2 n+\frac{1}{2}+j \frac{m}{a}\right)}{(p-n-1)!\left(2 n+j \frac{m}{a}\right)\left(2 n+1+j \frac{m}{a}\right) \Gamma\left(p+n+\frac{1}{2}+j \frac{m}{a}\right)}\left[M_{n}^{\prime \prime}\right] 2_{2 n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)\right.\)
\[
b_{2 p}=\frac{\left.+\sum_{n=1}^{p-1} \frac{(-1)^{n+1}(2)^{2 n-1}\left(2 n-\frac{1}{2}+j \frac{m}{a}\right)\left[(2 n-1)(2 n)+j \frac{m}{a}(4 n-2 p-1]\right.}{(p-n)!\left(2 n+j \frac{m}{a}\right)\left(2 n-1+j \frac{m}{a}\right) \Gamma\left(p+n+\frac{1}{2}+j \frac{m}{a}\right)}\left[M_{n}^{\prime}\right] \rho^{m} \begin{array}{l}
\left(\cos _{2 n-1+j \frac{m}{a}} \theta_{0}\right)
\end{array}\right\}}{\sum_{i}^{\infty}(-)^{p}(2)^{2 p-1}(2 p-1)(2 p) \rho_{2 p-1+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}
\]
\(\sum_{m=-\infty}^{\infty}\left\{\frac{\sin ^{2} \theta_{0} \sum^{p-1}}{a^{2}} \sum_{n=0}^{(p-n-1)!\left(2 n+1+j \frac{m}{a}\right)\left(2 n+2+j \frac{m}{a}\right) \Gamma\left(p+n+\frac{3}{2}+j \frac{m}{a}\right)}\left[N_{n}^{\prime \prime}\right] \mathcal{Z}_{2 n+1+j \frac{m}{a}}^{m+1}\left(\cos \theta_{0}\right)\right.\)
\[
\left.+\sum_{n=0}^{p} \frac{(-1)^{n+1}(2)^{2 n}\left(2 n+\frac{1}{2}+j \frac{m}{a}\right)\left[2 n(2 n+1)+j \frac{m}{a} 2(2 n-p)\right]}{(p-n)!\left(2 n+1+j \frac{m}{a}\right)\left(2 n+j \frac{m}{a}\right) \Gamma\left(p+n+\frac{3}{2}+j \frac{m}{a}\right)}\left[N_{n}^{\prime}\right] \rho_{2 n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)\right\}
\]
\[
b_{2 p+1}=\sum_{\substack{m=-\infty \\ \text { mod }}}^{\infty}(-)^{p}(2)^{2 p}(2 p)(2 p+1) \bigodot_{2 p+j \frac{m}{a}}^{m}\left(\cos \theta_{o}\right)
\]
where
\[
\begin{aligned}
& P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)=\frac{P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}{\frac{d P_{n+j \frac{-}{a}}^{m}\left(\cos \theta_{0}\right)}{d \theta}}-\frac{P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)}{d P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)} \\
& 2_{n+j \frac{m}{a}}^{m}\left(\cos 0_{0}\right)=\frac{d P_{n+j \frac{-}{a}}^{m}\left(\cos \theta_{0}\right)}{d \theta} \frac{d P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)}{P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}-\frac{d \theta}{P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)} \\
& \left.\frac{d P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}{d \theta} \text { stands for } \frac{d P_{n+j \frac{m}{a}}^{m}(\cos \theta)}{d \theta}\right]_{\theta=\theta_{0}} \\
& M_{n}^{\prime \prime}=\sum_{k=0}^{n} \frac{\Gamma\left(2 n-2 k+\frac{1}{2}+j \frac{m}{a}\right)}{k!(2)^{2 k}} b_{2(n-k)} \\
& M_{n}^{\prime}=\sum_{k=0}^{n} \frac{\Gamma\left(2 n-k-\frac{1}{2}+j \frac{m}{a}\right)}{k!(2)^{2 k}}\left[(2 n-1)(2 n)+j \frac{m}{a} 2(n+k)\right] \quad b_{2(n-k)} \quad \text { for } n \neq p \\
& M_{n}^{\prime}=\sum_{k=1}^{p} \frac{\Gamma\left(2 p-k-\frac{1}{2}+j \frac{m}{a}\right)}{k!(2)^{2 k}}\left[(2 p-1)(2 p)+j \frac{m}{a} 2(p+k)\right] b_{2(p-k)} \quad \text { for } n=p \\
& N_{n}^{\prime \prime}=\sum_{k=0}^{n} \frac{\Gamma\left(2 n-k+\frac{3}{2}+j \frac{m}{a}\right)}{k!(2)^{2 k}} b_{2(n-k)+1} \\
& N_{n}^{\prime}=\sum_{k=0}^{n} \frac{\Gamma\left(2 n-k+\frac{1}{2}+j \frac{m}{a}\right)}{k!(2)^{2 k}}\left[2 n(2 n+1)+j \frac{m}{a}(2 n+2 k+1)\right] b_{2(n-k)+1} \quad \text { for } n \neq p \\
& N_{n}^{\prime}=\sum_{k=1}^{p} \frac{\Gamma\left(2 p-k+\frac{1}{2}+j \frac{m}{a}\right.}{k!(2)^{2 k}}\left[2 p(2 p+1)+j \frac{m}{a}(2 p+2 k+1)\right] b_{2(p-k)+1} \quad \text { for } n=p
\end{aligned}
\]

Eq. \(5-12\) expresses \(b_{2}\) in terms of \(b_{0} ; b_{4}\) in terms of \(b_{2}\) and \(b_{0}\); \(b_{6}\) in terms of \(b_{4}, b_{2}\), and \(b_{0}\); etc. Eq. (5-13) expresses \(b_{3}\) in terms of \(b_{1} ; b_{5}\) in terms of \(b_{3}\), and \(b_{1}\); etc. Therefore, all of the coefficients in the power series expansion are expressed in terms of \(b_{o}\) and \(b_{1}\).

Since \(b_{0}\) is proportional to the input voltage, the coefficient \(b_{1}\) is the only one still to be determined.

\subsection*{5.4 The Far Fields and the Radiation Condition}

The relation between \(b_{0}\) and \(b_{1}\) must be such that the radiation condition \({ }^{2 l}\) is satisfied. This condition insures that the antenna is a source of energy, and for a finite antenna requires that the fields at large distances from the antenna be represented by divergent traveling waves. Making use of the relations
\[
\begin{equation*}
u^{-j \frac{m}{a}} e^{-j \frac{m}{a} \tau}=e^{-j m\left(\phi+\frac{\ln \beta}{a}\right)} \tag{5-14}
\end{equation*}
\]
and \(\lim _{r \rightarrow \infty}(\beta r)^{\frac{1}{2}} J_{n+\frac{1}{2}+j \frac{m}{a}}^{\left.(\beta r)^{( }\right)}=\left(\frac{2}{\pi}\right)^{\frac{1}{2}} \cos \left[\beta r-\frac{1}{2} \pi\left(n+1+j \frac{m}{a}\right)\right]\)
the electric fields for large values of \(r\) are given by Eqs. 5-16, 5-17, and 5-18. The magnitude of \(E_{r}\) varies as \(\frac{1}{r_{2}}\) for large \(r\), and thus becomes insignificant. As the antenna considered here is infinite in extent it is not possible to be a large distance from it. However, since only the relation between \(b_{0}\) and \(b_{1}\) is desired, it can be obtained by requiring a wave traveling away from the origin in one direction.

The most convenient direction to choose is \(\theta=\theta_{0}\) as
\[
\begin{aligned}
& \lim _{\theta \rightarrow 0} \frac{P_{n+j}^{m} \frac{m}{a}(\cos \theta)}{\sin \theta}=0 \quad \text { for all } m \text { except } m= \pm 1 \\
& \left.\quad \frac{d P_{n+j \frac{m}{a}}^{m}(\cos \theta)}{d \theta}\right]_{\Theta=0}=0 \quad \text { for all m except } m= \pm 1,
\end{aligned}
\]
and the summation with respect to \(m\) becomes trivial.


Using the \(e^{j \omega t}\) time convention a wave traveling away from the origin varies as \(\frac{1}{r} e^{-j \beta r}\). Making use of the fact that many terms from \(m=1\) and \(m=-1\) are related as complex conjugates, \(\left.E_{\theta}\right]_{\theta=0}\) and \(\left.E_{\phi}\right]_{\theta=0}\) in Eqs. 5-17 and 5-18 will have this \(r\) variation for all values of \(\phi\) if
\[
\begin{equation*}
\left.\sum_{n=0}^{\infty} e^{-\frac{j n \pi}{2}\left\{\frac{c_{n+\frac{j}{a}}^{11}}{P_{n+\frac{j}{1}}^{1}\left(\cos \theta_{0}\right)}+\frac{\left(n+1+\frac{j}{a}\right)\left(n+\frac{j}{a}\right) c_{n+\frac{j}{a}}^{1}}{d P_{n+\frac{j}{a}}^{1}\left(\cos \theta_{0}\right)}\right.}\right\}=0 \tag{5-19}
\end{equation*}
\]

Substituting for \(C_{n+\frac{j}{a}}^{\text {"1 }}\) and \(C_{n+j \frac{1}{a}}^{11}\) from Eqs. 5-8 and 5-9, and letting
\[
\begin{aligned}
\bar{M}_{n}^{\prime \prime} & =\sum_{k=0}^{n} \frac{\Gamma\left(2 n-k+\frac{1}{2}+\frac{j}{a}\right)}{k!(2)^{2 k}} b_{2(n-k)} \\
\bar{M}_{n}^{\prime} & =\sum_{k=0}^{n} \frac{\Gamma\left(2 n-k-\frac{1}{2}+\frac{j}{a}\right)}{k!(2)^{2 k}}\left[2 n(2 n-1)+\frac{j}{a} 2(n+k)\right] b_{2(n-k)}
\end{aligned}
\]
\[
\vec{N}_{n}^{\prime \prime}=\sum_{k=0}^{n} \frac{\Gamma\left(2 n-k+\frac{3}{2}+\frac{j}{a}\right)}{k!(2)^{2 k}} b_{2(n-k)+1}
\]
\[
\bar{N}_{n}^{\prime}=\sum_{k=0}^{n} \frac{\Gamma\left(2 n-k+\frac{1}{2}+\frac{j}{a}\right)}{k!(2)^{2 k}}\left[2 n(2 n+1)+\frac{j}{a}(2 n+2 k+1)\right] b_{2(n-k)+1}
\]

Eq 5-19 becomes
\[
\begin{aligned}
& \sum_{n=0}^{\infty}\left\{\frac{(-1)^{n}(2)^{2 n}\left(2 n+\frac{1}{2}+\frac{j}{a}\right) \sin \theta_{0}}{a P_{2 n+\frac{j}{a}}^{1}\left(\cos \theta_{0}\right)}\left[\bar{M}_{n}^{\prime \prime}\right]+j \frac{(-1)^{n}(2)^{2 n+1}\left(2 n+\frac{3}{2}+\frac{j}{a}\right)}{d P_{2 n+1+\frac{j}{a}}^{1}\left(\cos \theta_{0}\right)}\left[\bar{M}_{n+1}^{\prime}\right]\right\} \\
& =\sum_{n=0}^{d \theta}\left\{\frac{(-1)^{n}(2)^{2 n}\left(2 n+\frac{1}{2}+\frac{j}{a}\right)}{d P_{2 n+\frac{j}{a}}^{1}\left(\cos \theta_{\rho}\right)}\left[\bar{N}_{n}^{\prime}\right]+j \frac{(-1)^{n}(2)^{2 n+1}\left(2 n+\frac{3}{2}+\frac{j}{a}\right) \sin \theta_{0}}{a P_{2 n+1+\frac{j}{a}}^{1}\left(\cos \theta_{0}\right)}\left[\bar{N}_{n}^{d}\right]\right\}
\end{aligned}
\]

The LHS of Eq. 5-20 is proportional to \(b_{0}\), and the RHS is proportional to \(b_{1}\). Therefore, it gives the relation between \(b_{0}\) and \(b_{1}\) required for waves traveling from the origin for large \(r\) along the \(\theta=0\) axis. Eq. 5-20 is a convenient form for this relation as \(\bar{M}_{n}^{\prime \prime}, \bar{M}_{n}^{\prime}, \bar{N}_{n}^{\prime \prime}\), and \(\bar{N}_{n}^{\prime}\) are needed in Eq. 5-12 and 5-13 for the calculation of the \(b_{p}\) coefficients.

\subsection*{5.5 The Input Admittance}

The input voltage \(\mathrm{V}(0)\) can be obtained by taking the limit of \(V(u)\) as \(u \rightarrow 0\), and using Eq. 5-7
\[
\begin{equation*}
V(0)=\lim _{u \rightarrow 0} V(u)=\frac{b_{0}}{\beta} \tag{5-21}
\end{equation*}
\]

The input current \(I(0)\) can be determined by integrating \(\underline{H} \cdot \underline{d l}\) around one of the arms and taking the limit as \(u \rightarrow 0\). Using Eq. 4-30, 4-41, \(4-8\), and \(5-2\), an expression for the input admittance \(Y(0)\) can be


\subsection*{5.6 The Problem of Numerical Calculation}

To be completely satisfying from an engineering viewpoint, the rather complex mathematical expressions derived for the equiangular spiral antenna must be evaluated for various parameters of the structure. The fact that the expressions obtained are in series form makes them well adapted for computation using a digital computer. It is presently planned by the Antenna Laboratory of the University of Illinois to program the high-speed digital computer, ILLIAC, to make numerical calculations using the expressions derived here. Appropriate tables of the gamma function of complex argument are available, \({ }^{20}\) but no tables of complex order Bessel functions or complex degree associated Legendre functions are known. The series converge most rapidly with respect to \(n\) when \(r\) is small. In the limit as \(r \rightarrow 0\) only the \(n=0\) terms are needed, and the electric fields approach those given by the static solutions. This fact makes the near fields, including the current distribution on the antenna arms, the easiest to calculate. It will probably be better to use the conventional methods of obtaining the far fields for a known current distribution than to use the series developed here.

\section*{6. CONCLUSIONS}

Theoretical expressions for the fields produced by an infinite equiangular spiral structure have been obtained. It has been demonstrated that the static electric fields are a function of only two variables \(s\) and \(\theta\). For the static case exact expressions have been derived for the structure with narrow gaps, and approximate expressions using the "least squares" criterion for arbitrary gaps.

For the electromagnetic problem, solutions of the vector Helmholtz equation suitable for the spiral geometry have been obtained by using the separation of variables technique in an oblique coordinate system. These solutions express all of the electromagnetic fields in terms of the tangential electric fields existing in the gaps of an equiangular spiral antenna.

For the special case of the balanced antenna with narrow gaps between the arms, exact expressions for the fields in the gaps are derived. These solutions make available a means of calculating the input impedance, the current distribution, and the pattern of an equiangular spiral antenna.

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\section*{APPENDIX A}

If the potential on the cone \(\theta=\theta_{0}\) is real, the solutions for the potential in Section 3 : are real for all values of \(\theta\) and \(T\). This may be shown by first combining Eq. 3-15 and 3-18 for \(\theta \leq \theta_{0}\) to obtain
\[
\begin{equation*}
V(\theta, \tau)=\sum_{m=-\infty}^{\infty} c_{m} \frac{P_{j \frac{m}{a}}^{m}(\cos \theta)}{P_{j \frac{m}{a}}^{{ }_{j}^{m}}\left(\cos \theta_{0}\right)} e^{j \frac{m}{a} \tau} \tag{A-1}
\end{equation*}
\]

From Eq. 3-17
\[
\begin{equation*}
C_{m}=\frac{1}{2 \pi a} \int_{T_{1}}^{\tau_{1}+2 \pi a} V\left(\theta_{0}, \tau\right) e^{-j \frac{m}{a} T} d \tau \tag{3-17}
\end{equation*}
\]
\(C_{m}=\left(\mathrm{C}_{-\mathrm{m}}\right)^{*}\), and \(\mathrm{C}_{\mathrm{o}}\) is real if \(\mathrm{V}\left(\theta_{0}, \tau\right)\) is real. By Eq. 3-11, 3-12, and \(3-13, P_{o}^{0}(\cos \theta)=1\)
and
\[
\begin{equation*}
\frac{\mathbf{P}_{j \frac{m}{a}}^{m}(\cos \theta)}{\mathbf{P}_{j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}=\left[\frac{P^{-m}(\operatorname{jos} \theta) \prime}{P_{-j \frac{m}{a}}^{-m}\left(\cos \theta_{0}\right)}\right]^{*} \tag{A-2}
\end{equation*}
\]

Therefore, in Eq \(A-1\) the \(m=0\) term is real; for other values of \(m\) the \(+m\) and \(-m\) terms are complex conjugates for all values of \(o\) and \(T\). This assures that the potentials obtained from Eq. A-3 or Eq. 3-24 are real for all values of \(\theta\) and \(\tau\).

\section*{APPENDIX B}

\section*{DERIVATION OF THE \(b_{p}\) COEFFICIENTS}

The relations between the coefficients \(b_{p}\) of the power series expansion for the voltage along the gap are determined by requiring that the \(p\) components of the magnetic field at the gap from regions I and II are equal. By Eq. \(5-2 H_{p}\) is related to \(H_{r}\) and \(H_{\phi}\) by
\[
\begin{equation*}
H_{p}=\frac{a}{\sqrt{a^{2}+\sin ^{2} \theta}} H_{r}+\frac{\sin \theta}{\sqrt{a^{2}+\sin ^{2} \theta}} H_{\phi} \tag{B-1}
\end{equation*}
\]

Using Eqs. 4-30, 4-48, and 4-49, \(H_{p}\) in region I is
\(j \eta \sqrt{a^{2}+\sin ^{2} \theta^{\prime} H_{p}}=\frac{a}{u} \sum_{m=-\infty}^{\infty} \sum_{n=0}^{\infty}\left[c_{n+j \frac{m}{\operatorname{lm}} u^{\frac{1}{2}} u^{-j \frac{m}{a}}\left[\frac{\left(n+j \frac{m}{a}\right)\left(n+1+j 2 \frac{m}{a}\right)}{u} J_{n+\frac{1}{2}+j}^{(u)} \frac{m}{a}-1 .\right.}\right.\)
\[
\left.\left.-\left(j \frac{m}{a}\right) J_{n-\frac{1}{2}}^{(u)}+j \frac{m}{a}\right] \frac{p_{n+j \frac{m}{a}}^{m}(\cos \theta)}{d p_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)} e^{j \frac{m}{a} \tau}\right]
\]
\[
+\frac{\sin \theta}{u} \sum_{m=-\infty}^{\infty} \sum_{n=0}^{\infty}\left[\frac{C_{n+j \frac{m}{2}}^{1 \prime m} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{n+\frac{1}{2}+j \frac{m}{a}}^{(u)} \frac{d p_{n+j \frac{m}{a}}^{m}(\cos \theta)}{d \theta}}{\left(n+j \frac{m}{a}\right)\left(n+1+j \frac{m}{a}\right)} e_{P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}^{j \frac{m}{2} T}\right]
\]

The expression for \(H_{p}\) in region II is similar.
Let
\[
\begin{equation*}
\nabla_{n}^{m}+j \frac{m}{a}\left(\cos \theta_{0}\right)=\frac{P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}{d P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}-\frac{P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)}{d P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)} \tag{B-3}
\end{equation*}
\]
\[
\begin{equation*}
2_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)=\frac{d P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}{\frac{d P_{n+j}^{m} \frac{m}{a}\left(-\cos \theta_{0}\right)}{P_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)}-\frac{d \theta}{P_{n+j \frac{m}{a}}^{m}\left(-\cos \theta_{0}\right)}} \tag{B-3}
\end{equation*}
\]

Equating, \(H_{p}\) evaluated at \(\tau=0, \Theta=\theta_{0}\) from regions I and II gives
\(\frac{a}{u} \sum_{m=-\infty}^{\infty} \sum_{n=0}^{\infty} C_{n+j}^{m} u^{\frac{m}{2}} u^{-j \frac{m}{a}}\left[\frac{\left(n+j \frac{m}{a}\right)\left(n+1+j 2 \frac{m}{a}\right)}{u} J_{n+\frac{1}{2}+j \frac{m}{a}}^{(u)}-\left(j \frac{m}{a}\right) J_{n-\frac{1}{2}+j \frac{m}{a}}^{(u)}{ }_{\mathcal{P}_{n+j}^{m}}^{\frac{m}{a}}\left(\cos \theta_{0}\right)\right.\)
\(+\frac{\sin \theta_{0}}{u} \sum_{m=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} \frac{\bar{C}_{n+j}^{\prime m} \frac{m}{a} u^{\frac{1}{2}} u^{-j \frac{m}{a}} J_{n+\frac{1}{2}+j}^{(u)} \frac{m}{a}^{m}}{\left(n+j \frac{m}{a}\right)\left(n+1+j \frac{m}{a}\right)} 2_{n+j}^{m} \frac{m}{a}\left(\cos \theta_{0}\right)=0\)

If Eq. B-4 is to be satisfied for all \(u\) except \(u=0, \infty\), the coefficients of each power of \(u\) must be zero. Expanding the Bessel functions in a power series gives
\(\frac{a}{u} \sum_{m=-\infty}^{\infty} \sum_{n=0}^{\infty} \sum_{k=0}^{\infty}\left[\frac{(-1)^{k}\left[n(n+1)+j \frac{m}{a}(n-2 k)\right] u^{n+2 k}}{\left.k!(2)^{n+2 k+\frac{1}{2}+j \frac{m}{a} \Gamma\left(n+k+\frac{3}{2}+j \frac{m}{a}\right)} \dot{c}_{n+j \frac{m}{a}}^{m} \sigma_{n+j \frac{m}{a}}^{m}\left(\cos \theta_{0}\right)\right]}\right]\)
\(\frac{\sin \theta}{u} \sum_{m=-\infty}^{\infty} \sum_{n=1}^{\infty} \sum_{k=0}^{\infty}\left[\frac{(-1)^{k}(u)^{n+2 k}}{\left[k!(2)^{n+2 k-\frac{1}{2}+j \frac{m}{a}}\left(n-1+j \frac{m}{a}\right)\left(n+j \frac{m}{a}\right) \Gamma\left(n+k+\frac{1}{2}+j \frac{m}{a}\right)\right.} c_{n-1+j \frac{m}{a}}^{n_{m}^{m}}\right.\)
\(\left.\times \cdot 2_{n-1+j \frac{m}{a}\left(\cos \theta_{0}\right)}^{m}\right]=0\)

Letting \(p=n+2 k\) the method of summing can be changed as shown in Fig. 6. This is not a rearrangement as the terms in one row (or column) are in the same order as before.


FIGURE 6 THE SUMMATION METHOD

The coefficient of \(u\) is always zero for \(p=0\), and for the other coefficients of \(u\) to be zero, for \(p=1,2,3, \ldots\)

\(+\sin \theta_{0} \sum_{m=-\infty}^{\infty} \sum_{(n)=1}^{p} \frac{(j)^{p-n} c_{n-1+j \frac{m}{a}}^{2} 2^{m} \frac{m}{n}+j \frac{m}{a}\left(\cos \theta_{0}\right)}{\left(\frac{p-n}{2}\right)!(2)^{p-\frac{1}{2}+j \frac{m}{a}}\left(n-1+j \frac{m}{a}\right)\left(n+j \frac{m}{a}\right) \Gamma\left(\frac{p+n+1}{2}+j \frac{m}{a}\right)}=0\)

Substituting the values of \(C_{n+j}^{l^{\prime}} \frac{m}{a}\) and \(C_{n-1+j \frac{m}{a}}^{\|_{m}}\) from Eq. 5-8 and \(5-9\) gives, for \(p=1,2,3, \ldots\)

\[
-\sum_{\substack{m=-\infty \\ m \text { odd }}}^{\infty} \sum_{(n)=0}^{p}\left[\frac{(j)^{-n}(2)^{n}\left(n+\frac{1}{2}+j \frac{m}{a}\right)\left[n(n+1)+j \frac{m}{a}(2 n-p)\right]}{\left(\frac{p-n}{2}\right)!\left(n+1+j \frac{m}{a}\right)\left(n+j \frac{m}{a}\right) \Gamma\left(\frac{p+n+3}{2}+j \frac{m}{a}\right)}\right.
\]
\(\left.\sum_{k=0}^{\leq \frac{1}{2}(n+1)} \frac{\Gamma\left(n-k+\frac{1}{2}+j \frac{m}{a}\right)}{k!(2)^{2 k}}\left[n(n+1)+j \frac{m}{a}(n+2 k+1)\right] b_{n-2 k+1}\right]=0\)
\(\times\)

Eq. B-7 then gives Eq. 5-12 when p is odd and Eq. 5-13 when p is even.

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